# MANUAL

Serial Number \_\_\_\_\_

7A16
AMPLIFIER

# Scans By *Artek Media*

Artek Media 1042 Plummer Cir. SW Rochester, MN 55902

# www.artekmedia.com

"High resolution scans of obsolete technical manuals"

If your looking for a quality scanned technical manual in PDF format please visit our WEB site at <a href="www.artekmedia.com">www.artekmedia.com</a> or drop us an email at <a href="manuals@artekmedia.com">manuals@artekmedia.com</a> and we will be happy to email you a current list of the manuals we have available.

If you don't see the manual you need on the list drop us a line anyway we may still be able to point you to other sources. If you have an existing manual you would like scanned please write for details, This can often be done very reasonably in consideration for adding your manual to our library.

Typically the scans in our manuals are done as follows;

- 1) Typed text pages are typically scanned in black and white at 300 dpi.
- 2) Photo pages are typically scanned in gray scale mode at 600 dpi
- Schematic diagram pages are typically scanned in black and white at 600 dpi unless the original manual had colored high lighting (as is the case for some 70's vintage Tektronix manuals).

If you purchased this manual from us (typically through our Ebay name of ArtekMedia) thank you very much. If you received this from a well-meaning "friend" for free we would appreciate your treating this much like you would "share ware". By that we mean a donation of at least \$5-10 per manual is appreciated in recognition of the time (a manual can take as much as 40 hours to reproduce, book, link etc.), energy and quality of effort that went into preserving this manual. Donations via PayPal go to: <a href="manuals@artekmedia.com">manuals@artekmedia.com</a> or can be mailed to us the address above.

Thanks

Dave & Lynn Henderson

Kack & Synneth

Artek Media

# WARRANTY

All Tektronix instruments are warranted against defective materials and workmanship for one year. Tektronix transformers, manufactured in our plant, are warranted for the life of the instrument.

Any questions with respect to the warranty mentioned above should be taken up with your Tektronix Field Engineer.

Tektronix repair and replacement-part service is geared directly to the field, therefore all requests for repairs and replacement parts should be directed to the Tektronix Field Office or representative in your area. This procedure will assure you the fastest possible service. Please include the instrument Type and Serial or Model Number with all requests for parts or service.

Specifications and price change privileges reserved.

Copyright © 1969 by Tektronix, Inc., Beaverton, Oregon. Printed in the United States of America. All rights reserved. Contents of this publication may not be reproduced in any form without permission of the copyright owner.

# **TABLE OF CONTENTS**

Introduction   1-1	SECTION 1 SPECIFICATION	Page	SECTION 5 PERFORMANCE CHECK/ CALIBRATION	
Deflection Factor Gain 1-1 Short Form Procedure 5-1 Short Form Procedure 5-2 Frequency Response 1-1 Input Resistance 1-1 Input Resistance 1-1 Input Capcacitance	Introduction	1-1	CALIDRATION	
Sour Form Procedure	Electrical Characteristics		Introduction	
Performance Check/Calibration Procedure   Maximum Input Voltage   1-1   Preliminary Procedure   5-3   Input Resistance   1-1   Check or Adjust   Section 9   Preliminary Procedure   5-4   Check or Adjust   Section 9   Preliminary Procedure   5-4   Check or Adjust   Section 9   Preliminary Procedure   5-4   Check or Adjust   Preliminary Procedure   5-4   Noise (Tangenfially Measured)   1-1   Check or Adjust   STEP ATTENUATOR Range   5-4   STEP ATTENUATOR Range   5-4   STEP ATTENUATOR Range   5-4   STEP ATTENUATOR Range   5-4   STEP ATTENUATOR Range   5-5   President President   President	Deflection Factor	1-1	Test Equipment Required	
Maximum Input Voltage	Gain	1-1		5-2
Input Resistance   1-1   Preliminary Control Settings   5-4   Input Capacitance   1-1   Check or Adjust   Check or Adjus	Frequency Response	1 - 1	Performance Check/Calibration Procedure	
Input Capacitance Maximum Input Gate Current Moise (Tangentially Measured) DC Drift	Maximum Input Voltage	1-1	Preliminary Procedure	5-3
Maximum Input Gote Current Noise (Tangentially Measured) Noise (Tangentially Measured) DC Drift Environmental Characteristics Allitude 1-1 Transportation 1-1 Dimensions 1-1 Dimensions 1-1 Dimensions 1-1 Variable Range 5-5 Finish 1-1 Dimensions 1-1 VARIABLE Range 5-6 SECTION 2 OPERATING INSTRUCTIONS General Front Panel Controls and Connector First Time Operation Control Setup Chart General Operating Information Basic Applications 2-3 General Operating Information Bosch Diagram Description Input Coupling Input Atlenuator Input Stage Input Sta	Input Resistance	1-1	Preliminary Control Settings	5-4
Noise (Tengentially Measured) DO Drift 1-1 STEP ATTENUATOR Range 5-4 Environmental Characteristics Altitude 1-1 Position Centering 5-5 Finish 1-1 GAIN Position Range 5-6 Finish 1-1 Finish 1-1 Dimensions 1-1 VARIABLE Range 5-6 VOLTS/DIV Deffection Accuracy 5-7 Foregration 5-7 Foregration 5-7 SECTION 2 OPERATING INSTRUCTIONS  General Front Panel Controls and Connector First Time Operation 2-1 General Operating Information 2-3 Basic Applications 1-1 Introduction Block Diagram Description Introduction Block Diagram Description Input Attenuator Input Stage First Cascade Stage Output Stage Fir	Input Capacitance	1-1	Check or Adjust	
DC Drift Environmental Characteristics Allitude	Maximum Input Gate Current	1-1	DC Balance	5-4
Environmental Characteristics Altitude	Noise (Tangentially Measured)	1-1	Variable Balance	5-4
Altitude Transportation Altitude Altitude Altitude Transportation Altitude Altitu	DC Drift	1-1	STEP ATTENUATOR Range	5-4
Transportation Transportation Physical Characteristics Physical Characteristics Finish Dimensions Veight 1-1 VARIABLE Range 5-5 Finish Dimensions 1-1 VARIABLE Range 5-6 Fire Trigger DC level Trigger Gain 5-6 VOLTS/DIV Deflection Accuracy 5-6 Input Compensation 5-7 First Time Operation Control Setup Chart	Environmental Characteristics		STEP ATTENUATOR Balance	5-4
Physical Characteristics Finish Dimensions Weight 1-1 GAIN Trigger DC Level Trigger Gain S-6 VOITS/DIV Deflection Accuracy 5-6 Input Compensation 5-7 Front Panel Controls and Connector First Time Operation Ceneral Control Setup Chart Ceneral Operating Information 2-1 Front Panel Control Setup Chart Ceneral Operating Information 2-3 Ceneral Operating Information 2-3 Basic Applications 2-5 SECTION 3 CIRCUIT DESCRIPTION SECTION 3 CIRCUIT DESCRIPTION SECTION 3 CIRCUIT DESCRIPTION SECTION 4 MAINTENANCE  Preventive Maintenance Cleaning 1-1 Clorication Visual Inspection 1-1 Troubleshooting Troubleshooting Troubleshooting Equipment Troublesho	Altitude	1-1	Position Centering	5-5
Finish Dimensions Weight Finish Finis	Transportation	1-1	POSITION Range	5-5
Finish Dimensions Dime	Physical Characteristics		+ UP to INVERT Shift	5-5
SECTION 2 OPERATING INSTRUCTIONS  General		1-1	GAIN	5-5
SECTION 2 OPERATING INSTRUCTIONS  General Front Panel Controls and Connector Front Panel Controls and Connector First Time Operation Control Setup Chart General Operating Information Control Setup Chart Con	Dimensions	1-1	VARIABLE Range	5-6
SECTION 2 OPERATING INSTRUCTIONS  General General General General General Front Panel Controls and Connector Front Panel Controls and Connector First Time Operation Control Setup Chart General Operating Information Basic Applications Basic Applications  SECTION 3 CIRCUIT DESCRIPTION  Introduction Input Coupling Input Coupling Input Attenuator Input Stage First Cascode Stage Second Cascode Stage Output Stage Readout Block Section 4 MAINTENANCE  Preventive Maintenance Cleaning Voltage Aprile Stage Preventive Maintenance Cleaning Voltage Aprile Stage First Cascode Stage Output Stage Readout Block Cleaning First Cascode Stage Cleaning Voltage Aprile Stage Preventive Maintenance Cleaning Visual Inspection Visu	Weight	1-1	Trigger DC Level	5-6
SECTION 2 OPERATING INSTRUCTIONS  General General General Front Panel Controls and Connector First Time Operation Control Setup Chart General Operating Information Basic Applications  Series and Shunt Compensation First Time Operation Control Setup Chart General Operating Information Control Setup Chart General Operation Control Setup Chart Control Setup Compensation (5 mV) Compensation Control Setup Compensation (10 mV) Compensation Control Setup Compensation (10 mV) Compensation Control Setup Compensation (10 mV) Compensation Control Setup Compensation Control Setup Compensation Control Setup Compensation Control Setup Compensation (10 mV) Compensation Control Setup Compensation Control Setup Compensation Control Setup Compensation (10 mV) Compensation Control Setup Compensation (10 mV) Compensa	•		Trigger Gain	5-6
Input Compensation   5-7	SECTION 2 OPERATING INSTRUCTIONS	\$		5-6
General Front Panel Controls and Connector Front Panel Controls and Connector Front Panel Controls and Connector First Time Operation Control Setup Chart Control Setup Chart Ceneral Operating Information Basic Applications Control Setup Chart Ceneral Operating Information Control Setup Chart Ceneral Operation Control Setup Chart Control Setup Chart Ceneral Operation Control Setup Chart Control Setup Chart Control Setup Conpensation (15 mV) Control Setup Compensation (15 mV) Control Setup Compensation (10 mV) Control Setup Compensation (20 mV) Control Setup Compensation (10 mV) Control Setup Compensation (20 mV) Control Setup Compensation (10 mV) Control Setup Compensation (20 mV) Control Setup Control Compensation (20 mV) Control Setup Control Co	SECTION 2 OFERALING INSTRUCTION.	•		5-7
Front Panel Controls and Connector First Time Operation Control Setup Chart Control Setup Chart General Operating Information Basic Applications  SECTION 3 CIRCUIT DESCRIPTION  Introduction Block Diagram Description Input Coupling Input Attenuator Input Stage First Cascode Stage Second Cascode Stage Se	General	2-1		5-7
First Time Operation Control Setup Chart Control Setup Control Control Control Setup Control	Front Panel Controls and Connector	2-1		5-8
Control Setup Chart General Operating Information Basic Applications  SECTION 3 CIRCUIT DESCRIPTION  Introduction Block Diagram Description Input Coupling Input Attenuator Input Stage First Cascode Stage Output Stage Readout Block Output Stage Readout Block Readibration  SECTION 4 MAINTENANCE  Preventive Maintenance Cleaning Ubrication Visual Inspection Troubleshooting Troubleshooting Troubleshooting Troubleshooting Troubleshooting Troubleshooting Troubleshooting Troubleshooting Troubleshooting Techniques Obtaining Replacement Parts Obtaining Replacement Parts Soldering Techniques  4-6 Change information (20 mV) 5-8 Step Response 5-9 Step Response 5-9 Trigger Step Response 5-10 Step Obergonse 5-10 SECTION 6 ELECTRICAL PARTS LIST  Abbreviations and Symbols Parts Cascode Symbols Information Index of Electrical Parts List PARTS ILLUSTRATIONS  Became Application Abbreviations and Symbols used in this manual are based on or taken directly from IEEE Standard 260 "Standard Symbols for Units", MIL STD-128 and other standards of the electronics industry. Change information if any, is located at the rear	First Time Operation	2-1		
General Operating Information Basic Applications  2-3 Basic Applications  2-5 Bupper — 3 dB Point Trigger Step Response 5-9 20 Megahertz Bandwidth Limiting 5-11 Noise (Tangentially Measured) 5-10 SECTION 3 CIRCUIT DESCRIPTION  Introduction Block Diagram Description Detailed Circuit Description Input Coupling Input Attenuator Input Attenuator Input Stage First Cascode Stage 3-2 Second Cascode Stage 3-2 Second Cascode Stage 3-3 Readout Block  SECTION 4 MAINTENANCE  Preventive Maintenance Cleaning Lubrication Visual Inspection Transistor Checks Recalibration Troubleshooting Troubleshooting Troubleshooting Troubleshooting Equipment Troubleshooting Equipment Troubleshooting Techniques Obtaining Replacement Parts Soldering Techniques 4-6 Soldering Techniques 4-7 Soldering Techniques 4-8 Soldering Techniques 4-9 Soldering Techniques 5-10 Abbreviations and Symbols used in this manual are based on or taken directly from IEEE Standard 260 "Standard Symbols for Units", MIL STD-12B and other standards of the electronics industry. Change information if any, is located at the rear				
Basic Applications  2-5	•	2-3		
SECTION 3 CIRCUIT DESCRIPTION  Introduction Block Diagram Description Input Coupling Input Attenuator Input Stage First Cascode Stage Second Cascode Stage Output Stage Readout Block  SECTION 4 MAINTENANCE  Preventive Maintenance Cleaning Troubleshooting Troubleshooting Troubleshooting Techniques Obtaining Replacement Parts Odering Techniques  Trigger Step Response 20 Megahertz Bandwidth Limiting 5-11 Noise (Tangentially Measured) 5-10 Abbreviations and Symbols Parts Ordering Information Index of Electrical Parts List  Abbreviations and Symbols Parts Ordering Information Index of Electrical Parts List Parts Illustrations  SECTION 7 DIAGRAMS AND MECHANICAL PARTS ILLUSTRATIONS  Diagrams Mechanical Parts Illustrations  SECTION 8 MECHANICAL PARTS LIST  Mechanical Parts List Information Index of Mechanical Parts List Information Mechanical Parts List Information  Abbreviations and symbols used in this manual are based on or taken directly from IEEE Standard 260 "Standard Symbols for Units", MIL STD-128 and other standards of the electronics industry. Change information if any, is located at the rear Change information if any, is located at the rear Change information if any, is located at the rear Change information if any, is located at the rear Change information if any, is located at the rear				
SECTION 3 CIRCUIT DESCRIPTION  Introduction Block Diagram Description Detailed Circuit Description Input Coupling Input Attenuator Input Stage First Cascode Stage Second Cascode Stage Readout Block  SECTION 4 MAINTENANCE  Preventive Maintenance Cleaning Lubrication Visual Inspection Transistor Checks Recalibration Troubleshooting Troubleshooting Troubleshooting Troubleshooting Troubleshooting Techniques Obtaining Replacement Parts Soldering Techniques Obtaining Replacement Parts Soldering Techniques Obtaining Replacement Parts Soldering Techniques S-11 Noise (Tangentially Measured) 5-11 SECTION 6 ELECTRICAL PARTS LIST  Abbreviations and Symbols Fortier Information Index of Electrical Parts List Information Mechanical Parts List Information Index of Mechanical Parts List Information Index of Mechanical Parts List Information Mechanical Parts List Accessories  Change Information  Abbreviations and symbols used in this manual are based on or taken directly from IEEE Standard 260 "Standard Symbols for Units", MIL STD-12B and other standards of the electronics industry. Change information if any, is located at the rear	Saste Applications	- 0		
Introduction Block Diagram Description Detailed Circuit Description Input Coupling Input Attenuator Input Stage Second Cascode Stage Second Cascode Stage Readout Block  Preventive Maintenance Cleaning Lubrication Visual Inspection Troubleshooting Troubleshooting Troubleshooting Troubleshooting Equipment Troubleshooting Equipment Troubleshooting Techniques Obtaining Replacement Parts Soldering Techniques Obtaining Replacement Parts Section Section Section Section Sections and Symbols Parts Calcal Parts List Abbreviations and Symbols Parts Ordering Information Index of Electrical Parts List Parts Illustrations Section 7 Diagrams Mechanical Parts Illustrations  Section 8 MECHANICAL PARTS LIST  Mechanical Parts List Information Index of Mechanical Parts Illustrations Mechanical Parts List Information Index of Mechanical Parts List Accessories  Change Information  Abbreviations and symbols used in this manual are based on or taken directly from IEEE Standard 260 "Standard Symbols for Units", MIL STD-128 and other standards of the electronics industry. Change information if any, is located at the rear	SECTION 3 CIRCUIT DESCRIPTION			
Introduction Block Diagram Description Detailed Circuit Description Input Coupling Input Attenuator Input Stage First Cascode Stage Second Cascode Stage Output Stage Preventive Maintenance Cleaning Lubrication Visual Inspection Visual Inspection Troubleshooting Troubleshooting Troubleshooting Troubleshooting Troubleshooting Equipment Troubleshooting Equipment Troubleshooting Techniques Obtaining Replacement Parts Soldering Techniques Obtaining Replacement Parts Section  SECTION 6 ELECTRICAL PARTS LIST  Abbreviations and Symbols Parts Ordering Information Index of Electrical Parts List Parts Illustration Parts Illustrations  SECTION 7 DIAGRAMS AND MECHANICAL PARTS ILLUSTRATIONS  Diagrams Mechanical Parts Illustrations  SECTION 8 MECHANICAL PARTS LIST  Mechanical Parts List Information Index of Mechanical Parts List Information Index of Mechanical Parts List Accessories  Change Information  Abbreviations and symbols used in this manual are based on or taken directly from IEEE Standard 260 "Standard Symbols for Units", MIL STD-128 and other standards of the electronics industry. Change information if any, is located at the rear	SECTION S CIRCUIT DESCRIPTION			
Block Diagram Description Detailed Circuit Description Input Coupling Input Attenuator Input Stage Input Stage Second Cascode Stage Second Cascode Stage Output Stage Preventive Maintenance Cleaning Lubrication Visual Inspection Troubleshooting Troubleshooting Troubleshooting Troubleshooting Troubleshooting Troubleshooting Troubleshooting Equipment Troubleshooting Equipment Troubleshooting Techniques Obtaining Replacement Parts O-2 Obtaining R	Introduction	3-1	· · · · · · · · · · · · · · · · · · ·	J-11
Detailed Circuit Description Input Coupling Input Attenuator Input Stage Input Attenuator Input Stage Second Cascode Stage Second Cascode Stage Output Stage Readout Block  SECTION 4 MAINTENANCE  Preventive Maintenance Cleaning Lubrication Visual Inspection Transistor Checks Recalibration Troubleshooting Troubleshooting Troubleshooting Troubleshooting Troubleshooting Troubleshooting Troubleshooting Equipment Troubleshooting Equipment Troubleshooting Techniques Obtaining Replacement Parts Soldering Techniques Obtaining Replacement Parts Soldering Techniques Abbreviations and Symbols Information Index of Mechanical Parts List Accessories  Change Information  Abbreviations and symbols used in this manual are based on or taken directly from IEEE Standard 260 "Standard Symbols for Units", MIL STD-128 and other standards of the electronics industry. Soldering Techniques  4-6 Change information if any, is located at the rear			CECTION & ELECTRICAL DARTE LICT	
Input Coupling Input Attenuator Input Stage First Cascode Stage Second Cascode Stage Output Stage Readout Block  SECTION 4 MAINTENANCE  Preventive Maintenance Cleaning Lubrication Visual Inspection Transistor Checks Recalibration Troubleshooting Troubleshooting Troubleshooting Troubleshooting Troubleshooting Equipment Troubleshooting Techniques Corrective Maintenance Obtaining Replacement Parts Soldering Techniques  Abbreviations and Symbols Parts Ordering Information Index of Electrical Parts List PARTS ILLUSTRATIONS  SECTION 7 DIAGRAMS AND MECHANICAL PARTS ILLUSTRATIONS  Biagrams Mechanical Parts Illustrations  Mechanical Parts List Information Index of Mechanical Parts List Information Index of Mechanical Parts List Accessories  Change Information  Abbreviations and symbols used in this manual are based on or taken directly from IEEE Standard 260 "Standard Symbols for Units", MIL STD-12B and other standards of the electronics industry. Soldering Techniques  4-6 Change information if any, is located at the rear		• •	SECTION O ELECTRICAL PARTS LIST	
Input Attenuator Input Stage First Cascode Stage Second Cascode Stage Output Stage Readout Block  Preventive Maintenance Cleaning Lubrication Visual Inspection Transistor Checks Recalibration Troubleshooting Troubleshooting Troubleshooting Troubleshooting Troubleshooting Troubleshooting Equipment Troubleshooting Troubleshooting Troubleshooting Equipment Troubleshooting Techniques Obtaining Replacement Parts Soldering Techniques  4-6  Parts Crdering Information  SECTION 7 DIAGRAMS AND MECHANICAL PARTS ILLUSTRATIONS  Mechanical Parts Illustrations  Mechanical Parts List Information Index of Mechanical Parts List Information  Accessories  Change Information  Abbreviations and symbols used in this manual are based on or taken directly from IEEE Standard 260 "Standard Symbols for Units", MIL STD-128 and other standards of the electronics industry.  Change information if any, is located at the rear		3-2	Abbreviations and Symbols	
Input Stage First Cascode Stage Second Cascode Stage Output Stage Readout Block  SECTION 4 MAINTENANCE  Preventive Maintenance Cleaning Lubrication Visual Inspection Transistor Checks Recalibration Troubleshooting Troubleshooting Aids Troubleshooting Equipment Troubleshooting Techniques Corrective Maintenance Colaring Replacement Parts A-6 Soldering Techniques A-7 Soldering Techniques A-8 SECTION 7 DIAGRAMS AND MECHANICAL PARTS LILUSTRATIONS  SECTION 8 MECHANICAL PARTS LIST  Mechanical Parts List Information Index of Mechanical Parts List Accessories  Mechanical Parts List Information  Mechanical Parts List Information  Change Information  Abbreviations and symbols used in this manual are based on or taken directly from IEEE Standard 260 "Standard Symbols for Units", MIL STD-128 and other standards of the electronics industry. Change information if any, is located at the rear		and the second s		
First Cascode Stage Second Cascode Stage Output Stage Readout Block  SECTION 4 MAINTENANCE  Preventive Maintenance Cleaning Lubrication Visual Inspection Transistor Checks Recalibration Troubleshooting Troubleshooting Troubleshooting Troubleshooting Equipment Troubleshooting Equipment Troubleshooting Techniques Corrective Maintenance Obtaining Replacement Parts Section 7 DIAGRAMS AND MECHANICAL PARTS ILLUSTRATIONS  Mechanical Parts Illustrations Mechanical Parts List Information Index of Mechanical Parts Illustrations Mechanical Parts List Accessories  Change Information  Abbreviations and symbols used in this manual are based on or taken directly from IEEE Standard Corrective Maintenance Obtaining Replacement Parts Soldering Techniques  4-6  Change information if any, is located at the rear			Index of Electrical Parts List	
Second Cascode Stage Output Stage Readout Block  SECTION 4 MAINTENANCE  Preventive Maintenance Cleaning Lubrication Visual Inspection Transistor Checks Recalibration Troubleshooting Troubleshooting Troubleshooting Aids Troubleshooting Equipment Troubleshooting Equipment Troubleshooting Equipment Troubleshooting Techniques Obtaining Replacement Parts Soldering Techniques  Obtaining Replacement Parts Section 7 DIAGRAMS AND MECHANICAL PARTS ILLUSTRATIONS  Diagrams Mechanical Parts Illustrations Mechanical Parts List Information Index of Mechanical Parts List Information Index of Mechanical Parts List Accessories  Change Information  Abbreviations and symbols used in this manual are based on or taken directly from IEEE Standard 260 "Standard Symbols for Units", MIL STD-128 and other standards of the electronics industry. Soldering Techniques  Change information if any, is located at the rear				
Output Stage Readout Block  3-3  SECTION 4 MAINTENANCE  Preventive Maintenance Cleaning Lubrication Visual Inspection Transistor Checks Recalibration  Troubleshooting Troubleshooting Troubleshooting Troubleshooting Troubleshooting Troubleshooting Troubleshooting Troubleshooting Troubleshooting Equipment Troubleshooting Techniques Corrective Maintenance Obtaining Replacement Parts Soldering Techniques  4-6  Diagrams Mechanical Parts Illustrations Mechanical Parts List Information Index of Mechanical Parts List Accessories  Change Information  Abbreviations and symbols used in this manual are based on or taken directly from IEEE Standard 260 "Standard Symbols for Units", MIL STD-128 and other standards of the electronics industry. Soldering Techniques  4-6  Change information if any, is located at the rear			SECTION 7 DIAGRAMS AND MECHANIC	CAL
SECTION 4 MAINTENANCE  Preventive Maintenance Cleaning Lubrication Visual Inspection Transistor Checks Recalibration Troubleshooting Troubleshooting Troubleshooting Troubleshooting Troubleshooting Equipment Troubleshooting Techniques Corrective Maintenance Obtaining Replacement Parts Section 8 MECHANICAL PARTS LIST Mechanical Parts List Information Index of Mechanical Parts Illustrations Mechanical Parts List Accessories  Change Information  Abbreviations and symbols used in this manual are based on or taken directly from IEEE Standard 260 "Standard Symbols for Units", MIL STD-12B and other standards of the electronics industry. Soldering Techniques  4-6 Change information if any, is located at the rear				
SECTION 4 MAINTENANCE  Preventive Maintenance Cleaning Lubrication Visual Inspection Transistor Checks Recalibration Troubleshooting Troubleshooting Troubleshooting Equipment Troubleshooting Equipment Troubleshooting Techniques Corrective Maintenance Obtaining Replacement Parts Section 8 MECHANICAL PARTS LIST Mechanical Parts List Information Index of Mechanical Parts Illustrations Mechanical Parts List Information  Mechanical Parts List Information Index of Mechanical Parts Illustrations Mechanical Parts List Information  Mechanical P			FARIS ILLUSIRATIONS	
Preventive Maintenance  Cleaning Lubrication Visual Inspection Transistor Checks Recalibration Troubleshooting Troubleshooting Troubleshooting Equipment Troubleshooting Techniques Obtaining Replacement Parts Obtaining Replacement Parts Soldering Techniques  SECTION 8 MECHANICAL PARTS LIST  Mechanical Parts List Information Index of Mechanical Parts Illustrations Mechanical Parts List Accessories  Change Information  Abbreviations and symbols used in this manual are based on or taken directly from IEEE Standard 260 "Standard Symbols for Units", MIL STD-12B and other standards of the electronics industry. Change information if any, is located at the rear	Reddoor block	3-3	Diagrams	
Cleaning Lubrication Visual Inspection Transistor Checks Recalibration Troubleshooting Troubleshooting Equipment Troubleshooting Techniques Obtaining Replacement Parts Soldering Techniques  4-1  Mechanical Parts List Information Index of Mechanical Parts Illustrations Mechanical Parts List Accessories  Mechanical Parts List Information Index of Mechanical Parts Illustrations Mechanical Parts List Accessories  Mechanical Parts List Information Index of Mechanical Parts Illustrations Mechanical Parts List Accessories  Change Information  Abbreviations and symbols used in this manual are based on or taken directly from IEEE Standard 260 "Standard Symbols for Units", MIL STD-12B and other standards of the electronics industry. Change information if any, is located at the rear	SECTION 4 MAINTENANCE		Mechanical Parts Illustrations	
Lubrication Visual Inspection Transistor Checks Recalibration Troubleshooting Troubleshooting Equipment Troubleshooting Techniques Obtaining Replacement Parts Soldering Techniques  4-1  Mechanical Parts List Information Index of Mechanical Parts Illustrations Mechanical Parts List Accessories  Change Information  Abbreviations and symbols used in this manual are based on or taken directly from IEEE Standard 260 "Standard Symbols for Units", MIL STD-12B and other standards of the electronics industry.  Soldering Techniques  4-6  Change information if any, is located at the rear	Preventive Maintenance	*	SECTION 8 MECHANICAL PARTS LIST	
Visual Inspection Visual Inspection Transistor Checks Recalibration  Troubleshooting Troubleshooting Aids Troubleshooting Equipment Troubleshooting Techniques  Obtaining Replacement Parts Soldering Techniques  4-1 Index of Mechanical Parts Illustrations Mechanical Parts List Accessories  Change Information  Abbreviations and symbols used in this manual are based on or taken directly from IEEE Standard 260 "Standard Symbols for Units", MIL STD-12B and other standards of the electronics industry. Change information if any, is located at the rear	Cleaning	4-1	Manhanian Danta list Information	
Transistor Checks 4-1 Recalibration 4-1 Troubleshooting Troubleshooting Aids Troubleshooting Equipment Troubleshooting Techniques 4-4 Corrective Maintenance Obtaining Replacement Parts Soldering Techniques 4-6  Mechanical Parts List Accessories  Change Information  Abbreviations and symbols used in this manual are based on or taken directly from IEEE Standard 260 "Standard Symbols for Units", MIL STD-12B and other standards of the electronics industry. Change information if any, is located at the rear	Lubrication	4-1		
Recalibration 4-1 Recalibration 4-1 Troubleshooting Troubleshooting Aids Troubleshooting Equipment 4-4 Troubleshooting Techniques 4-4 Corrective Maintenance 260 "Standard Symbols for Units", MIL STD-12B and other standards of the electronics industry. Soldering Techniques 4-6 Change Information  Accessories  Change Information  Abbreviations and symbols used in this manual are based on or taken directly from IEEE Standard 260 "Standard Symbols for Units", MIL STD-12B and other standards of the electronics industry. Change information if any, is located at the rear	Visual Inspection	4-1		
Troubleshooting Troubleshooting Aids Troubleshooting Equipment Troubleshooting Techniques  Corrective Maintenance Obtaining Replacement Parts Soldering Techniques  4-1  Change Information  Abbreviations and symbols used in this manual are based on or taken directly from IEEE Standard 260 "Standard Symbols for Units", MIL STD-12B and other standards of the electronics industry.  Change information  Change information	Transistor Checks	4-1		
Troubleshooting Aids Troubleshooting Equipment Troubleshooting Techniques Corrective Maintenance Obtaining Replacement Parts Soldering Techniques  4-2  Abbreviations and symbols used in this manual are based on or taken directly from IEEE Standard 260 "Standard Symbols for Units", MIL STD-12B and other standards of the electronics industry. Change information	Recalibration	4-1	Accessories	
Troubleshooting Aids Troubleshooting Equipment Troubleshooting Techniques Corrective Maintenance Obtaining Replacement Parts Soldering Techniques  4-2  Abbreviations and symbols used in this manual are based on or taken directly from IEEE Standard 260 "Standard Symbols for Units", MIL STD-12B and other standards of the electronics industry. Change information	Troubleshooting			
Troubleshooting Equipment Troubleshooting Techniques  4-4 Corrective Maintenance Obtaining Replacement Parts Soldering Techniques  4-4 Abbreviations and symbols used in this manual are based on or taken directly from IEEE Standard 260 "Standard Symbols for Units", MIL STD-12B and other standards of the electronics industry.  4-6 Change information if any, is located at the rear		4-2	Change Information	
Troubleshooting Techniques  Corrective Maintenance  Obtaining Replacement Parts  Soldering Techniques  4-4  are based on or taken directly from IEEE Standard 260 "Standard Symbols for Units", MIL STD-12B and other standards of the electronics industry. Change information if any, is located at the rear	——————————————————————————————————————		Abbroviations and sumbols used in this -	nan1
Corrective Maintenance 260 "Standard Symbols for Units", MIL STD-12B Obtaining Replacement Parts 4-6 and other standards of the electronics industry. Soldering Techniques 4-6 Change information if any, is located at the rear				
Obtaining Replacement Parts  4-6  Soldering Techniques  4-6  Change information if any, is located at the rear				
Soldering Techniques 4-6 Change information if any, is located at the rear		4-6		

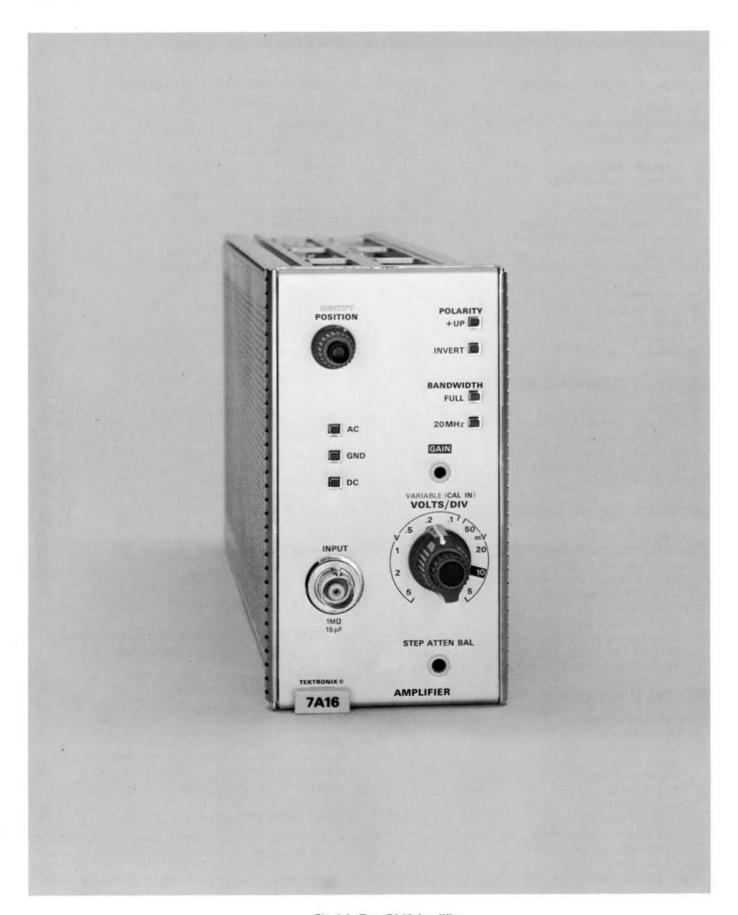


Fig. 1-1. Type 7A16 Amplifier.

# SECTION 1 SPECIFICATIONS

Change information, if any, affecting this section will be found at the rear of the manual.

# INTRODUCTION

The Type 7A16 vertical amplifier plug-in unit is part of the 7000-series oscilloscope system. It is a wide band DC coupled amplifier with calibrated deflection factors from 5 mV/Div to 5 V/Div. Internal gain and compensation circuits are automatically switched to correspond with the setting of the VOLTS/DIV switch. A polarity switch provides an inversion of the signal within the amplifier. A bandwidth limit switch allows low-frequency, low-level signals to be viewed with reduced interference from signals above 20 megahertz.

The upper bandwidth limit of the Type 7A16 is mainly determined by the oscilloscope in which it is used. For example, the Type 7A16 used with the Type 7504 oscilloscope will have an upper bandwidth limit of approximately 90 MHz, and when plugged into a Type 7704 oscilloscope the upper bandwidth limit will be approximately 150 MHz. Refer to the approperiate oscilloscope manual for complete information.

This instrument will meet the electrical characteristics listed in Table 1-1 following complete calibration as given in Section 5. The performance check procedure given in Section 5 provides a convenient method to check instrument performance without making internal adjustments.

The following electrical characteristics are valid over the stated environmental range for instruments calibrated at an ambient temperature of  $+20^{\circ}$ C to  $+30^{\circ}$ C, and after a five minute warmup unless otherwise stated.

The Type 7A16 should be calibrated every 1000 hours or every 6 months if used infrequently.

TABLE 1-1
ELECTRICAL

Characteristic	Performance
Deflection Factor Calibrated Range	5 mV/Div to 5 V/Div, 10 steps in a 1-2-5 sequence.
Gain Ratio Accuracy	Within 2% of gain adjusted at 10 mV/Div.
Uncalibrated (Variable)	Continuously variable between calibrated deflection factor settings. Extends uncalibrated deflection factor to at least 12.5 V/Div.
Gain	Permits adjustment of deflection factor for all 7000 series oscilloscopes.
Frequency Response; System Dependent (8 division reference)	With Type 7704 With Type 7504 Oscilloscope Oscilloscope
Upper Bandwidth DC Coupled	150 MHz 90 MHz
Lower Bandwidth AC Coupled	10 Hertz or less.
With P6053 Probe	1 Hertz or less.

20 Megahertz Band- width	DC to 20 megahertz within 3 megahertz.
Risetime	15 nanoseconds to 21 nanoseconds.
Maximum Input Voltage DC (Direct) Coupled 100 mV/Div to 5 V/Div	500 VDC. 500 V, DC + P-P AC at 1 kHz or less.
5 mV/Div to 50 mV/Div	100 VDC. 100 V, DC + P-P AC at 1 kHz or less.
AC (Capacitance Cou- pled Input DC Volt- age	500 V.
Input Resistance	1 megohm within 2%.
Input Capacitance	15 picofarads within 0.5 picofarad.
R and C Product	Within 1% over all deflection factor settings.
Maximum Input Gate Current	0.5 nanoampere or less at 0°C to +35°C, 3 nanoamperes or less at +35°C to +50°C.
Displayed Noise (Tangentially Measured)	0.1 division or less at 5 mV measured in a 7700-Series Oscilloscope.
DC Drift Drift With Time (Ambient Temperature and Line Voltage Constant) Short Term	250 μV/minute (P-P) or 0.05 division (whichever is greater) after 1 hour warmup.
Long Term	250 μV/hour (P-P) of 0.05 division (whichever is greater) after 1 hour warmup.
Drift With Ambient Temperature (Line Voltage Constant)	100 μV/°C or less.

# TABLE 1-2 ENVIRONMENTAL

Characteristic	Performance
Temperature Operating	0°C to +50°C
Altitude Non-operating	To 50,000 feet and —55°C
Transportation	Qualified under National Safe Transit Committee test procedure 1A, Category II.

#### TABLE 1-3 PHYSICAL

Item	Information
Finish	Front Panel is anodized aluminum.
Weight	About 1.75 pounds.
Dimensions	Fits plug-in compartment of 7000- Series Oscilloscopes.

# SECTION 2 **OPERATING INSTRUCTIONS**

Change information, if any, affecting this section will be found at the rear of the manual.

#### General

The Type 7A16 vertical plug-in unit operates with a Tektronix 7000-series oscilloscope and a 7B-series time base unit to form a complete oscilloscope system. To effectively use the Type 7A16, the operation and capabilities of the instrument should be known. This section describes the operation of the front-panel controls and connector, gives first time operation and general operating information, and lists some measurement techniques using the amplifier.

# Installation

The Type 7A16 is designed to operate in a vertical plugin compartment of Tektronix 7000-series oscilloscopes. For X-Y operation, the plug-in unit may also be installed in a horizontal plug-in compartment. (Refer to the indicator oscilloscope instruction manual for information concerning X-Y operation.)

To install the Type 7A16 into a plug-in compartment, push it in until it is seated into the front panel of the indicator unit. Pull the release latch to disengage the plug-in unit, then continue pulling on the release latch to remove the plug-in from the indicator.

# FRONT PANEL CONTROLS AND CONNECTOR

All controls required for operation of the Type 7A16 are located on the front panel of the unit. A brief description of the function or operation of the front-panel controls follows. More detailed information is given under General Operating Information.

**VOLTS/DIV** Selects vertical deflection factor from 5 mV/DIV to 5 V/DIV in 1-2-5 sequence (VAR control must be in the calibrated position for indicated deflection factor).

> Provides variable uncalibrated deflection factors to at least 2.5 times the setting of the VOLTS/DIV switch. Push knob in and release to activate; the knob moves outward from the VOLTS/DIV control when

activated.

**POSITION** Controls vertical position of trace.

**IDENTIFY** Moves trace upward about 0.25 division for identification. (Also replaces readout

information with the word IDENTIFY.)

**POLARITY** 

Provides means of inverting the display. +UP: A positive-going voltage at the INPUT produces a positive deflection on the CRT.

INVERT: A positive-going voltage at the INPUT produces a negative deflection on the CRT.

BANDWIDTH Provides limiting of upper bandwidth.

FULL: Normal operation with full band-

width capabilities.

20 MHz: Amplifier bandwidth limited to 20 MHz to provide a reduction in displayed high-frequency noise or interference.

AC-GND-DC Selects method of coupling input signal to Input Amplifier.

GAIN Screwdriver adjustment to set gain of the amplifier. Gain standardized at 10 mV/

Div.

STEP ATTEN Screwdriver adjustment to minimize trace BAL shift when switching VOLTS/DIV control.

**INPUT** Signal input connector. Input impedance

of 1 megohm paralleled by 15 picofarads. Similar to standard BNC connector, but with additional conductor to indicate to the readout circuit the attenuation factor

of the probe being used.

# FIRST-TIME OPERATION

# **General**

When shipped from the factory, the Type 7A16 has been calibrated to meet the specifications listed in Section 1 and is ready to be used with an indicator oscilloscope.

The following steps demonstrate the basic operation of the controls of the Type 7A16. It is recommended that this procedure be followed completely for familiarization with the instrument. Operation of the indicator oscilloscope and time base unit is described in the instruction manuals for these units.

# **Setup Information**

- 1. Insert the Type 7A16 into a vertical plug-in compartment of a 7000-series indicator oscilloscope.
- 2. Insert a 7B-series time-base unit into a horizontal plugin compartment.
  - 3. Set the controls as follows:

**VARIABLE** 

(CAL IN)

#### Type 7A16

VOLTS/DIV	10 mV
VARIABLE (CAL IN)	Calibrated
POSITION	Midrange
POLARITY	+UP
BANDWIDTH	FULL
AC-GND-DC	GND

#### Time Base

Time/Div	0.5 ms
Variable Time/Div	Calibrated
Slope	0/+
MODE	P-P Auto
Coupling	AC
Source	Int
Position	Midrange

#### Indicator Oscilloscope

Calibrator	40 mV Square Wave
Intensity	Counterclockwise
Focus	Midrange
Astigmatism	Midrange
Scale Illum	As desired

- 4. Connect the oscilloscope to a power source which meets the voltage and frequency requirements of the oscilloscope power supply.
- 5. Turn the oscilloscope power on and allow about five minutes warmup time.
- 6. Advance the Intensity and set the time base unit triggering controls to obtain a free-running trace on the CRT. Adjust the POSITION controls to center the trace vertically.
- 7. Connect the Calibrator output to the INPUT connector, using a 50-ohm BNC cable. Push the Type 7A16 DC input coupling button. (Adjust horizontal and vertical POSITION controls as necessary.)
- 8. Set the triggering controls for a stable display. (Adjust Focus and Astigmatism controls as necessary.)
- 9. Check the display for four divisions of vertical deflection (see Fig. 2-1). If necessary, adjust the front panel GAIN control for four divisions of deflection.
- 10. Press the IDENTIFY button to erase the readout information. When the IDENTIFY button is pressed and released, the display moves up and down about 0.25 division. This movement identifies the waveform when more than one display is on the CRT.
- 11. Press the INVERT button to display the opposite polarity of the square wave. (When observing a symmetrical waveform such as the Calibrator square wave, inverting the signal makes no apparent change in the display. This is because the time-base unit triggers on the indicated slope of the displayed waveform.)
- 12. Switch the VOLTS/DIV control through the remaining positions of the switch, setting the Calibrator to appropriate output amplitudes. The STEP ATTEN BAL control may be adjusted to minimize trace shift when switching the VOLTS/DIV control from 5 mV/DIV to 20 mV/DIV.

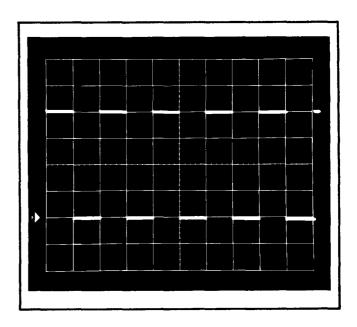


Fig. 2-1. 40 mV Calibrator square wave.

This completes the basic operating procedure for the Type 7A16. Instrument operations not explained here, or operations which need further explanation, are discussed under General Operating Information.

#### **CONTROL SETUP CHART**

Figure 2-2 shows the front panel of the Type 7A16. This chart can be reproduced and used as a front-panel record for special measurements, applications or procedures, or it may be used as a training aid for familiarization with this instrument.

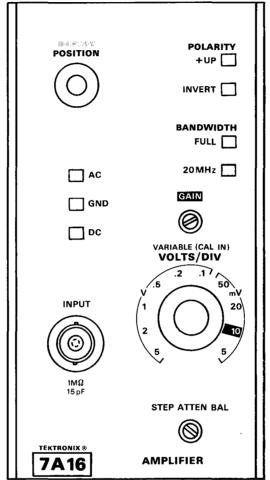
# **GENERAL OPERATING INFORMATION**

# **Signal Connection**

In general, probes offer the most convenient means of connecting signals to the input of the Type 7A16. The Tektronix probes are shielded to prevent pickup of electrostatic interference. A  $10\times$  attenuator probe offers a high input impedance and allows the circuit under test to perform very close to normal operating conditions. However, a  $10\times$  probe also attenuates the input signal ten times. To obtain maximum bandwidth when using probes, observe the grounding considerations given in the probe manuals. The probeto-connector adapters and the bayonet-ground tip provide the best frequency response. Remember that a ground strap only a few inches in length can produce several percent of ringing when operating at the higher frequency limit of this system (see Fig. 2-3).

In high-frequency applications requiring maximum overall bandwidth, use a coaxial cable terminated at both ends in the characteristic impedance of the cable. To maintain the high-frequency characteristics of the applied signal, use high-quality, low-loss cable. Resistive coaxial attenuators can be used to minimize reflections if the applied signal has suitable amplitude.

# **TYPE 7A16 AMPLIFIER SETUP CHART**



DATA	<u> </u>	······································	

Fig. 2-2. Control setup chart.

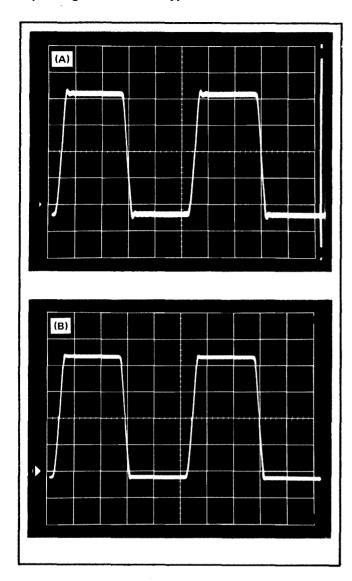


Fig. 2-3. Waveform distortion produced with incorrect probe ground.

(A) Eighteen-inch ground strap between generator and oscilloscope.

(B) Five-inch ground strap.

High-level, low-frequency signals can be connected directly to the Type 7A16 INPUT connector with short unshielded leads. This coupling method works best for signals below about one kilohertz and deflection factors above one volt/division. When this method is used, establish a common ground between the Type 7A16 and the equipment under test (common ground provided by line cords is usually inadequate). Attempt to position the leads away from any source of interference to avoid errors in the display. If interference is excessive with unshielded leads, use a coaxial cable or a probe.

#### Input Coupling

The AC-DC-GND pushbutton switch allows a choice of input coupling. The type of display desired determines the mode of input coupling used. The DC position can be used for most applications. However, if the DC component of the signal is much larger than the AC component, the AC position will probably provide a better display. DC coupling

should be used to display AC signals below about 10 hertz as they will be attenuated in the AC position.

In the AC position, the DC component of the signal is blocked by a capacitor in the input circuit. The low-frequency response in the AC position is about 10 hertz (—3 dB point). Therefore, some low-frequency distortion can be expected near this frequency limit. Distortion will also appear in square waves which have low-frequency components.

The GND position provides a ground reference at the input of the Type 7A16. The signal applied to the INPUT connector is internally disconnected but not grounded. The input circuit is held at ground potential, eliminating the need to externally ground the input to establish a DC ground reference.

The GND position is also used to pre-charge the coupling capacitor to the average voltage level of the signal applied to the INPUT connector. The pre-charging network allows the input-coupling capacitor to charge to the DC source voltage level when the Input Coupling switch is set to GND. The procedure for using this feature is as follows:

- 1. Before connecting the signal containing a DC component to the Type 7A16 INPUT connector, push the Input Coupling GND button. Then connect the signal to the INPUT connector.
- 2. Allow about one second for the coupling capacitor to charge.
- 3. Push the Input Coupling AC button. The trace (display) will return on the screen and the AC component of the signal can be measured in the normal manner.

#### **Deflection Factor**

The amount of vertical deflection produced by a signal is determined by the signal amplitude, the attenuation factor of the probe (if used), the setting of the VOLTS/DIV switch and the setting of the VARIABLE VOLTS/DIV control. The calibrated deflection factors indicated by the VOLTS/DIV switch apply only when the VARIABLE control is in the calibrated (pushed in) position.

The VARIABLE VOLTS/DIV control provides uncalibrated vertical deflection between the calibrated settings of the VOLTS/DIV switch. The VARIABLE control extends the maximum vertical deflection factor of the Type 7A16 to at least 12.5 volts/division (5 V position).

The GAIN control, a front-panel screwdriver adjustment, sets the gain of the Type 7A16 Amplifier. The vertical deflection of the unit should be checked for accuracy prior to making critical measurements, using either the indicator unit Calibrator or a Standard Amplitude Calibrator (067-0502-00). If adjustment is necessary, the GAIN control should be adjusted with the VOLTS/DIV switch in the 10 mV position. Apply a 40 millivolt Calibrator signal to the INPUT and adjust GAIN for four divisions of display.

#### **Step Attenuator Balance**

To check the step attenuator balance, push the Input Coupling GND button and set the time-base triggering controls to provide a free-running trace. Change the VOLTS/DIV switch from 20 mV to 5 mV. If the trace moves vertically, adjust the front-panel STEP ATTEN BAL adjustment as follows (allow

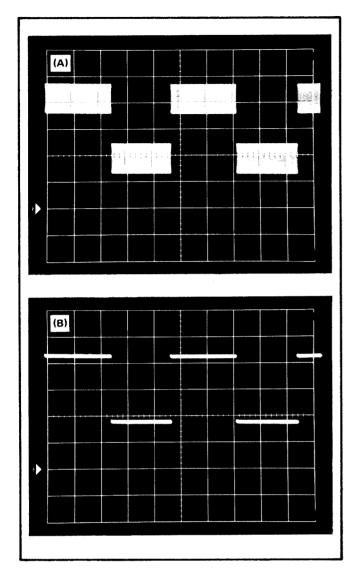


Fig. 2-4. (A) CRT display showing high-frequency interference when attempting to view low-level, low-frequency signal, (B) resultant display when 20 MHz pushbutton is pressed.

at least ten minutes warmup before performing this adjustmentl:

- 1. With the Input Coupling GND button pressed and the VOLTS/DIV switch set to 20 mV, move the trace to the center horizontal line of the graticule with the vertical POSITION control.
- 2. Set the VOLTS/DIV switch to  $5\,\mathrm{mV}$  and adjust the STEP ATTEN BAL adjustment to return the trace to the center horizontal line.
- 3. Recheck step attenuator balance and repeat adjustment until no trace shift occurs as the VOLTS/DIV switch is changed from  $20\,\text{mV}$  to  $5\,\text{mV}$ .

# Signal Polarity

The POLARITY switch provides a means of inverting the display. With the  $+ \mathrm{UP}$  button pressed, a positive-going

voltage at the INPUT produces a positive deflection on the CRT. With the INVERT button pressed, a positive-going voltage at the INPUT produces a negative deflection on the CRT. However, when observing a symmetrical waveform, such as the Calibrator square wave, inverting the signal makes no apparent change in the display. This is due to the time-base unit triggering on the indicated slope of the displayed waveform.

# **Bandwidth Limiter**

The bandwidth switch provides a method of reducing interference from unwanted high-frequency signals when viewing low-frequency signals. With the FULL button pressed, the full bandwidth capabilities of the amplifier are available. When the 20 MHz button is pressed, the upper—3dB bandwidth point of the amplifier is limited to about 20 megahertz. The unwanted high-frequency signals (such as television broadcast radiation interference) are reduced in the displayed waveform. Fig. 2-4 illustrates the use of this feature. The waveform in Fig. 2-4A is the display produced when a low-level, low-frequency signal is viewed in the presence of a strong 50-megahertz radiation (FULL button pressed). Fig. 2-4B shows the resultant CRT display when the high-frequency interference is reduced by pressing the 20 MHz button.

# **Display Identification**

When the Type 7A16 IDENTIFY button is pressed, the CRT display is deflected upward about 0.25 division for identification. This feature is particularly useful when the Type 7A16 is used with an indicator unit designed for use with more than one vertical amplifier.

When using an oscilloscope system equipped with the readout feature, information such as polarity, deflection factor, etc. is displayed on the CRT. When the Type 7A16 IDENTIFY button is pressed, the readout information pertaining to the Type 7A16 is replaced by the word IDENTIFY.

#### **BASIC APPLICATIONS**

The following information describes the procedure and technique for making basic measurements with a Type 7A16 Amplifier. These applications are not described in detail, since each application must be adapted to the requirements of the individual measurements. Familiarity with the Type 7A16 will permit these basic techniques to be applied to a wide variety of uses.

# Peak-to-Peak Voltage Measurements—AC

To make a peak-to-peak voltage measurement, use the following procedure:

- 1. Connect the signal to the INPUT connector.
- 2. Push the Input Coupling AC button.
- 3. Set the VOLTS/DIV switch to display about five divisions of the waveform. Make sure the VARIABLE VOLTS/DIV control is in the calibrated (pushed in) position.

#### NOTE

For low-frequency signals below about 10 hertz, push the DC button.

- 4. Set the triggering controls to obtain a stable display. Set the sweep rate to display several cycles of the waveform.
- 5. Turn the vertical POSITION control so the lower portion of the waveform coincides with one of the graticule lines below the center horizontal line, and the top of the waveform is within the viewing area. Move the display with the horizontal position control, so one of the upper peaks lies near the center vertical line (see Fig. 2-5).
- 6. Measure the divisions of vertical deflection from peak-to-peak.

#### NOTE

This technique may also be used to make measurements between two points on the waveform rather than peak-to-peak.

7. Multiply the distance measured in step 6 by the VOLTS/DIV switch setting. Also include the attenuation factor of the probe, if any.

Example. Assume a peak-to-peak vertical deflection of 4.6 divisions using a  $10\times$  attenuator probe and a VOLTS/DIV switch setting of .5 V.

Using the formula:

Volts vertical VOLTS/DIV probe peak to peak = deflection  $\times$  setting  $\times$  attenuation factor

Substituting the given values:

Volts peak to peak =  $4.6 \times 0.5 \times 10$ 

The peak-to-peak voltage is 23 volts.

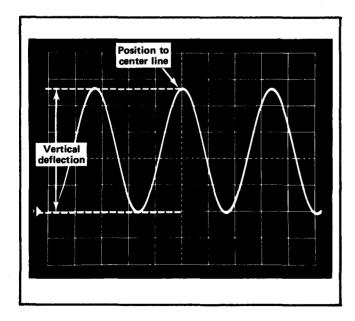


Fig. 2-5. Measuring peak-to-peak voltage of a waveform.

# Instantaneous Voltage Measurements—DC

To measure the DC level at a given point on a waveform, use the following procedure:

- 1. Connect the signal to the INPUT connector.
- 2. Set the VOLTS/DIV switch to display about five divisions of the waveform. Make sure the VARIABLE VOLTS/DIV control is in the calibrated (pushed in) position.
  - 3. Push the Input Coupling GND button.
  - 4. Set the triggering controls to obtain a free-running trace.
- 5. Position the trace to the bottom line of the graticule or other reference line. If the voltage to be measured is negative with respect to ground, position the trace to the top line of the graticule. Do not move the vertical POSITION control after this reference line has been established.

#### NOTE

To measure a voltage level with respect to a voltage other than ground, make the following changes in step 5: Push the Input Coupling DC button and apply the reference voltage to the INPUT connector. Then position the trace to the reference line.

- 6. Push the Input Coupling DC button. The ground reference line can be checked at any time by pushing the GND button.
- 7. Set the triggering controls to obtain a stable display. Set the sweep rate to display several cycles of the signal.
- 8. Measure the distance in divisions between the reference line and the point on the waveform at which the DC level is to be measured. For example, in Fig. 2-6 the measurement is made between the reference line and point A.
- 9. Establish the polarity of the signal. If the waveform is above the reference line, the voltage is positive; below the line, negative.
- 10. Multiply the distance measured in step 8 by the VOLTS/DIV switch setting. Include the attenuation factor of the probe, if any.

Example. Assume that the vertical distance measured is 4.6 divisions, the waveform is above the reference line, using a  $10\times$  attenuator probe and a VOLTS/DIV switch setting of 2 V.

Using the formula: Instantaneous Voltage =

vertical VOLTS/DIV probe distance × polarity × setting × attenuation (divisions)

Substituting the given values:

Instantaneous voltage =  $4.6 \times +1 \times 2 \times 10$ 

The instantaneous voltage is +92 volts.

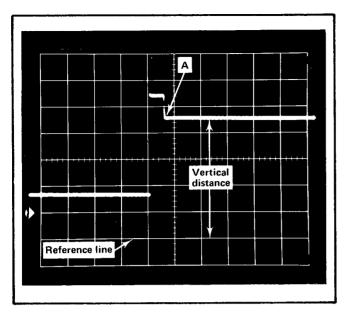


Fig. 2–6. Measuring instantaneous DC voltage with respect to a reference voltage.

# **Voltage Comparison Measurements**

In some applications, it may be necessary to establish a set of deflection factors other than those indicated by the VOLTS/DIV switch. This is useful for comparing signals to a reference voltage amplitude. To establish a new set of deflection factors based upon a specific reference amplitude, proceed as follows:

- 1. Apply the reference signal of known amplitude to the INPUT connector. Using the VOLTS/DIV switch and the VARIABLE control, adjust the display for an exact number of divisions. Do not move the VARIABLE VOLTS/DIV control after obtaining the desired deflection.
- 2. Divide the amplitude of the reference signal (volts) by the product of the deflection in divisions (established in step 1) and the VOLTS/DIV switch setting. This is Deflection Conversion Factor.

- 3. To determine the peak-to-peak amplitude of a signal compared to a reference, disconnect the reference and apply the signal to the INPUT connector.
- 4. Set the VOLTS/DIV switch to a setting that provides sufficient deflection to make the measurement. Do not readjust the VARIABLE VOLTS/DIV control.
- 5. To establish an Adjusted Deflection Factor at any setting of the VOLTS/DIV switch, multiply the VOLTS/DIV switch setting by the Deflection Conversion Factor established in step 2.

This Adjusted Deflection Factor is correct only if the VAR-IABLE VOLT/DIV control is not moved from the position set in step 1.

6. Measure the vertical deflection in divisions and determine the amplitude by the following formula:

Example. Assume a reference signal amplitude of 30 volts, a VOLTS/DIV setting of 5 and a deflection of four divisions. Substituting these values in the Deflection Conversion Factor formula (step 2).

Deflection Conversion = 
$$\frac{30 \text{ V}}{4 \times 5 \text{ V}} = 1.5$$

Then, with a VOLTS/DIV switch setting of 2, the Adjusted Deflection Factor (step 5) is:

Adjusted Deflection 
$$=$$
 2 V  $\times$  1.5  $=$  3 volts/division Factor

To determine the peak-to-peak amplitude of an applied signal which produces a vertical deflection of five divisions, use the Signal Amplitude formula (step 6):

$$rac{ ext{Signal}}{ ext{Amplitude}} = 3 ext{ V} imes 5 = 15 ext{ volts}$$

# SECTION 3 CIRCUIT DESCRIPTION

Change information, if any, affecting this section will be found at the rear of this manual.

## Introduction

This section of the manual contains a description of the circuitry used in the Type 7A16 amplifier. The description begins with a discussion of the instrument using the block diagrams shown in the Diagrams section. Then each circuit is described in detail using the block diagram to show interconnections between the circuits and the relationship of the frontpanel controls to the individual stages.

Complete schematics of each circuit are given in the Diagrams section. Refer to these diagrams throughout the following circuit description for electrical values and relationship.

#### **BLOCK DIAGRAM DESCRIPTION**

The following discussion is provided to aid in understanding the overall concept of the Type 7A16 before the individual circuits are discussed in detail. Each block on the Block Diagram, located in the Diagrams section, represents an individual circuit within the instrument. The number on

each block refers to the diagram on which the complete circuit is found.

The signal to be displayed on the CRT is applied to the INPUT connector, through the input coupling circuit to the VOLTS/DIV switch. The VOLTS/DIV switch provides the appropriate input attenuation and applies the signal to the first stage of the Input Amplifier. The signal is coupled through two emitter followers, Q40-Q50, to the First Cascode stage, which operates as a phase-splitter. The First Cascode stage, Q60A-Q70-Q60B-Q90, contains variable gain circuits and bandwidth limiting circuits.

The Second Cascode Stage, Q100A-Q120A-Q100B-Q120B, provides gain-switching, signal polarity inversion, and vertical positioning. The gain-switching relays in the two cascode stages are operated by the VOLTS/DIV switch which, with the input attenuators, sets the overall gain of the amplifier. Additional amplification is provided by the Output Amplifier, Q125-Q140-Q165-Q180. The Trigger Pickoff circuit, Q130-Q135-Q170-Q175, takes the signal from the emitters of Q125-Q165 and amplifies it to provide + and — trigger signals for the time base unit.

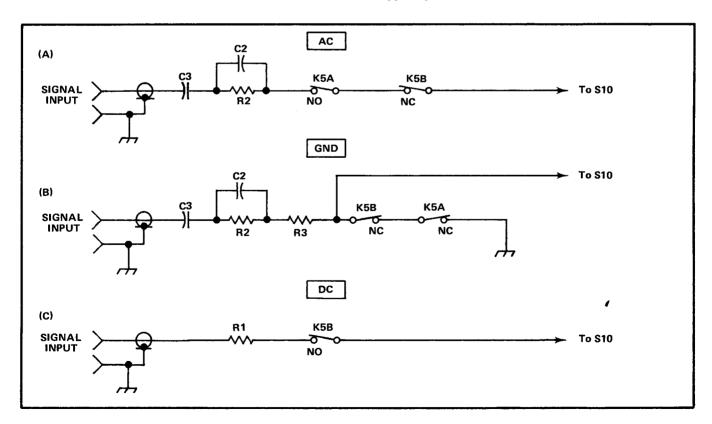


Fig. 3-1. Signal paths through input COUPLING switch.

#### Circuit Description—Type 7A16

In addition to the functions of the amplifier just explained, the Type 7A16 also provides readout logic for the indicator oscilloscope, Logic identifying the Polarity and the deflection factor, whether calibrated or uncalibrated is supplied. When the IDENTIFY button is pressed, the readout is replaced with the word IDENTIFY. At the same time, the collector of Q120B is grounded through R200, shunting some of the collector current which moves the trace upward approximately 0.25 division.

# **DETAILED CIRCUIT DESCRIPTION**

# Input Coupling

Input signals applied to the INPUT connector can be ACcoupled, DC-coupled, or internally disconnected. The input coupling relay, K5, a dual pole alternate throw relay, is operated by S3, a three-position pushbutton switch. Only one side of the DPAT relay operates at a time. When the AC button is pressed, K5A is actuated providing a signal path from the INPUT connector through C3-K5A-K5B-C2-R2 (see Fig. 3-1A). In this position, C3 prevents the DC component of the signal from passing to the amplifier. When the DC button is pressed, K5B is actuated, providing a signal path directly through K5B to R1 (see Fig. 3-1C). When the GND button is pressed, the input signal is AC-coupled through C3 and R3 to ground. The input circuit is grounded to provide a zero volts reference level (see Fig. 3-1B). Resistor R3 allows C3 to be precharged in the GND position so the trace remains on screen when the AC button is pressed with a high DC level applied.

# Input Attenuator

The effective overall deflection factor of the Type 7A16 is determined by the VOLTS/DIV switch attenuators and the gain-switching relays, K105-K110-K155-K160. The 5 mV, 10 mV, and 20 mV switch positions employ  $1\times$  attenuators. In all positions of the VOLTS/DIV switch above 20 mV, the basic deflection factor of the vertical deflection system is 20 millivolts per division of deflection. To increase this basic deflection factor to the values indicated on the front panel, precision attenuators are switched into the input circuit. The positions of the VOLTS/DIV switch and the corresponding attenuators are as follows:

5 mV	$1\times$	.2 V	$10 \times$
10 mV	$1\times$	.5 V	25 $ imes$
20 mV	$1\times$	.1 V	$50 \times$
50 mV	$2.5 \times$	2 V	100×
.1 V	$5 \times$	5 V	250 $ imes$

The Input Attenuators, with R14-C14-R17-R18-C18 form frequency-compensated voltage dividers. For DC and low-frequency signals, they are primarily resistance dividers and the voltage attenuation is determined by the resistance ratio in the circuit. The reactance of the capacitors in the circuit is so high at low frequencies that their effect is negligible. However, at higher frequencies, the reactance of the capacitors decreases and the attenuator becomes primarily a capacitance voltage divider.

In addition to providing constant attenuation at all frequencies within the bandwidth of the system, the Input Attenuators are designed to maintain the same input RC

characteristics (one megohm  $\times 15$  pF) for each setting of the VOLTS/DIV switch. The attenuators contain adjustable shunt capacitors to provide input capacitance.

# Input Stage

The signal from the Input Attenuator is connected to the Input Stage through the network R14-C14-R17-R18-C18. These resistors are part of the attenuation network at all VOLTS/DIV switch positions. Variable capacitor C18 adjusts the basic input time constant for a nominal value of one megohm  $\times$  15 picofarads. R14-C14 isolate the input from the gate of the input field-effect transistor, Q20. Resistor R14 also limits the gate current of Q20.

FET Q20B is a constant current source for the source follower, Q20A. The DC Bal adjustment, R34, varies the gate level of Q20B to provide a zero volt level at the base of Q60A with no signal applied. Low-frequency by-pass capacitors C34 and C36, with L34, filter noise from the gate of Q20B. L20-C20 and L30-C30 are decoupling networks. Damping for Q20A is provided by R23. The source of Q20A is isolated from the base of Q40 by R28-C28. Resistor R28 sets the bias of Q20A, preventing the gate from going more positive than the source. Damping for Q20B is provided by R38. The bias for Q20B is set by R30. Diode CR29 clamps the gate of Q20A at about —12 volts, protecting the FET from large negative voltage swings.

Two emitter followers, Q40 and Q50 couple the input signal through R52-C52 to the First Cascode Stage. Capacitors C45 and C52 are adjustable for high frequency peaking. In the collector of each of the emitter followers is a damping adjustment. Maximum damping for Q40 is achieved when R40 is adjusted away from the collector of Q40. Maximum damping for Q50 is achieved when R55 is adjusted away from the collector of Q50. These two damping adjustments are set for a compromise between maximum risetime and minimum ringing. Capacitors C23 and C56 assure that no feedback signals are seen by the input FETs.

# First Cascode Stage

The first cascode stage is a paraphase amplifier. With R34 adjusted for zero volts at the base of Q60A, the quiescent current through both sides of the paraphase amplifier is approximately 10 milliamperes. The input signal drives the base of Q60A, and the base of Q60B is grounded through R82. A positive signal at the base of Q60A increases the current through R80-Q60A-R68-R71-Q70-R100 and reduces the current through R80-Q60B-R88-R90-Q90-R150, producing push-pull signals at the bases of Q100A and Q100B. Resistor R68, paralleled by C68-L68, and R88, paralleled by C68-L88, provide thermal balance for the stage. Resistors R70, R71 and R90 provide damping. The divider R73-R74 sets the base voltage of Q70 and Q90 at approximately 6.7 V. The common-emitter circuit contains two high-frequency peaking adjustments, C61 and R61.

The voltage gain of this stage, from single-ended to pushpull, is approximately 1.6 and is set by the ratio of R100 or R150 to R60 and R80. With K65 as shown (VARIABLE pushed in), the exact gain of the amplifier is set by R66 (VOLTS/DIV switch set to 10 mV), which adjusts the amount of shunt current through R64-R66-R84. Relay K65, actuated in the uncalibrated position, switches in the R65-R85-R86

network and switches out the R64-R66-R84 network. The VARIABLE control (R86) affects the gain of the amplifier by a greater degree than R66, due to the comparatively small values of R65 and R85. With R86 set to minimum resistance, the gain of the amplifier is reduced by a factor of at least 2.5. The Var Gain Bal control, R89, is adjusted for no trace shift when K65 is switched.

With the BANDWIDTH switch FULL button pressed, the output of the first cascode stage is connected directly through K75 to the second cascode stage. With the 20 MHz button pressed, the bandwidth limiting circuit, C77-C97-L76-L96-L97, is switched in by K75. This sets the upper frequency limit of the amplifier to approximately 20 MHz.

# Second Cascode Stage

The second cascode stage, formed by Q100A-Q120A-Q100B-Q120B, contains gain switching, signal inversion, and vertical positioning circuits. The gain of this stage in the 5 mV position of the VOLTS/DIV switch is set by the ratio of R123 or R163 to R102 or R151. With the POSITION control and R117 set to midrange, the quiescent current through Q100A and Q100B is approximately 15 milliamperes, set by R104-R106-R156. The quiescent current through Q120A and Q120B is approximately 10 milliamperes, set by R118-R166. In the 10 mV position, K110 and K160 switch in shunt resistor R161, reducing the gain by a factor of two. In the 20 mV position, K105 and K155 switch in shunt resistor R159 and series resistors R108 and R158, reducing the gain by an additional factor of two. The deflection factor at the output of this stage is 15 mV/Div per side.

The emitter circuit of Q100A-Q100B contains high-frequency peaking adjustments C102-R103-C103. Compensation in the 10 mV position is provided by C111-R111. Additional compensation in the 20 mV position is provided by C109-R109. Thermal compensation networks for Q100A and Q100B are formed by R105-C105 and R155-C155. Resistors R106 and R156 set the voltage drop across the gain-setting dividers to zero volts. The Step Atten Bal control, R153, is adjusted for no trace shift when switching K105 and K155 or K110 and K160. Thermal compensation networks for Q120A and Q120B are formed by C124-R124 and C164-R164.

The polarity inversion circuit consists of a DPDT relay, K115, and a front panel push-button POLARITY switch. With the +UP button pressed, the relay is as shown in the schematic. With the INVERT button pressed, K115 is actuated, inverting the signal outputs and the trigger outputs.

The vertical POSITION control, R115, applies DC voltages of opposite polarity to the two sides of the amplifier through R114 and R160. This offset voltage is DC-coupled to the output moving the trace upward or downward on the CRT. With the vertical POSITION control set to midrange, the position centering network, R117-R118-R168, applies a positive voltage to one side of the amplifier, centering the trace vertically on the CRT.

# **Output Stage**

The output stage consists of the emitter-feedback and shunt-feedback amplifiers, Q125-Q165 and Q140-Q180, and the trigger pick-off amplifier Q130-Q135-Q170-Q175. The gain of the output amplifier is approximately five, set by

the ratio of R142-R182 to R128-R168. Thermistor (RT128) and Varactors (CR128-CR168) provide proper compensation for transient response variations with temperature. Thermal compensation for Q125 and Q165 is provided by R125-C125 and R165-C165. Resistor R129 provides the DC current source for Q125 and Q165. Decoupling for the output amplifier is provided by L140 and C140. The —15 volt supply is decoupled in the common-emitter circuit of Q140-Q180 by L143 and C143. R141-R181-R143 provide approximately 18 milliamperes DC current for each output transistor. The output signals are reverse terminated by C145-R145 and C185-R185. These networks, with the 50-ohm terminations in the indicator oscilloscope, produce an output deflection factor of 25 millivolts/division per side.

The trigger pickoff amplifier takes the output signal from the emitters of Q125 and Q165 and amplifies it to a level near that of the output amplifier. Resistor R131 sets the DC current for Q130 and Q170 through R130 and R170 respectively. Capacitor C130 provides high-frequency peaking. Thermal compensation for Q130 and Q170 is provided by C133-R133 and C173-R173. Divider R172-R174-R137-R177 provides approximately 15 milliamperes each for Q135-Q175. The output signal from the trigger pickoff amplifier is reverse terminated by C138-R138 and C178-R178.

#### Readout Block

The readout block consists of switching resistors and a probe sensing device. The switching resistors, selected by the setting of the Readout Switch (part of the VOLTS/DIV switch), are used to signal the Indicator Oscilloscope the setting of the VOLTS/DIV switch.

Refer to Schematic Diagram 4 (Section 7), Switching and Interconnecting Plug, to find the resistors associated with a particular setting of the VOLTS/DIV switch. The number 1, 2, or 5 is selected by R207-R208-R209. R207 selects the numeral 1, R207-R208 selects the numeral 2, and R207-R209 selects the numeral 5. R226-R228-R234 and the output of the probe sensing device (Q200) selects the decimal point (number of zeroes). R224-R225, when switched in, gives the Volts sub-unit m (milli). R205-R206 selects the symbol V (volts). R218-R220 selects the symbol > when the VARIABLE VOLTS/DIV knob is in the uncalibrated position. R219-R222 selects the symbol ↓ when the INVERT pushbutton is pressed in.

The probe connected to the INPUT connector forms a voltage divider with R202 to the -15 volt supply. The amount of probe resistance will determine the bias applied to the base of Q200.

With a  $1 \times$  probe connected, Q200 is biased off by the -15 volt supply, and the deflection factor (in the readout display) is determined by the setting of the Readout Switch (part of the VOLTS/DIV switch).

With a 10 $\times$  probe connected to the INPUT connector, the bias applied to the base of Q200 will allow 100  $\mu$ A of collector current to flow. When the clock pulse interrogates interface connector B33, this current is added to the current corresponding to the setting of the Readout Switch to increase the deflection factor (in the displayed readout) by 10.

The Indicator Oscilloscope displayed readout will give the correct deflection factor from the probe tip (using the

# Circuit Description—Type 7A16

recommended attenuator probes) whereas the VOLTS/DIV knob on the Plug-In will display only the Plug-In deflection factor.

The trace IDENTIFY button, when pressed, does two things:

- 1. It causes the trace, representing the output of the Type 7A16, to move upward a small amount by inserting R200 from the collector of Q120B to ground. This shunts a small amount of the collector current causing the trace to move.
  - 2. It also grounds the base of Q200. This causes Q200

to turn on hard erasing the displayed readout and causing the word IDENTIFY to appear.

These two actions aid in identifying the Type 7A16 trace when multiple traces are displayed. When the IDENTIFY button is released, the readout is restored to its previous display.

For more specific information on the operation of the Indicator Oscilloscope refer to the appropriate Indicator Oscilloscope Manual.

# SECTION 4 MAINTENANCE

Change information, if any, affecting this section will be found at the rear of the manual.

# Introduction

This section of the manual contains maintenance information for use in preventive maintenance, corrective maintenance and troubleshooting of the Type 7A16.

# PREVENTIVE MAINTENANCE

#### General

Preventive maintenance consists of cleaning, visual inspection, lubrication, etc. Preventive maintenance performed on a regular basis may prevent instrument breakdown and will improve the reliability of this instrument. The severity of the environment to which the Type 7A16 is subjected determines the frequency of maintenance. A convenient time to perform preventive maintenance is preceding recalibration of the instrument.

# Cleaning

The Type 7A16 should be cleaned as often as operating conditions require. Accumulation of dirt in the instrument can cause overheating and component breakdown. Dirt on components acts as an insulating blanket and prevents efficient heat dissipation. It may also provide an electrical conduction path.

The covers of the indicator oscilloscope minimize the amount of dust which reaches the interior of the Type 7A16. Operation of the system without the indicator oscilloscope covers in place necessitates more frequent cleaning. When the Type 7A16 is not in use, it should be stored in a protected location such as a dust-tight cabinet.

# CAUTION

Avoid the use of chemical cleaning agents which might damage the plastics used in this instrument. Avoid chemicals which contain benzene, toluene, xylene, acetone or similar solvents.

**Exterior.** Loose dust accumulated on the outside of the Type 7A16 can be removed with a soft cloth or small paint brush. The paint brush is particularly useful for dislodging dirt on and around the front-panel controls. Dirt which remains can be removed with a soft cloth dampened in a mild detergent and water solution. Abrasive cleaners should not be used.

Interior. Dust in the interior of the instrument should be removed occasionally due to its electrical conductivity under high-humidity conditions. The best way to clean the interior is to blow off the accumulated dust with dry, low-velocity air. Remove any dirt which remains with a soft paint brush or a cloth dampened with a mild detergent and water solution. A cotton-tipped applicator is useful for cleaning in narrow spaces.

# Lubrication

**General.** The reliability of potentiometers and other moving parts can be maintained if they are kept properly lubricated. Potentiometer shaft bushings should be lubricated with a light-weight lubricant (e.g., Tektronix Part No. 006-0172-00). Do not over lubricate. A lubrication kit containing the necessary lubricants and instructions is available from Tektronix, Inc. Order Tektronix Part No. 003-0342-01.

# Visual Inspection

The Type 7A16 should be inspected occasionally for such defects as broken connections, broken or damaged circuit boards, improperly seated transistors or relays, and heat-damaged parts.

The corrective procedure for most visible defects is obvious; however, particular care must be taken if heat-damaged components are found. Overheating usually indicates other trouble in the instrument; therefore, it is important that the cause of overheating be corrected to prevent a recurrence of the damage.

#### **Transistor Checks**

Periodic checks of the transistors in the Type 7A16 are not recommended. The best check of transistor performance is actual operation in the instrument. More details on checking transistor operation is given under Troubleshooting.

#### Recalibration

To ensure accurate measurements, check the calibration of this instrument after each 1000 hours of operation or every six months if used infrequently. In addition, replacement of components may necessitate recalibration of the affected circuits. Complete calibration instructions are given in Section 5.

The Performance Check/Calibration Procedure can also be helpful in localizing certain troubles in the instrument. In some cases, minor troubles may be revealed and/or corrected by calibration.

# **TROUBLESHOOTING**

#### Introduction

The following information is provided to facilitate troubleshooting of the Type 7A16. Information contained in other sections of this manual should be used along with the following information to aid in locating the defective component.

# Maintenance—Type 7A16

An understanding of the circuit operation is very helpful in locating troubles. See the Circuit Description section for complete information.

# **Troubleshooting Aids**

**Diagrams.** Circuit diagrams are given on foldout pages in section 7. The component number and electrical value of each component in this instrument are shown on the diagrams.

**Switch Wafer Identification.** Switch wafers shown on the diagrams are coded to indicate the position of the wafer in the complete switch assembly. The numbered portion of the code refers to the wafer number counting from the front, or mounting end of the switch, toward the rear. The letters F and R indicates whether the front or rear of the wafer performs the particular switching function. For example, a wafer designated 2R indicates that the rear of the second wafer is used for this particular switching function.

Wiring Color-Code. All insulated wire and cable used in the Type 7A16 is color-coded to facilitate circuit tracing. Signal carrying leads are identified with one or two colored stripes on white insulation. Voltage supply leads have colored insulation indicating the polarity of the supply; red for positive supplies, violet for negative supplies. The stripe on a voltage lead indicates the number of the supply, using the

EIA color code, counting in sequence from ground all supplies in the oscilloscope system. The +15-volt supply lead is identified by a brown stripe on red insulation, indicating the second positive supply from ground. (The +5-volt supply is the first positive supply.) The -15-volt supply lead is identified by a black stripe on violet insulation.

**Resistor Color-Code.** Brown composition resistors and metal-film resistors are used in the Type 7A16. The resistance values of composition resistors and metal-film resistors are color coded on the components (some metal-film resistors may have the value printed on the body) with EIA color-code. The color code is read starting with stripe nearest the end of the resistor. Composition resistors have four stripes which consist of two significant figures, a multiplier and a tolerance value (see Fig. 4-1). Metal-film resistors have five stripes consiting of three significant figures, a multiplier and a tolerance value.

**Capacitor Marking.** The capacitance values of common disc capacitors and small electrolytics are marked in microfarads on the side of the component body. The white ceramic capacitors used in the Type 7A16 are color coded in picofarads using a modified EIA code (see Fig. 4-1).

**Diode Color Code.** The cathode end of each glassencased diode in indicated by a stripe, a series of stripes or a dot. For most silicon or germanium diodes with a series of stripes, the color code also indicates the type of diode

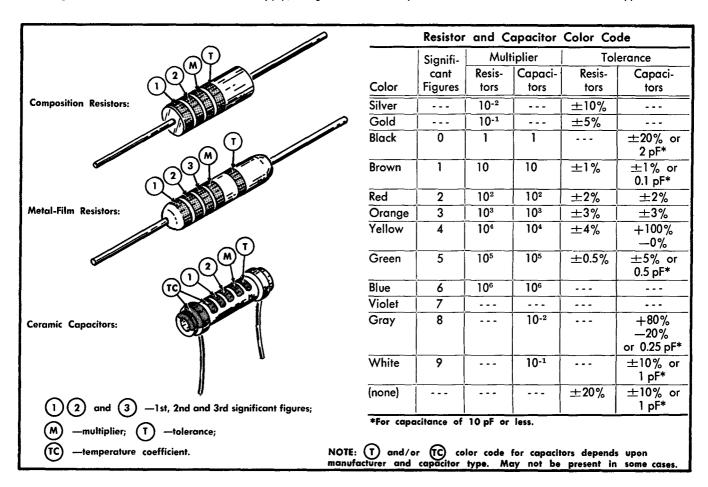


Fig. 4-1. Color-code for resistors and ceramic capacitors.

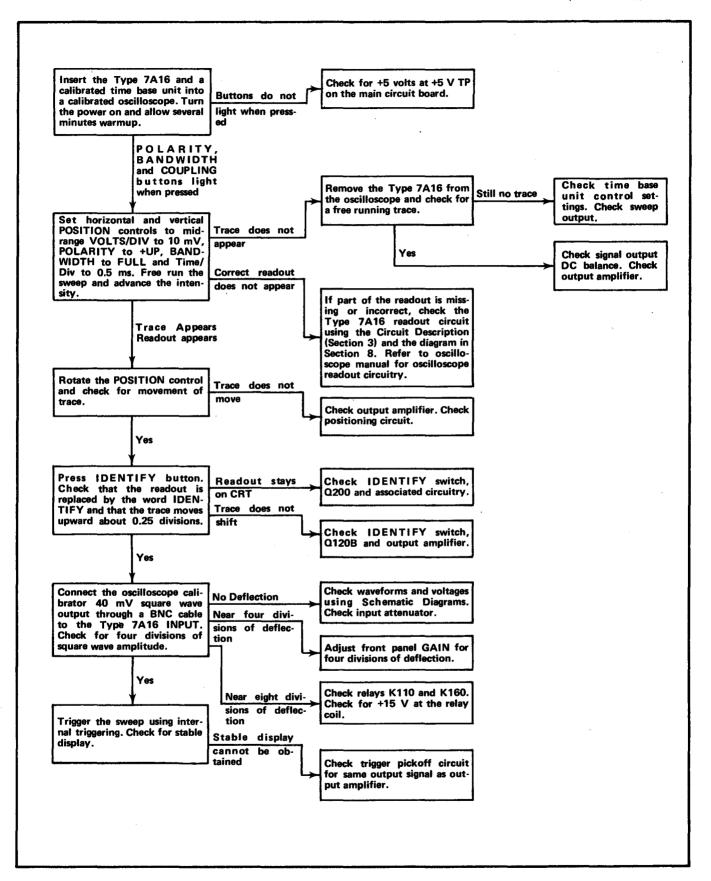


Fig. 4-2. Troubleshooting chart for Type 7A16.

# Maintenance—Type 7A16

or identifies the Tektronix Part Number using the resistor color-code system (e.g., a diode color coded blue- or pink-brown-gray-green indicates Tektronix Part Number 152-0185-00). The cathode and anode end of metal-encased diodes can be identified by the diode symbol marked on the body.

# **Troubleshooting Equipment**

The following equipment is useful for troubleshooting the Type 7A16.

#### 1. Transistor Tester

Description: Tektronix Type 576 Transistor-Curve Tracer or equivalent.

Purpose: To test the semiconductors used in this instrument.

#### 2. Volt-ohmmeter

Description: 20,000 ohm/volt. 0-500 volts DC. Accurate within 3%. Test probes must be well insulated.

Purpose: To measure voltages and resistances.

# 3. Test Oscilloscope

Description: DC to 50 MHz frequency response, 5 millivolts to 5 volts/division deflection factor. Use a 10× probe.

Purpose: To check waveforms in the instrument.

#### 4. Plug-In Extension

Description: Rigid plug-in extender, Tektronix Part Number 067-0589-00.

Purpose: Permits operation of the unit outside the plug-in compartment for better accessibility during troubleshooting.

# Troubleshooting Techniques

This troubleshooting procedure is arranged in an order which checks the simple trouble possibilities before proceeding with extensive troubleshooting. The first few checks ensure proper connection, operation and calibration. If the trouble is not located by these checks, the remaining steps aid in locating the defective component. When the defective component is located, it should be replaced following the replacement procedures given under Corrective Maintenance.

- 1. Check Control Settings. Incorrect control settings can indicate a trouble that does not exist. If there is any question about the correct function or operation of any control, see the Operating Instructions section.
- 2. Check Associated Equipment. Before proceeding with troubleshooting of the Type 7A16, check that the equipment used with this instrument is operating correctly. Check that the signal is properly connected and that the interconnecting cables are not defective. The indicator oscilloscope and time-base plug-in unit can be checked for proper operation by substituting another vertical unit which is known to be operating properly (preferably another Type 7A16 or similar unit). If the trouble persists after substitution, the indicator oscilloscope and/or time-base plug-in unit is defective.
- **3. Check Instrument Calibration.** Check the calibration of this instrument, or the affected circuit if the trouble exists in one circuit. The apparent trouble may only be a result of misadjustment or may be corrected by calibration. Com-

plete calibration instructions are given in the Calibration section.

- **4. Visual Check.** Visually check the portion of the instrument in which the trouble is located. Many troubles can be located by visual indications such as unsoldered connections, broken wires, damaged components, etc.
- **5. Isolate Trouble to a Circuit.** To isolate a trouble to a circuit, note the trouble symptom. The symptom often indicates the circuit in which the trouble is located. When trouble symptoms appear in more than one circuit, check all affected circuits by taking voltage and waveform readings. If the signal is correct, the circuit is working correctly up to that point.

Fig. 4-2 provides a guide to aid in locating a defective circuit. This chart does not include checks for all possible defects; use steps 6 and 7 for further troubleshooting. Start from the top of the chart and perform the given checks on the left side of the page until a step is found which is not correct. Further checks and/or the circuit in which the trouble is probably located are listed to the right of the step.

After the defective circuit has been located, proceed with steps 6 and 7 to locate the defective component(s).

**6.** Check Voltages and Waveforms. Often the defective component can be located by checking for the correct voltage or waveform in the circuit. Typical voltages and waveforms are given on the diagram.

#### NOTE

Voltages and waveforms given on the diagrams are not absolute and may vary slightly between instruments. To obtain operating conditions similar to those used to take these readings, see the first diagram page.

- **7. Check Individual Components.** The following procedure describes methods of checking individual components in the Type 7A16. Components which are soldered in place are best checked by first disconnecting one end. This isolates the measurement from the surrounding circuitry.
- A. RELAYS. There are three types of relays in the Type 7A16. They are the five-pin SPDT relay, Tektronix Part No. 148-0035-00, the eight-pin DPDT relay, Tektronix Part No. 148-0034-00, and the eight-pin DPAT relay, Tektronix Part No. 148-0063-00. These relays, which are plugged into the circuit board, may be removed and checked. Fig. 4-3 shows the internal configurations of the three relays. Using an ohmmeter, check for the indicated DC resistances. Each relay can be actuated by applying 15 volts to the coil, as shown in Fig. 4-3. With the relay actuated, check the normally open contacts for continuity. When checking the DPAT relay, the polarity of the 15 volt determines which side of the relay is actuated. When returning the relays to the circuit board, place the five-pin SPDT relays in the five-pin sockets. The eight-pin DPDT relays are symmetrical, hence may be placed in their sockets facing either direction. The eight-pin DPAT relay, which is not symmetrical, must be placed in the socket with the Tektronix Part Number facing toward the top of the instrument.
- B. TRANSISTORS. The best check of transistor operation is actual performance under operating conditions. If a transsistor is suspected of being defective, it can best be checked by substituting a new component or one which has been checked previously. However, be sure that circuit conditions are not such that a replacement transistor might also be

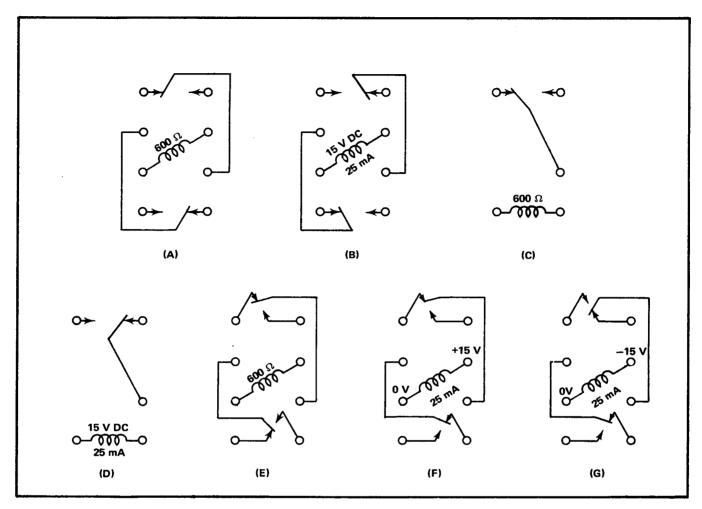


Fig. 4-3. Internal configuration of relays (pin views, with Tektronix Part Number on right), showing (A) DPDT relay not energized, (B) DPDT relay energized, (C) SPDT relay not energized, (D) SPDT relay energized, (E) dual SPDT relay not energized, (F) dual DPAT relay energized with +15 volts (AC button pressed), and (G) dual DPAT relay energized with -- 15 volts (DC button pressed).

damaged. If substitute transistors are not available, use a dynamic tester (such as Tektronix Type 576).

C. DIODES. A diode can be checked for an open or shorted condition by measuring the resistance between terminals. With an ohmmeter scale having an internal source of between 800 millivolts and 3 volts, the resistance should be very high in one direction and very low when the leads are reversed.

#### CAUTION

Do not use an ohmmeter scale that has a high internal current. High currents may damage the diode.

- D. RESISTORS. Resistors can be checked with an ohmmeter. Check the Electrical Parts List for the tolerance of the resistors used in this instrument. Resistors normally do not need to be replaced unless the measured value varies widely from the specified value.
- E. INDUCTORS. Check for open inductors by checking continuity with an ohmmeter. Shorted or partially shorted inductors can usually be found by checking the waveform response when high-frequency signals are passed through the

circuit. Partial shorting often reduces high-frequency response.

- F. CAPACITORS. A leaky or shorted capacitor can best be detected by checking the resistance with an ohmmeter on the highest scale. Do not exceed the voltage rating of the capacitor. The resistance reading should be high after initial charge of the capacitor. An open capacitor can best be detected with a capacitance meter or by checking whether the capacitor passes AC signals.
- 8. Repair and Readjust the Circuit. If any defective parts are located, follow the replacement procedures given in this section. Be sure to check the performance of any circuit that has been repaired or that has had any electrical components replaced.

# **CORRECTIVE MAINTENANCE**

# General

Corrective maintenance consists of component replacement and instrument repair. Special techniques required to replace components in this instrument are given here.

# **Obtaining Replacement Parts**

**Standard Parts.** All electrical and mechanical part replacements for the Type 7A16 can be obtained through your local Tektronix Field Office or representative. However, many of the standard electronic components can be obtained locally in less time than is required to order them from Tektronix, Inc. Before purchasing or ordering replacement parts, check the parts list for value, tolerance, rating and description

#### NOTE

When selecting replacement parts, it is important to remember that the physical size and shape of a component may affect its performance in the instrument, particularly at high frequencies. All replacement parts should be direct replacements unless it is known that a different component will not adversely affect instrument performance.

**Special Parts.** In addition to the standard electronic components, some special parts are used in the Type 7A16. These parts are manufactured or selected by Tektronix, Inc., to meet specific performance requirements, or are manufactured for Tektronix, Inc., in accordance with our specifications. These special parts are indicated in the electrical parts list by an asterisk preceding the part number. Most of the mechanical parts used in this instrument have been manufactured by Tektronix, Inc. Order all special parts directly from your local Tektronix Field Office or representative.

**Ordering Parts.** When ordering replacement parts from Tektronix, Inc., include the following information:

- 1. Instrument Type.
- 2. Instrument Serial Number.
- 3. A description of the part (if electrical, include circuit number).
  - 4. Tektronix Part Number.

# Soldering Techniques

#### WARNING

Disconnect the instrument from the power source before soldering.

**Circuit Boards.** The components mounted on the circuit boards in the amplifier can be replaced using normal circuit board soldering techniques. Keep the following points in mind when soldering on the circuit boards:

- 1. Use a pencil-type soldering iron with a power rating from 15 to 50 watts.
- 2. Apply heat from the soldering iron to the junction between the component and the circuit board.
- 3. Heat-shunt the lead of the component by means of a pair of long-nosed pliers.
- 4. Avoid excessive heating of the junction with the circuit board, as this could separate the circuit board wiring from the laminate.

- 5. Use electronic grade 60-40 tin-lead solder.
- 6. Clip off any excess lead length extending beyond the circuit board and clean off any residual flux with a flux-removing solvent. Be careful that the solvent does not remove any printing from the circuit board.

**Metal Terminals.** When soldering metal terminals (e.g., switch terminals, potentiometers, etc), use 60-40 tin lead solder and a 15 to 50 watt soldering iron. Observe the following precautions when soldering metal terminals:

- 1. Apply only enough heat to make the solder flow freely.
- 2. Apply only enough solder to form a solid connection. Excess solder may impair the function of the part.
- 3. If a wire extends beyond the solder joint, clip off the excess.
- 4. Clean the flux from the solder joint with a flux-removing solvent.

# **Component Replacement**

#### WARNING

Disconnect the test equipment from the power source before replacing components.

Relay Replacement. The relays in the Type 7A16 are manufactured by Tektronix, Inc. If a relay fails, a replacement may be ordered from your local Tektronix Field Office or representative. The five-pin relay sockets on the circuit board will accept only the five-pin SPDT relay. It is possible, however, to place a five-pin SPDT relay in an eight-pin socket intended for use with one of the eight-pin relays. This would not damage the instrument or the relay, but would cause a malfunction of the instrument. The eight-pin DPDT relays may be placed in their sockets facing either direction, as these relays are symmetrical. The eight-pin DPAT relay is not symmetrical and must be placed in the socket with the Tektronix Part Number facing toward the top of the instrument.

**Transistor Replacement.** Transistors should not be replaced unless actually defective. If removed from their sockets during routine maintenance, return them to their original sockets. Unnecessary replacement of transistors may affect the calibration of this instrument. When transistors are replaced, check the operation of that part of the instrument which may be affected.

Replacement transistors should be of the original type or a direct replacement. Remount the transistors in the same manner as the original. Fig. 4-4 shows the lead configurations of the transistors used in this instrument. This view is as seen from the bottom of the transistor. When replacing transistors, check the manufacturer's basing diagram for correct basing.

**Light-Bulb Replacement.** The POLARITY, BANDWIDTH, and Input Coupling switches each contain one incandescent light bulb common to the two or three push-buttons of the switch. This light bulb may be replaced without removal of the switch as follows:

1. Remove the screw and cover from the back of the switch, exposing the light bulb.

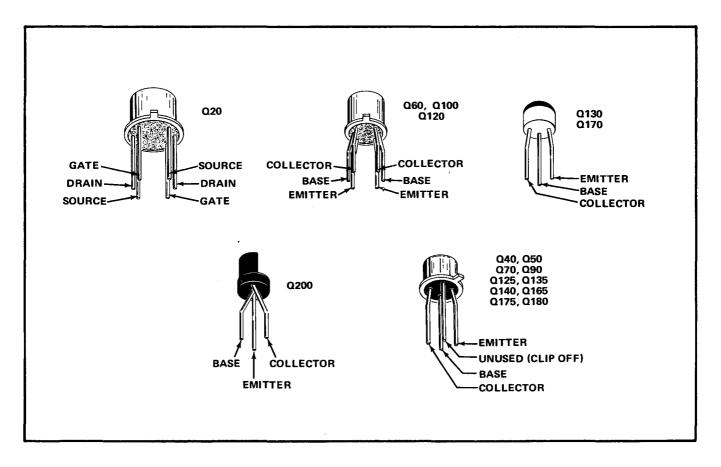


Fig. 4-4. Electrode configuration for transistors in this instrument.

- 2. While holding one lead of the bulb with a pair of longnosed pliers, touch a 15-watt pencil-type soldering iron to the connection on the other side of the circuit board. Remove the lead from the circuit board. Unsolder the remaining lead and remove the bulb.
- 3. Cut the leads of the replacement bulb to the same length as those of the old bulb.
- 4. Grasp one lead of the replacement bulb with the longnosed plier and position in one of the appropriate holes in the circuit board. Touch the soldering iron to the connection on the other side of the circuit board and push the lead into place. Repeat with the remaining lead.
- 5. Position the bulb so that it does not fall in line with the bottom pushbutton. Replace the cover.

**POLARITY BANDWIDTH, or Input Coupling Switch Replacement.** Should one of the pushbutton switches fail, the front panel must be removed to gain access to the switch mounting screws. Proceed as follows:

- 1. Remove the four control knobs from their shafts. The IDENTIFY button pulls off; use a  $^{1}/_{16}$ -inch hex-head wrench to remove the POSITION, VOLTS/DIV, and VAR control knobs.
- 2. Remove the front panel to gain access to the switch mounting screws.
  - 3. Remove the screw holding the faulty switch assembly.

- 4. Remove the connections on the circuit board.
- 5. Install the replacement switch by reversing the above procedure.

**VOLTS/DIV** Switch Strip Replacement. The VOLTS/DIV switch contains ten strips which are individually adjusted for optimum input response in each position of the switch. These strips should not be removed unless they are known to be defective, in which case replacements can be obtained from your local Tektronix Field Office or representative. To replace a defective strip, proceed as follows:

- 1. Remove the attenuator cover.
- 2. Rotate the VOLTS/DIV control to position the defective strip to the right side of the instrument.
- 3. Move the strip about one-quarter inch toward the rear of the switch. Lift the strip out of the switch assembly.
- 4. Replace the defective strip with the new part. (Refer to the Electrical Parts List for replacement information.)

#### CAUTION

When replacing a VOLTS/DIV switch strip, carefully align the guides on the edges of the strip with the grooves in the switch assembly, then slide the strip into place.

# Maintenance—Type 7A16

5. Adjust the new strip(s) for optimum response as described in Section 5.

**Main Circuit Board Replacement.** If the main amplifier circuit board requires replacement, a complete wired board is available from Tektronix, Inc. To replace the circuit board, proceed as follows:

- 1. The GAIN potentiometer is driven from the front panel by a control shaft. Using a .05-inch hex-head wrench, loosen the two set screws on the front portion of the coupling and remove the shaft.
- 2. Disconnect the VARIABLE control shaft from the push switch and potentiometer.
- 3. Remove the two screws which secure the circuit board to the VOLTS/DIV switch housing.
- 4. Unsolder R14-C14 (connected from the VOLTS/DIV switch to the tie point at the front of the circuit board) from the VOLTS/DIV switch.
- 5. Remove all the pin connections on the left side of the main circuit board.
- 6. Unsolder the four leads from the VARIABLE switch (cal/uncal switch) circuit board.
- 7. Remove the four screws which secure the rear casting to the top and bottom frames.
- 8. Remove the screws on the six mounting clamps along the top and bottom edges of the circuit board.
  - 9. Remove the circuit board assembly from the instrument.
- 10. Lift the top and bottom tabs which hold the rear casting to the circuit board and remove.
- 11. Unsolder the VARIABLE and GAIN potentiometer connections and remove the mounting brackets from the circuit board.
- 12. Install the replacement circuit board by reversing the above procedure. The wiring color-codes for the pin connections are shown in Fig. 4-5.

#### Recalibration After Repair

After any electrical component has been replaced, the calibration of that particular circuit should be checked, as well as the calibration of other closely related circuits. The Performance Check procedure in Section 5 provides a quick and convenient means of checking instrument operation.

**Circuit Board Square Pin Replacement.** If the circuit board pins are damaged or broken a field replacement kit (Tektronix Part Number 040-0542-00), containing the necessary parts and a replacement instruction sheet, can be obtained from Tektronix, Inc. To replace a pin proceed as follows:

- 1. Remove the broken pin by applying heat to the pin while maintaining a steady pull on the pin. Do not use excessive heat as this may separate the pin ferrule from the circuit board laminate.
  - 2. Remove and discard the ferrule from the new pin.
- 3. Position the new pin in place and carefully solder the pin to both sides of the circuit board. Do not use excessive heat.
- 4. For those pins that have been formed, use pliers to bend to appropriate configuration after installation.

**End Lead Pin Connector Replacement.** The pin connectors used to connect the wires to the circuit board pins are clamped to the ends of the associated leads. To replace the pin connectors proceed as follows:

- 1. Clip off the damaged pin connector and dress the lead for the new connector.
  - 2. Clamp the new pin connector to the lead.

Some of the pin connectors are grouped together and mounted in a plastic holder. To remove the pin connector from the plastic holder, lift up on the back end and pull out. To provide correct orientation of this multi connector when it is replaced, an arrow is stamped on the circuit board and a matching arrow is molded into the plastic housing of the multi pin connector.

# Instrument Repackaging

If the Type 7A16 is to be shipped for long distances by commercial means of transportation, it is recommended that the instrument be repackaged in the original manner for maximum protection. The original shipping carton can be saved and used for this purpose. Repackaging information and/or new shipping cartons can be obtained from Tektronix, Inc. Contact your local Tektronix Field Office or representative.

#### NOTE

The plug-ins should not be shipped installed in an oscilloscope. The oscilloscope packaging material is not designed to protect the plug-ins.

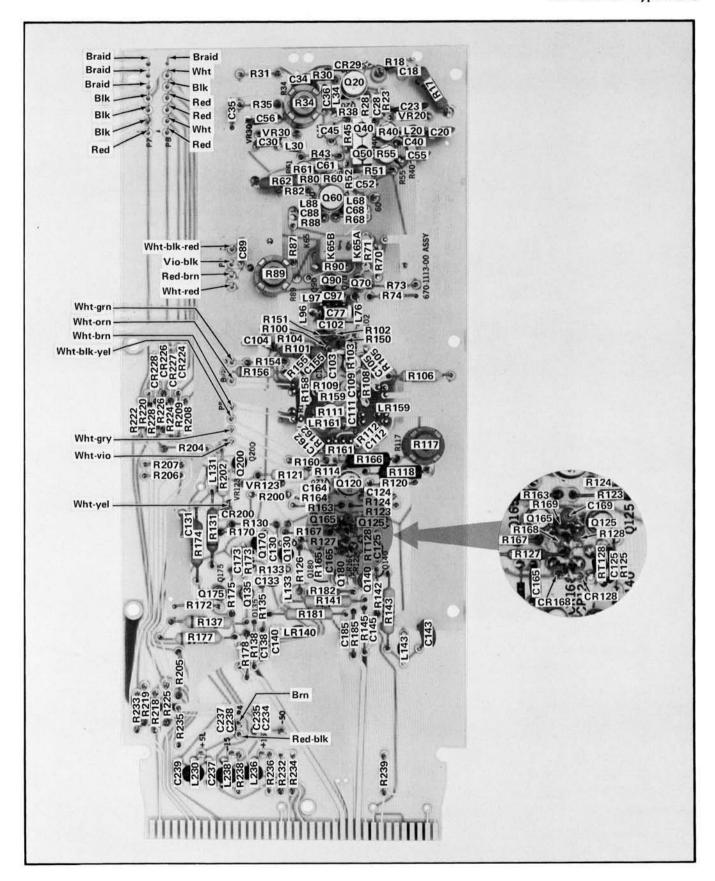


Fig. 4-5. Main amplifier circuit board (front).

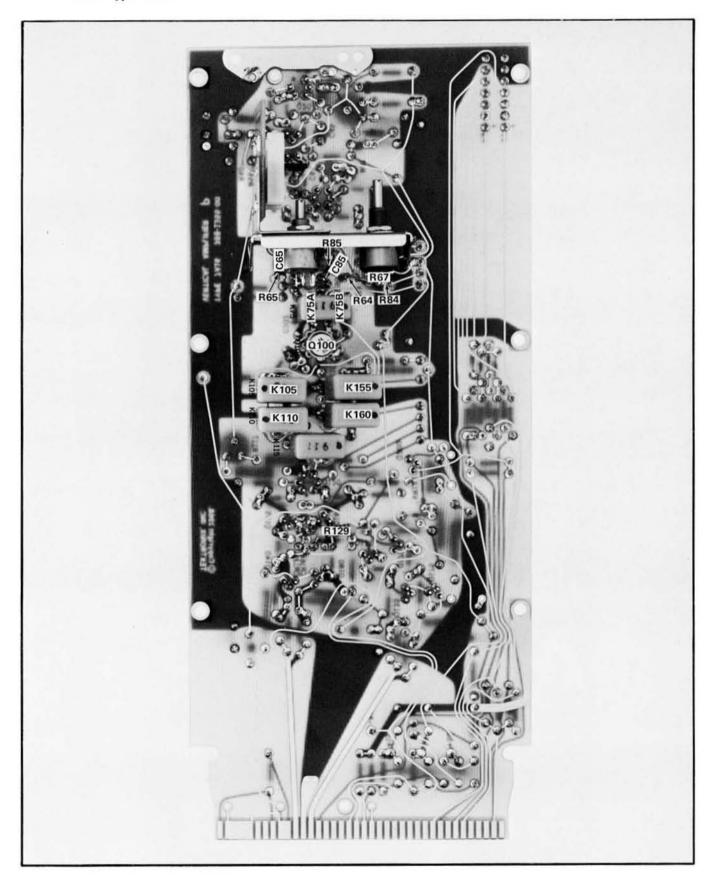


Fig. 4-6. Main amplifier circuit board (rear).

# SECTION 5 PERFORMANCE CHECK/CALIBRATION

Change information, if any, affecting this section will be found at the rear of the manual.

# INTRODUCTION

To assure instrument accuracy, check the calibration of the 7A16 every 1000 hours of operation, or every six months if used infrequently. Before complete calibration, thoroughly clean and inspect this instrument as outlined in the Maintenance section.

As an aid to the calibration of the instrument, a Short-Form Procedure is given prior to the complete procedure. To facilitate instrument calibration for the experienced calibrator, the Short-Form Procedure lists the calibration adjustments necessary for each step and the applicable tolerances. This procedure also includes the step number and title as listed in the complete Performance Check/Calibration Procedure and the page number on which each step begins. Therefore, the Short-Form Procedure can be used as an index to locate a step in the complete procedure. Another feature of the Short-Form Procedure is the spaces provided to record performance data or to check off steps as they are completed. This procedure can be reproduced and used as a permanent record of instrument calibration.

The complete Performance Check/Calibration Procedure can be used to check instrument performance without removing the covers or making internal adjustments by performing all portions except the ADJUST part of a step. Screwdriver adjustments accessible without removing the covers are adjusted as part of the performance check procedure. A note titled PERFORMANCE CHECK ONLY gives instuctions which are applicable only to the performance check procedure and if necessary, lists the next applicable step for the performance check procedure.

Completion of each step in the complete Performance Check/Calibration Procedure insures that this instrument meets the electrical specifications given in Section 1. Where possible, instrument performance is checked before an adjustment is made. For best overall instrument performance when performing a complete calibration procedure, make each adjustment to the exact setting even if the CHECK is within the allowable tolerance.

# NOTE

Limits, tolerances and waveforms in this procedure are given as calibration guides and should not be interpreted as instrument specifications except as specified in Section 1. All waveforms shown in this procedure were taken with a Tektronix Oscilloscope Camera System.

A partial calibration is often desirable after replacing components, or to touch up the adjustment of a portion of the instrument between major recalibrations. To check or adjust only part of the instrument, set the controls as given under Preliminary Control Settings and start with the nearest test equipment picture preceding the desired portion. If any controls need to be changed from the preliminary settings for this portion of the calibration procedure, they are listed under the heading Partial Procedure following the equipment required picture. To prevent unnecessary recalibration of other parts of the instrument, readjust only if the tolerance given in the CHECK part of the step is not met. If readjustment is necessary, also check the calibration of any steps listed in the INTERACTION part of the step.

#### TEST EQUIPMENT REQUIRED

#### General

The following test equipment and accessories, or its equivalent, are required for complete calibration of the Type 7A16. Specifications given are the minimum necessary for accurate calibration. Some of the recommended equipment may have specifications which exceed those given. All test equipment is assumed to be correctly calibrated and operating within the given specifications. If equipment is substituted, it must meet or exceed the specifications of the recommended equipment.

# Test Equipment

- 1. 7000 series Indicator Oscilloscope. Type 7704 used in these checks.
  - 2. 7B—series Time-Base. Type 7B71 used in these checks.
- 3. Test Oscilloscope. Storage and Sampling capabilities; bandwidth, at least 1000 megahertz; minimum deflection factor, 50 millivolts/div. Tektronix Type 564B with 3S1/3T2 plug-in units recommended.
- 4. Pulse Generator. Risetime, 0.25 nanosecond; amplitude, 0 to 50 volts into 50 ohms. Tektronix Type 109 recommended.
- 5. Delay Line. Characteristic impedance, 50 ohms; 60 nanoseconds delay. Tektronix Type 113 Delay Cable recommended.

# Performance Check/Calibration—Type 7A16

- 6. Constant Amplitude Sine-Wave Generator. Reference frequency, 50 kHz; frequency range, below 15 megahertz to above 60 megahertz; output amplitude, variable from 0.5 to 5 volts peak to peak; amplitude accuracy, within 3% of 50 kHz reference as output frequency changes. Tektronix Type 191 Constant Amplitude Signal Generator recommended.
- 7. Type 106 Square Wave Generator. Risetime, 1 nanosecond into 50 ohms; amplitude, 50 mV to 500 mV; frequency, 1 kHz.
- 8. Constant Amplitude Signal Generator. Repetition rate, about 1 kHz; voltage range, 25 millivolts to 25 volts; accuracy,  $\pm 0.25\%$ . Tektronix Standard Amplitude Calibrator 067-0502-00 recommended.
- 9. DC Voltmeter. 20,000 ohms/volt minimum sensitivity; range, 0 to 50 volts; accuracy, checked to within 1% at the voltages to be measured. For example, Triplett Model 630-NA.
- 10. Calibration Fixture, Constant Amplitude Signal Generator. Reference frequency, 3 megahertz; frequency range, 65 megahertz to above 175 megahertz; output amplitude, 0.5 to 5 volts peak to peak into 50 ohms; amplitude accuracy, output amplitude constant within 1% of 3 megahertz reference as output frequency changes. Tektronix Part Number 067-0532-00.
- 11. Calibration Fixture, Plug-In Extender. Tektronix Part Number 067-0589-00.
- 12. Pulse Generator. Risetime, 70 picoseconds; amplitude, 200 mV into 50 ohms; pulse width, 1 microsecond. Tektronix Type 284 recommended.

#### Accessories

- 13. Cable (two). Impedance, 50 ohms; electrical length, 2 nanoseconds; connectors, GR. Tektronix Part Number 017-0505-00.
- 14. Adapter (two). GR to BNC female. Tektronix Part Number 017-0063-00.
- 15. Adapter. GR to BNC male. Tektronix Part Number 017-0064-00.
- 16. Adapter (two). GR elbow. Tektronix Part Number 017-0070-00.
- 17. Termination. Impedance, 50 ohms; endline; connector, GR. Tektronix Part Number 017-0081-00.
- 18. 50 ohm Feedthrough Termination. Tektronix Part Number 011-0049-01 (2 each).
- 19.  $10 \times$  Attenuator, BNC connectors. Tektronix Part Number 011-0059-01, (2 each).
- 20. 15 pF RC Normalizer, BNC connectors. Tektronix Part Number 067-0537-00.
- 21. Coaxial Cable; electrical length, 5 nanoseconds; GR connectors. Tektronix Part Number 017-0512-00.

- 22. CT-3 Signal Pickoff. Tektronix Part Number 017-0061-00.
- 23. Coaxial Cable. Impedance, 50 ohms; length, 42 inches; connectors, BNC. Tektronix Part Number 012-0057-01.

# SHORT FORM PROCEDURE

. 741/

Type 7A16	
Calibration Date	· · · · · · · · · · · · · · · · · · ·
Calibrated By	<del></del>
ground.	Page 5-4 or zero volts from TP60 to; Incorrect
<ul> <li>2. Check/Adjust Variable B</li> <li>Requirement: 0.5 div or ABLE is rotated.</li> </ul>	
3. Check Step Attenuator R     Requirement: At least 10     Performance: Correct	
4. Check/Adjust Step Atten (R153)	uator Balance Page 5-4
VOLTS/DIV is changed 1	of 0.5 division or less as from one setting to the next; Incorrect
5. Adjust Position Centering	(R117) Page 5-5
output lines (A11 and B tioned to graticule cent	ial difference between the ill) when the trace is posier; Incorrect
6. Check Position Range	Page 5-5
	ions from graticule center; Incorrect
7. Check +UP to Invert Sh	ift Page 5-5
switching from +UP to	on or less trace shift when INVERT; Incorrect
8. Check/Adjust Front Pane	l Gain (R66) Page 5-5
a 50 mV signal applied, to five divisions.	VOLTS/DIV at 10 mV and the display can be adjusted; Incorrect
9. Check Variable Control	Range Page 5-6
Requirement: Continuous brated VOLTS/DIV setti Performance: Correct	

[] 10.	. Check Trigger DC Level	Page 5-6		neck Trigger Step Response	Page 5-10
	Requirement: Within one division of signal Performance: Correct; Incorrect		ar	equirement: Risetime not to exceed 2.1 ad aberrations not to exceed 15% P-P or formance: Correct; Incorrect	•
<u> </u>	. Check Trigger Gain	Page 5-6	□ 21 CF	neck 20 Megahertz Bandwidth Limiting	Page 5-11
	Requirement: Within 10% of signal gain. Performance: Correct; Incorrect		Re	equirement: —3 dB at 20 megahertz wiertz.	J
12.	Check Volts/Div Deflection Accuracy	Page 5-6	Pe	rformance: Correct; Incorrec	:t
	Requirement: Vertical deflection factor v		☐ 22. Ch	neck Overall Noise Level Tangentially	Page 5-11
	of VOLTS/DIV switch indication with gair at 10 mV/Div.  Performance: Correct; Incorrect .	•		quirement: 0.1 division or less at 5 n rformance: Correct; Incorrec	
<u> </u>	Adjust Input Compensation (C18)	Page 5-7	PER	FORMANCE CHECK/CALIBRA PROCEDURE	TION
	Requirement: Optimum square wave res Performance: Correct; Incorrect		C		
	, mestroci	······································	General		T 741/
☐ 14.	. Adjust Volts/Div Compensation (C6A, C6B, C7A, C7B, C8A, C8B, C9A, C9B, C1 C11A, C11B, C12A, C12B)		can be co	owing procedure is arranged so the alibrated with the least interaction of nection of equipment. A picture of th pired for each group of steps is give	adjustments e test equip-
	Requirement: Optimum square corner and Performance: Correct; Incorrect	flat top.	identificati tings and continue f	on of the necessary equipment. The test equipment setup throughout thi rom the preceding step(s) unless note	control set- is procedure d otherwise.
☐ 15.	Adjust High Frequency Compensation, 5 mV (R40, R55, C61, C102, C52, C45, C R61)		required" start of th	ol settings can be checked at any "test picture by setting the controls as go ne procedure under the heading Preli gs. Then make any changes listed fo	given at the minary Con-
	Requirement: Best square corner and level rations not to exceed 6% P-P.			ment required picture, under the hed (also applies to partial calibration	
	Performance: Correct; Incorrect _	•	The foll	owing procedure uses the equipment oment Required. If other equipment is	listed under
□ 16.	Adjust High Frequency Compensation, 10 mV (R111, C111)	Page 5-8	control set to meet t	ttings or calibration setup may need to the requirements of the equipment use	o be altered ed. Detailed
	Requirement: Best square corner and level rations not to exceed 6% P-P.		this proce	instructions for the test equipment are dure. Refer to the instruction manual if more information is required.	
	Performance: Correct; Incorrect _	•		NOTE	
☐ 1 <i>7</i> .	Adjust High Frequency Compensation, 20 mV (R109, C109)	Page 5-8		strument should be calibrated at an	
	Requirement: Best square corner and level rations not to exceed 6% P-P. Performance: Correct; Incorrect;		accura be che	ature of +20°C to +30°C for bes cy. The performance of this instrur cked at any temperature within the C range. If the temperature is ou	ment can e 0°C to
	renormance. Correct, mcorrect _	<del></del> •	given ı	ange, see Section 1 for the applic	
□ 18	Check Step Response	Page 5-9	erance	s.	
	Requirement: Risetime not to exceed 1.4 na and aberrations not to exceed 6% P-P at to .5 V/div or 8% P-P at 1 V/div to 5 V/div programments.	5 mV/div iv.	Prelimin Calibrat	ary Procedure for Complete ion	
	Performance: Correct; Incorrect _	•	1. Conn	ect the Type 7A16 to the plug-in exte	nder.
<u> </u>	Check Upper Bandwidth —3 dB Point	Page 5-9		the plug-in extender in the oscillo	oscope right
	Requirement: Not more than —3 dB at 2 hertz.	_	3. Insert	ompartment.  the time base in the oscilloscope (	eft (A) hori-
	Performance: Correct; Incorrect _	<del></del>	zontal cor	nparment.	

# Performance Check/Calibration-Type 7A16

- 4. Connect the oscilloscope to a suitable power source.
- 5. Set the controls as given under Preliminary Control Settings.
- Turn the oscilloscope power switch to on and allow 20 minutes warmup before proceeding with calibration of the instrument.

# **Preliminary Control Settings**

# Type 7A16

POSITION	Midrange
POLARITY	+UP
BANDWIDTH	FULL
COUPLING	GND
VOLTS/DIV	5 mV
VARIABLE	CAL IN

# Type 7B71

Level/Slope	0/+
Triggering	
Mode	P-P Auto
Coupling	AC
Source	Int
Magnifier	×1
Time/Div	0.5 ms
Variable	Cal In
B Delay Mode	Independen

#### Type 7704

Calibrator	
Rate	1 kHz
Volts	40 mV
Vertical Mode	Right
Horizontal Mode	A
A Trigger Source	Right Vertica

# Type 564B

Intensity	Optimum	
Upper Screen	Store	
Lower Screen	Store	

# Type 3T2

Time Position	
(Fine and Coarse)	Fully cw
Horiz Position	Midrange

Range	100 ns
Start Point	With Trigger
Time Magnifier	×1
Display Mode	Normal
Polarity	+
Source	Int

# Type 3S1

Position (A and B)	Midrange
Dual Trace	A + B
mVOLTS/Div (both)	50
CH 1 Invert/Norm	Norm
CH 2 Invert/Norm	Invert
Internal Trigger	Α

# 1. Adjust DC Balance (R34)

- a. Set the controls as given under Preliminary Control Settings.
  - b. Connect the voltmeter between TP 60 and ground.
  - c. ADJUST-R34 for zero volts from TP 60 to ground.

# 2. Check/Adjust Variable Balance (R89)

- a. Press and release the VARIABLE control to its outward position.
- b. CHECK—For 0.5 div or less of trace shift as the VARI-ABLE control is rotated throughout its range.
- ADJUST—R89 for minimum movement of trace as VARI-ABLE control is rotated.

# 3. Check Step Attenuator Range

- a. Turn STEP ATTEN BAL adjustment fully clockwise and position the trace to graticule center with the POSITION control.
- b. Connect a 50 mV square wave from the standard amplitude calibrator to the Type 7A16 INPUT.
- c. CHECK—Set the COUPLING switch to DC and turn the STEP ATTEN BAL adjustment fully counterclockwise. Check that the top of the square wave is at or below graticule center.
  - d. Set the STEP ATTEN BAL adjustment to midrange.

# Check/Adjust STEP ATTENUATOR BAL (R153)

a. Set the COUPLING switch to GND and center the trace on the CRT with the POSITION control.

Intensity

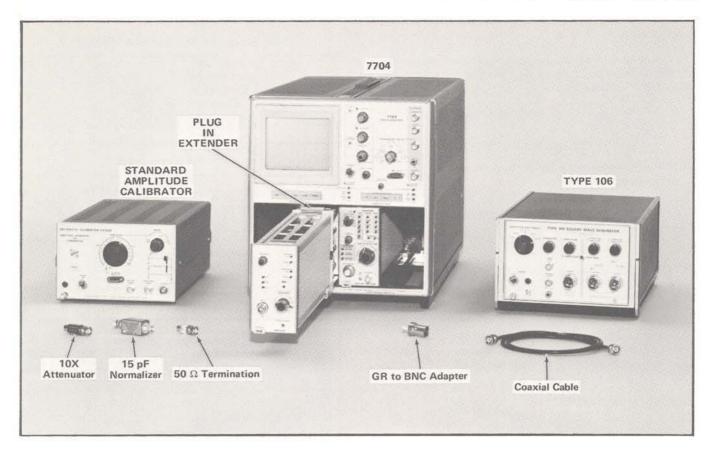


Fig. 5-1. Test equipment required for steps 8 through 12.

#### PERFORMANCE CHECK

This adjustment may be performed as part of the Performance Check.

- b. ADJUST—STEP ATTEN BAL (a front-panel adjustment) for minimum trace shift as the VOLTS/DIV is changed from  $5\,\text{mV}$  to  $20\,\text{mV}$ .
- c. CHECK—The remaining positions of the VOLTS/DIV switch for no trace shift between steps.

# 5. Adjust Position Centering (R117)

- a. Center the trace on the CRT with the POSITION control.
- b. Connect the voltmeter between All and Bl1 (the rearward end of R185 and R145).
- c. ADJUST—R117 for a null (zero) reading on the voltmeter.

# 6. Check Position Range

a. Set the input COUPLING to AC, VOLTS/DIV to 20 mV and center the trace with the POSITION control.

- b. Set the oscilloscope calibrator to 40 mV and connect a BNC cable from the calibrator output to the Type 7A16 INPUT
- c. Center the display on the CRT with the POSITION control.
- d. Reset the oscilloscope calibrator to 0.4 V and turn the POSITION control fully clockwise.
- e. CHECK—The bottom of the waveform must position to graticule center or above. Turn the POSITION control fully counterclockwise and check that the top of the wave form can be positioned to graticule center or below.
  - f. Disconnect the signal from the Type 7A16 INPUT.

# 7. Check + UP to INVERT shift

- a. Set the VOLTS/DIV to 5 mV.
- b. CHECK—Press the INVERT button and check for 1 division or less of trace movement.

# 8. Check/Adjust Front Panel GAIN (R66)

a. Test Equipment is shown in Fig. 5-1.

# Performance Check/Calibration-Type 7A16

- b. Set the VOLTS/DIV to 10 mV, POLARITY to + UP and COUPLING to DC.
- c. Connect a 50 mV square wave signal from the standard amplitude calibrator through a coaxial cable to the Type 7A16 INPUT connector.
  - d. CHECK-The vertical amplitude for exactly 5 divisions.

#### PERFORMANCE CHECK

This adjustment may be performed as part of the performance check.

e. ADJUST—GAIN (a front panel adjustment) for exactly 5 divisions of vertical amplitude.

# 9. Check VARIABLE Control Range

- a. With the standard amplitude calibrator connected as above, press and release the VARIABLE control to its outward position.
- b. CHECK—Rotate the VARIABLE control fully counterclockwise and check for 2 divisions or less off vertical amplitude (2.5:1 ratio requirement).
  - c. Return the VARIABLE control to the CAL IN position.

# 10. Check Trigger DC Level

- a. Set the Type 7A16 COUPLING switch to GND and position the trace to graticule center with the POSITION control.
- Connect the extender trigger cables to the signal jacks and terminate the signal cables into 50 ohms.
- CHECK—The trace must be within one division of graticule center.

# 11. Check Trigger Gain

- a. Reset the COUPLING switch to AC and VOLTS/DIV to  $10\ \mathrm{mV}$ .
- b. Connect a 50 mV square wave from the standard amplitude calibrator to the Type 7A16 INPUT.
- c. CHECK—For a display amplitude of five divisions  $\pm 0.5$  division.
- Return the extender trigger and signal cables to their correct jacks.

# 12. Check VOLTS/DIV Deflection accuracy

- a. CHECK—Using Table 5-1 as a guide, check the vertical deflection factor from 5 volts to 5 millivolts.
  - b. Disconnect the standard amplitude calibrator.

TABLE 5-1
Deflection Factor Accuracy Check

VOLTS/DIV Switch Setting	Standard Amplitude Calibrator Output Amplitude	Divisions of Deflection	Accuracy
5 V	20 V	4	土2%
2 V	10 V	5	±2%
1 V	5 V	5	±2%
.5 V .2 V	2 V	4	土2%
	1.V	5	±2%
.1 V	.5 V	5	土2%
50 mV	.2 V	4	土2%
20 mV	.1 V	5	土2%
10 mV	50 mV	5	土2%
5 mV	5 mV 20 mV		±2%

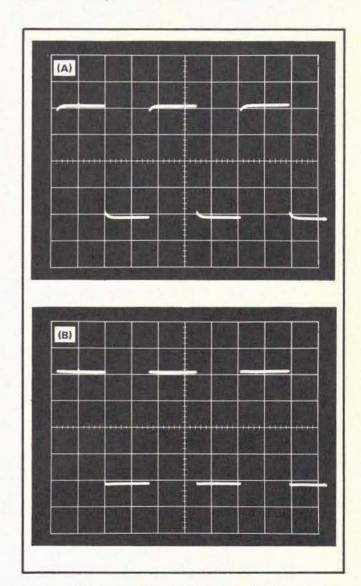


Fig. 5-2. (A) Compensation incorrectly set. (B) Input properly compensated.

# 13. Adjust Input Compensation (C18)

- a. Reset the Type 7A16 VOLTS/DIV to 5 mV and the time-base Time/Div to .1 ms.
- b. Connect a 3 kHz square wave from the Type 106 high-amplitude output through a GR to BNC adapter, coaxial cable,  $10\times$  attenuator, 50 ohm feedthrough termination and 15 pF input RC normalizer to the Type 7A16 INPUT connector. Adjust the Type 106 amplitude for about four divisions of display.
- c. ADJUST—C18 for best square leading corner (no over-shoot or rolloff, see Fig. 5-2A and B).
- d. Switch the COUPLING to AC and check that the display shifts up about two divisions. Return the COUPLING switch to DC.

# Adjust Volts/Division Series and Shunt Compensation

a. Using Table 5-2 as a guide, check the CRT display at each VOLT/DIV setting and adjust for best square leading corner and flat top on the display. Adjust the Type 106 amplitude as necessary to maintain a four division display for each VOLTS/DIV setting.

TABLE 5-2
Series and Shunt Compensations

VOLTS/DIV Switch Setting	Adjust For Best Flat Top	Adjust For Best Square Corner
50 mV	C6A	C6B
.1 V	C7A	C7B
.2 V	C8A	C8B
.5 V	C9A	C9B
1 /	C10A	C10B
2 V	CIIA	C11B
5 V	C12A	C12B

b. Disconnect the Type 106 square wave generator.

# Partial Procedure

If beginning a partial procedure with this step, set the controls as given under Preliminary Control Settings, except set the Type 7A16 Input Coupling to DC.

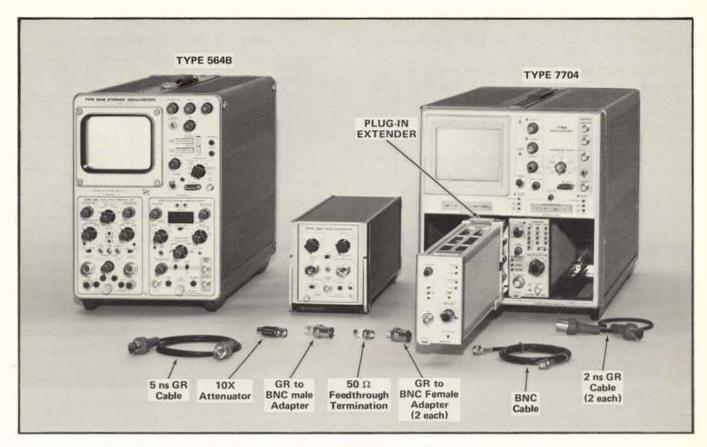


Fig. 5-3. Test equipment required for steps 15, 16 and 17.

# Adjust High Frequency Compensation (5 mV)

- a. Test equipment required is shown in Fig. 5-3.
- b. Set the Type 7A16 VOLTS/DIV to 5 mV.
- c. Connect the plug-in extender left signal cable (A11) through a 2 nanosecond cable to the Type 3S1 channel A input; connect the right signal cable (B11) through a 2 nanosecond cable to the Type 3S1 channel B input; connect the Type 284 pulse output through a 5 nanosecond cable, GR to BNC adapter, 10× attenuator and 50 ohm feedthrough termination to the Type 7A16 INPUT; connect the Type 284 trigger output through a BNC cable to the Type 3T2 50 ohm trigger input.
- d. ADJUST—According to the information given below for best overall response (compromise between best risetime and least aberrations):

Adjustment	Adjust For		
R40 - R55	Least Ringing		
C61 - C102	Best Front Corner		
C52	Best Level		
C45	Best Front Corner		
C103 - R103	Best Level		
R61	Best Level		

INTERACTION: Perform steps 16 and 17.

# Adjust High Frequency Compensation (10 mV)

- a. Equipment setup as in step 15 except Type 7A16 VOLTS/DIV to 10 mV.
- b. ADJUST—R111 for minimum ringing and C111 for best front corner.

INTERACTION: Perform steps 15 and 17.

# Adjust High Frequency Compensation (20 mV)

- a. Equipment setup as in step 15 except, Type 7A16 VOLTS/DIV to 20 mV.
- b. ADJUST—R109 and C109 for best front corner and best level.

  INTERACTION: Repeat steps 15, 16 and 17 until optimum results are obtained.
- c. Remove the Type 7A16 from the plug-in extender and insert the Type 7A16 into the Type 7704 vertical compartment.
- d. Repeat steps 15, 16 and 17 touching up adjustments as necessary to obtain the best front corner and level.

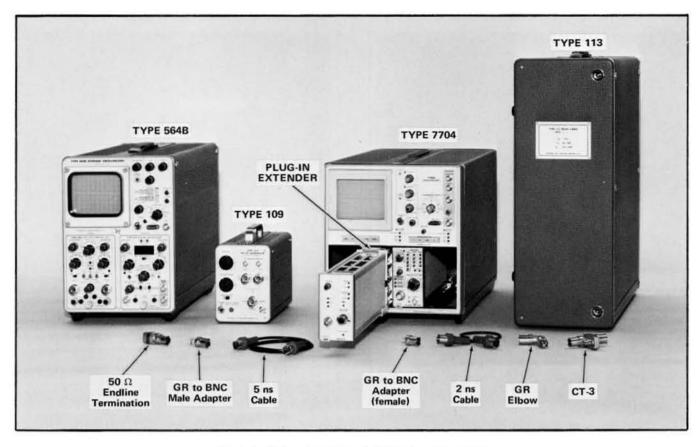


Fig. 5-4. Test equipment required for steps 18 and 20.

e. Reconnect the Type 7A16 to the plug-in extender. Check the sampling display to ensure that no ringing has been introduced.

# **Partial Procedure**

If beginning a partial procedure with this step, set the controls as given under Preliminary Control Settings, except set Type 7A16 Input Coupling to DC.

# 18. Check Step Response

- a. Test equipment required is shown in Fig. 5-4.
- b. Connect the Type 109 charge line through two GR elbows to the Type 113 delay cable; terminate the other charge line with a 50 ohm GR end-line termination; connect the Type 109 output through the CT-3 pickoff, 5 nanosecond cable, 50 ohm feedthrough termination to the Type 7A16 INPUT; connect a BNC cable from the CT-3 BNC connector to the 3T2 50 ohm trigger input; using two 2 nanosecond cables, connect the plug-in extender left signal cable (A11) to the Type 3S1 channel A input and the extender right signal cable (B11) to the channel B input.
- c. CHECK—All positions of the VOLTS/DIV switch for risetime and aberrations (see Fig. 5-5) using the information given in Table 5-3.

TABLE 5-3 Step Response Adjustments

VOLTS/DIV Setting	Risetime	Aberrations (maximum)	Type 109
5 mV/Div to 20 mV/Div	1.4 ns	+3%, -3%; total of 6% P-P	five divisions
50 mV/Div to 0.5 V/Div	1.4 ns	+4%, -4%; total of 6% P-P	
1 V/Div to 5 V/Div	1.4 ns	+5%, -5%; total of 8% P-P	

# NOTE

The risetime and aberrations given in Table 5-3 are for calibration aids only and are not instrument specifications.

# 19. Check Upper Bandwidth —3 dB Point

- a. Set the VOLTS/DIV to 10 mV and COUPLING to DC.
- b. Connect the constant amplitude generator 067-0532-00 through a GR to BNC adapter,  $10\times$  attenuator and 50 ohm feedthrough termination to the Type 7A16 INPUT.
- c. Set generator frequency to 3 MHz and adjust the amplitude for a six division display on the sampling oscilloscope.

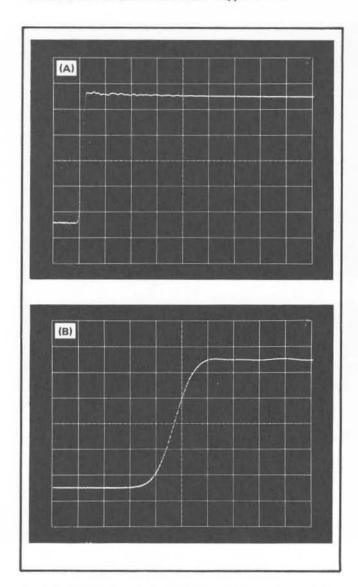


Fig. 5-5. CRT display showing (A) typical aberrations and (B) typical risetime of the Type 7A16.

d. CHECK—Increase the generator frequency until the display decreases to 4.2 divisions and check that the frequency of the signal generator is 250 MHz or greater.

#### NOTE

This bandwidth limit is given as an aid to calibration and is not an instrument specification.

- Return the extender signal cables to their correct jacks and reset the generator to 3 MHz.
- f. Adjust the generator amplitude for a six division display on the Type 7704 oscilloscope .
- g. CHECK—Increase the generator frequency until the display decreases to 4.2 divisions and check that the frequency of the generator is 150 MHz or greater (if a Type 7504 oscilloscope is used, check that the frequency is 90 MHz or greater).

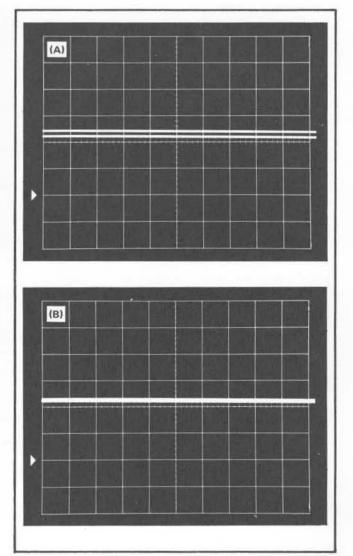


Fig. 5-6. Noise (Tangentially Measured). (A) CRT display showing noise and free running square wave. (B) CRT display showing the two noise bands merged.

#### 20. Check Trigger Step Response

- a. Equipment setup as in Step 18 except: Replace the extender signal cables to their correct jacks; connect the left trigger cable through the 2 ns cable to the Type 3S1 channel A input; connect the right trigger cable through the 2 ns cable to the channel B input.
- b. CHECK—With the VOLTS/DIV switch set to  $5\,\mathrm{mV}$ , check for a risetime of 2.1 nanoseconds or less and aberrations not to exceed +10%, -10% total of 15% P-P (use the Type 109 amplitude control to obtain a five division display).

#### NOTE

Risetime and aberrations are given as an aid to calibration and are not instrument specifications.

 Reconnect the extender trigger cables to their proper jacks.

#### 21. Check 20 Megahertz Bandwidth Limiting

- a. Set the Type 7A16 VOLTS/DIV to 10 mV.
- b. Connect a 20 megahertz signal from the Type 191 signal generator through a 5 nanosecond cable and a 50 ohm feed-through termination to the Type 7A16 INPUT.
- c. Adjust the Type 191 amplitude control for a six division display on the CRT.
- d. Press the BANDWIDTH 20 MHz pushbutton and adjust the Type 191 frequency control to obtain exactly 4.2 divisions of displayed amplitude.
- e. CHECK—The frequency, as read from the Type 191 frequency dial, must be 20 MHz within 3 MHz.
  - f. Disconnect the 20 megahertz signal from the Type 7A16.

#### 22. Check Overall Noise Level Tangentially

a. Set the VOLTS/DIV to 5 mV and free run the time base.

- b. Connect the Type 106 fast rise output through a GR to BNC adapter, BNC cable two  $10\times$  attenuators and a 50 ohm termination to the Type 7A16 INPUT. Set the Type 106 frequency to 1 kHz.
- c. Increase the Type 106 amplitude until two noise bands are observed (noise and free running square wave). Decrease the amplitude until the two noise bands merge (dark line between the noise bands just disappears). See Fig. 5-6. The final adjustment should be made slowly.
- d. Set the VOLTS/DIV to 50 mV and remove the two 10 $\times$  attenuators.
- e. CHECK—Adjust the time base for a stable display and check for a square wave amplitude of one division or less.

#### **EXAMPLE:**

Tangentially Measure Noise 
$$\frac{\text{Square Wave Amplitude}}{100} = \frac{50 \text{ mV}}{100} = 0.5 \text{ mV}$$

#### **PARTS LIST ABBREVIATIONS**

ВНВ	binding head brass	int	internal
BHS	binding head steel	lg	length or long
cap.	capacitor	met.	metal
cer	ceramic	mtg hdw	mounting hardware
comp	composition	OD	outside diameter
conn	connector	OHB	oval head brass
CRT	cathode-ray tube	OHS	oval head steel
csk	countersunk	P/O	part of
DE	double end	PHB	pan head brass
dia	diameter	PHS	pan head steel
div	division	plstc	plastic
elect.	electrolytic	PMC	paper, metal cased
	•	poly	polystyrene
EMC	electrolytic, metal cased	prec	precision
EMT	electrolytic, metal tubular	PT	paper, tubular
ext	external	PTM	paper or plastic, tubular, molded
F&I	focus and intensity	RHB	round head brass
FHB	flat head brass	RHS	round head steel
FHS	flat head steel	SE	single end
Fil HB	fillister head brass	SN or S/N	serial number
Fil HS	fillister head steel	S or SW	switch
h	height or high	TC	temperature compensated
hex.	hexagonal	THB	truss head brass
ННВ	hex head brass	thk	thick
HHS	hex head steel	THS	truss head steel
HSB	hex socket brass	tub.	tubular
HSS	hex socket steel	var	variable
ID	inside diameter	w	wide or width
inc	incandescent	WW	wire-wound

#### PARTS ORDERING INFORMATION

Replacement parts are available from or through your local Tektronix, Inc. Field Office or representative.

Changes to Tektronix instruments are sometimes made to accommodate improved components as they become available, and to give you the benefit of the latest circuit improvements developed in our engineering department. It is therefore important, when ordering parts, to include the following information in your order: Part number, instrument type or number, serial or model number, and modification number if applicable.

If a part you have ordered has been replaced with a new or improved part, your local Tektronix, Inc. Field Office or representative will contact you concerning any change in part number.

#### SPECIAL NOTES AND SYMBOLS

$\times$ 000	Part first added at this serial number
$\sim$	Part removed after this serial number
*000-0000-00	Asterisk preceding Tektronix Part Number indicates manufactured by or for Tektronix, Inc., or reworked or checked components.
Use 000-0000-00	Part number indicated is direct replacement.

#### INDEX OF ELECTRICAL PARTS LIST

Title P	'age	No.
CHASSIS		6-1
ATTENUATOR STRIP Assembly 1 $ imes$		6-2
ATTENUATOR STRIP Assembly 2 $1/2  imes \dots$		6-2
ATTENUATOR STRIP Assembly $5 imes$		6-2
ATTENUATOR STRIP Assembly $10  imes \dots$		6-3
ATTENUATOR STRIP Assembly 25 $ imes$		6-3
ATTENUATOR STRIP Assembly $50 \times \dots \dots$		6-3
ATTENUATOR STRIP Assembly $100  imes \dots$		6-4
ATTENUATOR STRIP Assembly 250 $ imes$		6-4
AC-DC-GND RELAY Circuit Board Assembly		6-5
VERTICAL AMPLIFIER Circuit Board Assembly		6-5
AC-DC-GND Switch Circuit Board Assembly		6-12
POLARITY Switch Circuit Board Assembly		6-12
BANDWIDTH Switch Circuit Bound Assembly		<u>د</u> 10

### SECTION 6 ELECTRICAL PARTS LIST

Values are fixed unless marked Variable.

Ckt. No.	Tektronix Part No.	Serial/N Eff	Aodel No. Disc		Descrip	otion	
			CHA	SSIS			
			Сара	citors			
Tolerance ±2	20% unless otherwise	indicated.					
C3 <sup>1</sup>	201.0.407.00			5000 F		100.1	. 1000/
C4 C14	281-0697-00 283-0674-00			5000 pF 85 pF	Cer Mica	100 ∨ 100 ∨	+100% -0%
C200	281-0697-00			5000 pF	Cer	100 V	1 % + 100% 0%
			Conn	ector			
Jī	131-0725-01		30	BNC, receptacle	electrical		
<b>3.</b>	101-0/25-01			bive, receptable	, orcentear		
			Semiconducto	r Device, Diode			
CR210	*152-0185-00			Silicon	Rep	olaceable by	1N4152
			Indu	tors			
L4 L200	*120-0382-00 *120-0382-00			Toroid, 14 turns, Toroid, 14 turns,			
			Resis	tors			
Resistors are	fixed, composition, ±	±10% unless	otherwise indic	ated.			
R14	321-0756-03			50 kΩ	⅓ W	Prec	1/4 %
R115 <sup>2</sup>	311-0652-00			$2 \times 5 k\Omega$ , Var			,,,,
R153	311-0443-00			2.5 k $\Omega$ , Var			
			Swite	:hes			
٧	Vired or Unwired						
\$10 Wire \$10	ed *263-0009-00 263-0510-00			Rotary	VO	LTS/DIV	
S115 <sup>3</sup>	255 55.0 55				IDE	NTIFY	
¹Furnished as a	unit with J1,						
	unit with \$115.						

6-1

<sup>3</sup>Furnished as a unit with R115.

#### ATTENUATOR STRIP Assembly 1 X

		A CONTRACTOR OF THE PASSENDAY OF THE PAS
Ckt. No.	Tektronix Part No.	Serial/Model No. Eff Disc Description
	*307-1001-00	Complete Attenuator Strip
C5⁴		Capacitor
		Resistor
R5⁴		
		ATTENUATOR STRIP Assembly 2½ X
	*307-1002-00	Complete Attenuator Strip
		Capacitors
C6A⁵ C6B⁵ C6C⁵		
		Resistors
R6A⁵ R6B⁵ R6C⁵		
		ATTENUATOR STRIP Assembly 5 X
	*307-1003-00	Complete Attenuator Strip
		Capacitors
C76 <sup>6</sup> C7B <sup>6</sup>		
		Resistors
R7A <sup>6</sup> R7B <sup>6</sup> R7C <sup>6</sup>		
<sup>5</sup> Furnished as	a unit with *307-1001-00 a unit with *307-1002-00 a unit with *307-1003-00	

#### ATTENUATOR STRIP Assembly 10 X

Ckt. No.	Tektronix Part No.	Serial/Model No. Eff Disc Description
	*307-1004-00	Complete Attenuator Strip
C8A <sup>7</sup> C8B <sup>7</sup> C8C <sup>7</sup>		Capacitors
R8A <sup>7</sup> R8B <sup>7</sup> R8C <sup>7</sup>		Resistors
	*307-1005-00	ATTENUATOR STRIP Assembly 25 X  Complete Attenuator Strip
C9A <sup>s</sup> C9B <sup>s</sup> C9C <sup>s</sup>		Capacitors
R9A <sup>8</sup> R9B <sup>8</sup> R9C <sup>8</sup>		Resistors
	*307-1006-00	ATTENUATOR STRIP Assembly 50 X  Complete Attenuator Strip
C10A° C10B° C10C°		Capacitors
<sup>8</sup> Furnished as	a unit with *307-1004-00. a unit with *307-1005-00. a unit with *307-1006-00.	

#### ATTENUATOR STRIP Assembly 50 X (cont)

Ckt. No.	Tektronix Part No.	Serial/Model Eff	No. Disc	Description
			Resisto	rs
R10A <sup>10</sup> R10B <sup>10</sup> R10C <sup>10</sup>				
		ATTENUATO	R STRIP	Assembly 100 X
	*307-1007-00			Complete Attenuator Strip
			Capacit	ors
C11A <sup>11</sup> C11B <sup>11</sup> C11C <sup>11</sup>				
			· Resisto	rs
R11A <sup>11</sup> R11B <sup>11</sup> R11C <sup>11</sup>	·			
		ATTENUATO	R STRIP	Assembly 250 X
	*307-1008-00			Complete Attenuator Strip
			Capacit	ors
C12A <sup>12</sup> C12B <sup>12</sup> C12C <sup>12</sup>				
			Resisto	rs
R12A <sup>12</sup> R12B <sup>12</sup> R12C <sup>12</sup>				
	a unit with *307-1006-00			

6-4

 $^{12}\text{Furnished}$  as a unit with \*307-1008-00.

#### **AC-DC-GND RELAY Circuit Board Assembly**

Ckt. No.	Tektronix Part No.	Serial/Model No. Eff Disc		Descriț	otion	
	*670-1092-00		Complete Bo	ard		
		Сара	citor			
Tolerance =	±20% unless otherwise	indicated.				
C2	283-0160-00		1.5 pF	Cer	50 ∨	10%
		Rele	y			
K5 S5A, B	*148-0063-00		Polarized, 200 m\	V, dpat, 5	pin	
		Resis	tors			
Resistors are	e fixed, composition, =	±10% unless otherwise indic	ated.			
R1 R2	317-0620-00 317-0620-00		62 Ω 62 Ω	¹/8 W ¹/8 W		5% 5%
R3	317-0105-00		1 MΩ	1/8 W		5% 5%
	v	ERTICAL AMPLIFIER CI	rcuit Board Asse	embly		
	*670-1113-00 *670-1113-01 *670-1113-02 *670-1113-03 *670-1113-04 *670-1113-05	B010100 B019999 B020000 B029999 B030000 B039999 B040000 B049999 B050000 B059999 B060000	Complete Boo Complete Boo Complete Boo Complete Boo Complete Boo Complete Boo	ard ard ard ard		
		Сарас	itors			
Tolerance ±	=20% unless otherwise	indicated.				
C18 C20 C23 C24 C28	281-0064-00 283-0080-00 283-0059-00 290-0135-00 281-0651-00	XB060000	0.25-1.5 pF, Var 0.022 μF 1 μF 15 μF 47 pF	Tub. Cer Cer Elect. Cer	25 V 25 V 20 V	+80%-20%+80%-20%
C30	283-0080-00		0.022 μF	Cer	25 V	+80%-20%
C34 C35 C36 C40	283-0080-00 283-0178-00 283-0080-00 283-0060-00		$0.022~\mu { m F} \ 0.1~\mu { m F} \ 0.022~\mu { m F} \ 100~{ m pF}$	Cer Cer Cer Cer	25 V 100 V 25 V 200 V	+80% -20% +80% -20% +80% -20% 5%

#### Electrical Parts List—Type 7A16

Ckt. No.	Tektronix Part No.	Serial/Model No Eff I	o. Disc	Descrip	tion	
		Ca	pacitors (cont)			
C45 C52 C55 C56 C57 C61	281-0123-00 281-0123-00 283-0060-00 283-0059-00 290-0135-00 281-0122-00	XB060000	5-25 pF, Var 5-25 pF, Var 100 pF 1 $\mu$ F 15 $\mu$ F 2.5-9 pF, Var	Cer Cer Cer Cer Elect. Cer	100 V 100 V 200 V 25 V 20 V 100 V	5% +80%—20%
C65 C68 C77 C85 C88	281-0656-00 283-0065-00 281-0577-00 281-0656-00 283-0065-00		$22 \text{ pF} \\ 0.001  \mu\text{F} \\ 14 \text{ pF} \\ 22 \text{ pF} \\ 0.001  \mu\text{F}$	Cer Cer Cer Cer Cer	200 V 100 V 500 V 200 V 100 V	5% 5% 5% 5% 5%
C89 C97 C102 C103 C104	283-0178-00 283-0629-00 281-0122-00 281-0122-00 283-0178-00		0.1 $\mu$ F 62 pF 2.5-9 pF, Var 2.5-9 pF, Var 0.1 $\mu$ F	Cer Mica Cer Cer Cer	100 V 500 V 100 V 100 V 100 V	+80% -20% 1% +80% -20%
C105 C109 C111 C112 C124	283-0077-00 281-0122-00 281-0122-00 281-0601-00 283-0077-00		330 pF 2.5-9 pF, Var 2.5-9 pF, Var 7.5 pF 330 pF	Cer Cer Cer Cer Cer	500 V 100 V 100 V 500 V 500 V	5% ±0.5 pF 5%
C125 C130 C131 C133 C138	283-0065-00 283-0185-00 283-0080-00 283-0065-00 281-0613-00		0.001 $\mu$ F 2.5 pF 0.022 $\mu$ F 0.001 $\mu$ F 10 pF	Cer Cer Cer Cer	100 V 50 V 25 V 100 V 200 V	5% 5% +80% -20% 5% 10%
C140 C143 C145 C155 C162	283-0178-00 283-0080-00 281-0612-00 283-0077-00 281-0601-00		0.1 $\mu$ F 0.022 $\mu$ F 5.6 pF 330 pF 7.5 pF	Cer Cer Cer Cer	100 V 25 V 200 V 500 V 500 V	+80%20% +80%20% ±0.5 pF 5% ±0.5 pF
C164 C165 C169 C173 C178	283-0077-00 283-0065-00 281-0617-00 283-0065-00 281-0613-00		$330 \text{ pF}$ $0.001 \ \mu\text{F}$ $15 \text{ pF}$ $0.001 \ \mu\text{F}$ $10 \text{ pF}$	Cer Cer Cer Cer	500 V 100 V 200 V 100 V 200 V	5% 5% 5% 10%
C185 C234 C235 C236 C237	281-0612-00 290-0135-00 283-0178-00 283-0065-00 290-0135-00		5.6 pF 15 $\mu$ F 0.1 $\mu$ F 0.001 $\mu$ F 15 $\mu$ F	Cer Elect. Cer Cer Elect.	200 V 20 V 100 V 100 V 20 V	±0.5 pF +80%-20% 5%
C238 C239	283-0178-00 283-0065-00		0.1 μF 0.001 μF	Cer Cer	100 V 100 V	+80% -20% 5%

Ckt. No.	Tektronix Part No.	Serial/Ma Eff	odel No. Disc		Description
		Se	miconductor	Device, Diodes	
VR20 VR20 CR29 CR30 VR30	152-0278-00 152-0279-00 *152-0323-00 *152-0153-00 152-0278-00	B010100 B030000	B029999 B029999	Zener Zener Silicon Silicon Zener	1N4372A 400 mW, 3 V, 5% 1N751A 400 mW, 5.1 V, 5% Tek Spec Tek Spec 1N4372A 400 mW, 3 V, 5%
VR30 VR123 CR128 CR168 CR200	152-0279-00 152-0166-00 152-0422-00 152-0422-00 *152-0185-00	B030000		Zener Zener Silicon Silicon Silicon	1N751A 400 mW, 5.1 V, 5% 1N753A 400 mW, 6.2 V, 5% Voltage Variable Capacitance Voltage Variable Capacitance Replaceable by 1N4152
CR220 CR222 CR224 CR226 CR227 CR228	*152-0185-00 *152-0185-00 *152-0185-00 *152-0185-00 *152-0185-00 *152-0185-00	XB060000 XB060000		Silicon Silicon Silicon Silicon Silicon Silicon	Replaceable by 1N4152 Replaceable by 1N4152 Replaceable by 1N4152 Replaceable by 1N4152 Replaceable by 1N4152 Replaceable by 1N4152
			Reio	ıys	
K65 K75 K105 K110 K115	*148-0034-00 *148-0034-00 *148-0035-00 *148-0035-00 *148-0034-00			Armature, dpdt Armature, dpdt Armature, spdt Armature, spdt Armature, spdt	15 V DC 15 V DC 15 V DC 15 V DC 15 V DC
K155 K160	*148-0035-00 *148-0035-00			Armature, spdt Armature, spdt	15 V DC 15 V DC
			Induci	ors	
L20 L20 L30 L30 L34	*108-0440-00 *120-0382-00 *108-0440-00 *120-0382-00 276-0507-00	B010100 B060000 B010100 B060000	B059999 B059999	8 $\mu$ H Toroid, 14 turns, sing 8 $\mu$ H Toroid, 14 turns, sing Core, ferramic suppr	gle
L68 L76	276-0507-00 *108-0170-01			Core, ferramic suppr 0.5 $\mu$ H	essor
L88 L96 L97 L131 L133	276-0507-00 *108-0170-01 276-0507-00 *108-0440-00 276-0507-00			Core, ferramic suppr 0.5 μΗ Core, ferramic suppr 8 μΗ Core, ferramic suppre	essor

Ckt. No.	Tektronix Part No.	Serial/Ma Eff	odel No. Disc		Description	
			Inductors	(cont)		
L140 L143 L173 L230 L236	*108-0440-00 *108-0440-00 276-0507-00 *120-0382-00 *120-0382-00			8 μΗ 8 μΗ Core, ferramic Toroid, 14 turn Toroid, 14 turn	ns, single	
L238 LR159	*120-0382-00 *108-0568-00			Toroid, 14 turi 75 nH (wound	ns, single l on a 68 Ω, 1/ <sub>8</sub> W, 5% resistor)	
			Trans	istors		
Q20	151-1032-00			Silicon	FET, dual	
Q40 }	*153-0580-00			Silicon	Selected, Tek Spec	
Q50 ) Q60 Q70	*151-0268-00 *151-0212-00			Silicon Silicon	Tek Spec, dual Tek Spec	
Q90 Q100 Q120 Q125 Q130 Q130	*151-0212-00 *151-0272-00 *151-0272-00 *151-0212-00 *151-0259-00 *151-0269-00	B010100 B040000	B039999	Silicon Silicon Silicon Silicon Silicon Silicon	Tek Spec Tek Spec, dual Tek Spec, dual Tek Spec Selected from 2N3563 Selected from SE3005	
Q135 Q140 Q165 Q170 Q170 Q175	*151-0212-00 151-0298-00 *151-0212-00 *151-0259-00 *151-0269-00 *151-0212-00	B010100 B040000	B039999	Silicon Silicon Silicon Silicon Silicon Silicon	Tek Spec NPN, TO-72, MM1606 Tek Spec Selected from 2N3563 Selected from SE3005 Tek Spec	
Q180 Q200	151-0298-00 151-0254-00			Silicon Silicon	NPN, TO-72, MM1606 TO-98, D16P4	
			Resis	tors		
Resistors are f	ixed, composition, =	±10% unless	otherwise indic	ated.		
R17 R18 R23 R28 R30	323-0612-03 315-0561-00 317-0151-00 325-0041-00 325-0041-00			950 kΩ 560 Ω 150 Ω 19.75 Ω 19.75 Ω	1/ <sub>2</sub> W Prec 1/ <sub>4</sub> W 1/ <sub>8</sub> W 1/20 W Prec 1/20 W Prec	1/4 % 5% 5% 1% 1%
R31 R34 R35 R38 R40	315-0472-00 311-0462-00 315-0913-00 317-0151-00 311-0634-00			$4.7~\mathrm{k}\Omega$ 1 $\mathrm{k}\Omega$ , $\mathrm{Var}$ 91 $\mathrm{k}\Omega$ 150 $\Omega$ 500 $\Omega$ , $\mathrm{Var}$	1/ <sub>4</sub> W 1/ <sub>4</sub> W 1/ <sub>8</sub> W	5% 5% 5% 5%

Ckt. No.	Tektronix Part No.	Serial/M Eff	odel No. Disc		Descrip	otion	
			Resistors	(cont)			
R43 R45 R51 R52 R55	315-0182-00 317-0470-00 315-0182-00 317-0560-00 311-0634-00			1.8 kΩ 47 Ω 1.8 kΩ 56 Ω 500 Ω, Var	1/ <sub>4</sub> W 1/ <sub>8</sub> W 1/ <sub>4</sub> W 1/ <sub>8</sub> W		5% 5% 5% 5%
R60 R61 R62 R64 R64	321-0062-00 311-0605-00 323-0175-00 321-0114-00 321-0097-00 321-0076-00	B010100 B020000 B050000	B019999 B049999	43.2 Ω 200 Ω, Var 649 Ω 150 Ω 100 Ω 60.4 Ω	1/8 W 1/2 W 1/8 W 1/8 W 1/8 W	Prec Prec Prec Prec Prec	1% 1% 1% 1%
R65 R65 R66 R67 R68	321-0033-00 321-0024-00 311-0963-00 315-0153-00 317-0241-00	B010100 B050000	B049999	21.5 $\Omega$ 17.4 $\Omega$ 5 k $\Omega$ , Var 15 k $\Omega$ 240 $\Omega$	1/8 W 1/8 W 1/4 W 1/8 W	Prec Prec	1% 1% 5% 5%
R70 R71 R73 R74 R80	325-0053-00 325-0053-00 321-0186-00 321-0177-00 321-0062-00			50 Ω 50 Ω 845 Ω 681 Ω 43.2 Ω	1/20 W 1/20 W 1/ <sub>8</sub> W 1/ <sub>8</sub> W 1/ <sub>8</sub> W	Prec Prec Prec Prec Prec	1% 1% 1% 1%
R82 R84 R84 R85	317-0200-00 321-0114-00 321-0097-00 321-0076-00 321-0033-00	B010100 B020000 B050000 B010100	B019999 B049999 B049999	20 Ω 150 Ω 100 Ω 60.4 Ω 21.5 Ω	1/8 W 1/8 W 1/8 W 1/8 W 1/8 W	Prec Prec Prec Prec	5% 1% 1% 1%
R85 R86 R87 R88 R89	321-0024-00 311-0963-00 315-0153-00 317-0301-00 311-0510-00	B050000		$\begin{array}{l} 17.4~\Omega \\ 5~k\Omega,~Var \\ 15~k\Omega \\ 300~\Omega \\ 10~k\Omega,~Var \end{array}$	1/ <sub>8</sub> W 1/ <sub>4</sub> W 1/ <sub>8</sub> W	Prec	1% 5% 5%
R90 R100 R101 R102 R103	325-0053-00 321-0085-00 323-0135-00 321-0039-00 311-0635-00			50 Ω 75 Ω 249 Ω 24.9 Ω 1 kΩ, Var	1/20 W 1/8 W 1/2 W 1/8 W	Prec Prec Prec Prec	1% 1% 1% 1%
R104 R105 R106 R108 R109	323-0114-00 317-0331-00 322-0193-00 325-0047-00 311-0634-00			$150~\Omega$ $350~\Omega$ $1~k\Omega$ $25~\Omega$ $500~\Omega$ , Var	1/ <sub>2</sub> W 1/ <sub>8</sub> W 1/ <sub>4</sub> W 1/20 W	Prec Prec Prec	1% 5% 1% ½%
R111 R112 R114 R117 R118	311-0634-00 325-0045-00 315-0103-00 311-0442-00 322-0206-00			500 Ω, Var 46.4 Ω 10 kΩ 250 Ω, Var 1.37 kΩ	1/20 W 1/4 W 1/4 W	Prec	½% 5% 1%

#### Electrical Parts List—Type 7A16

Ckt. No.	Tektronix Part No.	Serial/Model Eff	No. Disc	Descrip	tion	
			Resistors (cont)			
R120 R121 R123 R124 R125	321-0085-00 322-0207-00 321-0114-00 317-0391-00 317-0241-00		75 Ω 1.4 kΩ 150 Ω 390 Ω 240 Ω	1/8 W 1/4 W 1/8 W 1/8 W 1/8 W	Prec Prec Prec	1% 1% 1% 5% 5%
R126 R127 R128 RT128	321-0434-00 321-0068-00 321-0068-00 307-0181-00		324 kΩ 49.9 Ω 49.9 Ω 100 kΩ	1/8 W 1/8 W 1/8 W Thermal	Prec Prec Prec	1% 1% 1%
R129	322-0147-00		332 Ω	1/ <sub>4</sub> W	Prec	1%
R130 R131 R133 R135 R137	321-0062-00 323-0142-00 317-0241-00 321-0135-00 323-0171-00		43.2 Ω 294 Ω 240 Ω 249 Ω 590 Ω	1/8 W 1/2 W 1/8 W 1/8 W 1/2 W	Prec Prec Prec Prec	1% 1% 5% 1%
R138 R141 R142 R143 R145	321-0062-00 323-0167-00 321-0135-00 323-0146-00 321-0062-00		43.2 Ω 536 Ω 249 Ω 324 Ω 43.2 Ω	1/ <sub>8</sub> W 1/ <sub>2</sub> W 1/ <sub>8</sub> W 1/ <sub>2</sub> W 1/ <sub>8</sub> W	Prec Prec Prec Prec Prec	1% 1% 1% 1% 1%
R150 R151	321-0085-00 321-0039-00		75 Ω 24.9 Ω	1/8 W 1/8 W	Prec Prec	1% 1%
R154 R155 R156	315-0103-00 317-0331-00 322-0193-00		10 kΩ 330 Ω 1 kΩ	1/ <sub>4</sub> W 1/ <sub>8</sub> W 1/ <sub>4</sub> W	Prec	5% 5% 1%
R158 R159 R160	325-0047-00 325-0044-00 315-0103-00		25 Ω 100 Ω 10 kΩ	1/20 W 1/20 W 1/4 W	Prec Prec	1/2 % 1/2 % 5 %
R161 R162	325-0044-00 325-0045-00		100 Ω 46.4 Ω	1/20 W 1/20 W	Prec Prec	1/ <sub>2</sub> % 1/ <sub>2</sub> %
R163 R164 R165	321-0114-00 317-0391-00 317-0241-00		150 Ω 390 Ω 240 Ω	1/8 W 1/8 W 1/8 W	Prec	1 % 5 % 5 %
R166 R167	322-0206-00 321-0068-00		1.37 kΩ 49.9 Ω	1/ <sub>4</sub> W 1/ <sub>8</sub> W	Prec Prec	1% 1%
R168 R169 R170 R172	321-0068-00 317-0472-00 321-0062-00 321-0196-00		49.9 Ω 4.7 kΩ 43.2 Ω 1.07 kΩ	1/ <sub>8</sub> W 1/ <sub>8</sub> W 1/ <sub>8</sub> W 1/ <sub>8</sub> W	Prec Prec Prec	1% 5% 1% 1%
R173	317-0241-00		240 Ω	1/8 W		5%

Ckt. No.	Tektronix Part No.	Serial/Model Eff	No. Disc	Descrip	ition	
			Resistors (cont)			
R174 R175	323-0149-00 321-0135-00		348 Ω 249 Ω	1/ <sub>2</sub> ₩ 1/ <sub>8</sub> ₩	Prec Prec	1% 1%
R1 <i>77</i> R1 <i>7</i> 8 R181	323-0171-00 321-0062-00 323-01 <i>6</i> 7-00		590 Ω 43.2 Ω 536 Ω	1/ <sub>2</sub> W 1/ <sub>8</sub> W 1/ <sub>2</sub> W	Prec Prec Prec	1% 1% 1% 1% 1%
R182 R185	321-0135-00 321-0062-00		249 Ω 43.2 Ω	1/8 W 1/8 W	Prec Prec	1% 1% 5%
R200 R202 R204	315-0184-00 322-0223-00 321-0299-00		180 kΩ 2.05 kΩ 12.7 kΩ	1/ <sub>4</sub> W 1/ <sub>4</sub> W 1/ <sub>8</sub> W	Prec Prec	5% 1% 1%
R205 R206 R207	321-0344-00 315-0753-00 315-0753-00		37.4 kΩ 75 kΩ 75 kΩ	1/ <sub>8</sub> W 1/ <sub>4</sub> W 1/ <sub>4</sub> W	Prec	6% 5% 5%
R208 R209	315-07-33-00 315-0154-00 321-0344-00		150 kΩ 37.4 kΩ	1/4 W 1/4 W 1/8 W	Prec	1% 5%
R218 R219 R220	315-0154-00 315-0154-00 315-0133-00		150 kΩ 150 kΩ 13 kΩ	1/4 W 1/4 W 1/4 W		5% 5% 5%
R222 R224	315-0154-00 315-0154-00		150 kΩ 150 kΩ	1/ <sub>4</sub> W 1/ <sub>4</sub> W		5% 5% 5% 5%
R225 R226 R228 R232	315-0513-00 315-0154-00 315-0753-00 315-0510-00		51 kΩ 150 kΩ 75 kΩ 51 Ω	1/4 W 1/4 W 1/4 W 1/4 W		5% 5% 5% 5%
R233	315-0753-00		75 kΩ	1/ <sub>4</sub> W		5%
R234 R235 R236 R238 R239	315-0510-00 307-0103-00 315-0101-00 315-0101-00 315-0470-00		51 Ω 2.7 Ω 100 Ω 100 Ω 47 Ω	1/4 W 1/4 W 1/4 W 1/4 W 1/4 W		5% 5% 5% 5%
			Switch			
	Wired or Unwired					
S65 <sup>13</sup>	*670-1134-00		Slide	VAI	RIABLE CAL IN	

<sup>&</sup>lt;sup>13</sup>See Mechanical Parts List for replacement parts.

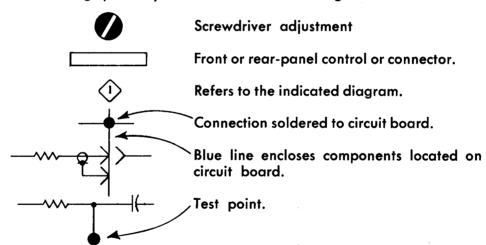
#### **AC-DC-GND Switch Circuit Board Assembly**

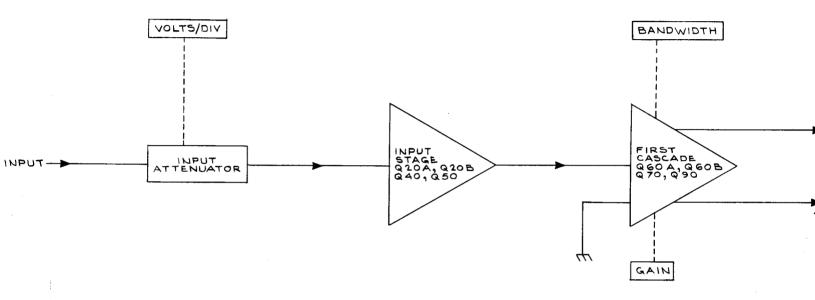
Ckt. No.	Tektronix Part No.	Serial/Mod Eff	del No. Disc		Description
	*670-1124-00 *670-1124-01	B010100 B070000	B069999	Complete Bo	
			Bul	b	
DS3 D53	*150-0057-01 *150-0048-01	B010100 B070000	B069999	Incandescent Incandescent	7153AS15, selected #683, selected
			Swit	ch	
	Wired or Unwired				
S3 <sup>14</sup> S3 <sup>14</sup>	*670-1124-00 *670-1124-01	B010100 B070000	B069999	Pushbutton Pushbutton	AC-GND-DC AC-GND-DC
		POLARITY :	Switch Circ	uit Board Asse	embly
	*670-1125-00 *670-1125-01	B010100 B070000	B069999	Complete Bo Complete Bo	
			Bul	b	
DS118 DS118	*150-0057-01 *150-0048-01	B010100 B070000	B069999	Incandescent Incandescent	7153AS15, selected #683, selected
			Swit	ch	
	Wired or Unwired				
S118 <sup>14</sup> S118 <sup>14</sup>	*670-1125-00 *670-1125-01	B010100 B070000	B069999	Pushbutton Pushbutton	INVERT INVERT
	E	BANDWIDTH	Switch Cir	rcuit Board As	sembly
	*670-1126-00 *670-1126-01	B010100 B070000	B069999	Complete Bo	
			Buli	ь	
DS75 DS75	*150-0057-01 *150-0048-01	B010100 B070000	B069999	incandescent Incandescent	7153AS15, selected #683, selected
			Swit	ch	
	Wired or Unwired				
\$75 <sup>14</sup> \$75 <sup>14</sup>	*670-1126-00 *670-1126-01	B010100 B070000	B069999	Pushbutton Pushbutton	BANDWIDTH BANDWIDTH

# SECTION 7 DIAGRAMS and MECHANICAL PARTS ILLUSTRATIONS

INPUT-

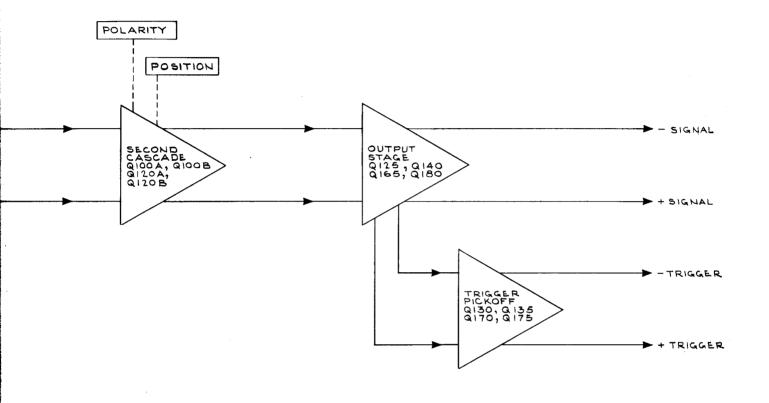
The following special symbols are used on the diagrams:





7AIG AMPLIFIER

**(A)** 



hq 1069

BLOCK DIAGRAM

**(A)** 

#### VOLTAGE AND WAVEFORM TEST CONDITIONS

Typical voltage measurements and waveform photographs were obtained under the following conditions unless noted otherwise on the individual diagrams:

#### Type 7704 Oscilloscope

Vertical Mode
Horizontal Mode

Right

Α

#### Type 7A16 Controls (left vertical compartment)

POLARITY BANDWIDTH AC-GND-DC VOLTS/DIV

+UP FULL DC 10 mV

INPUT

50 mV from a Standard Amplitude Calibrator

#### Type 7A16 Controls (right vertical compartment)

#### Use a 10X attenuator probe

Polarity +Up
Bandwidth Full
AC-GND-DC AC
Volts/Div 10 mV

#### Type 7B71 Controls (A horizontal compartment)

Level/Slope

0/+

**Triggering** 

Mode Coupling Source P-P Auto AC Ext

Source Ext
Magnifier X1
Time/Div 1 ms
Variable Cal In

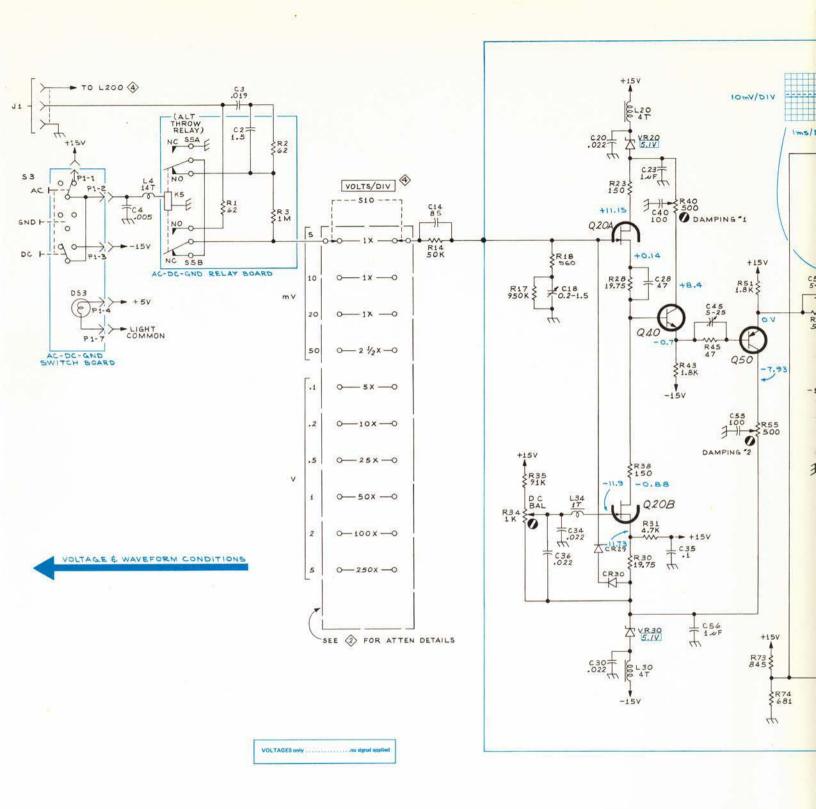
**Ext Trig In** 

Positive trigger signal (A13) from the Type 7A16 in the left

vertical compartment.

All voltages given on the diagrams are in volts. Waveforms shown are actual waveform photographs taken with a Tektronix Oscilloscope Camera System. Voltages and waveforms on the diagrams (shown in blue) are not absolute and may vary between instruments because of differing component tolerances, internal calibration or front-panel control settings.

#### NOTE



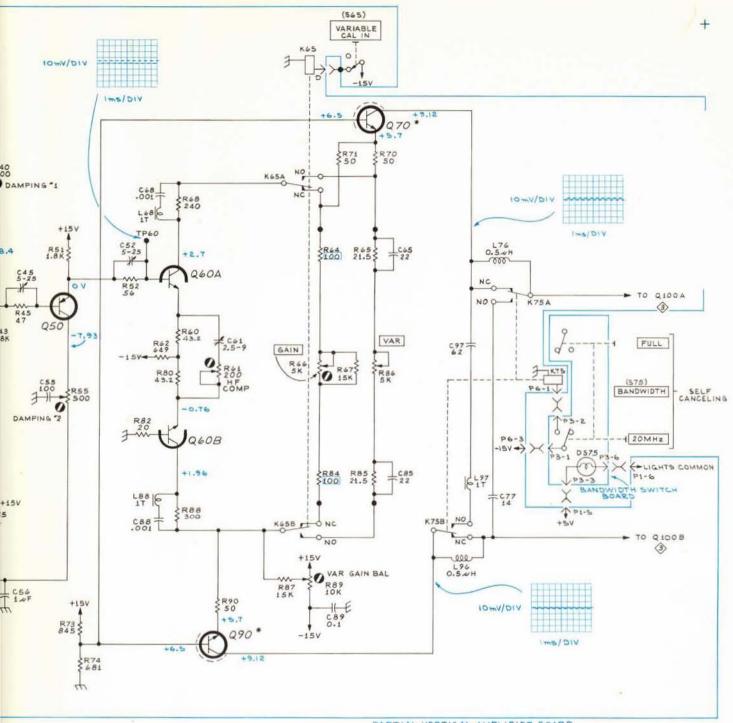
NOTES:

1. SEE PARTS LIST FOR
SEMICONDUCTOR TYPES
2. HEAT SINKED

REFERENCE DIAG

- 2 ATTENUATORS
- 3 OUTPUT AMPLI
  - SWITCHING & I

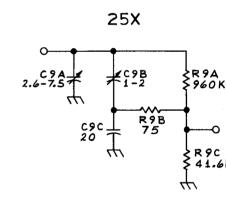
+

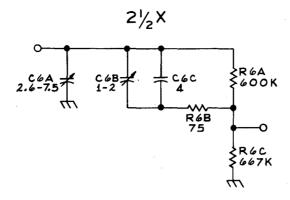


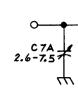
PARTIAL VERTICAL AMPLIFIER BOARD

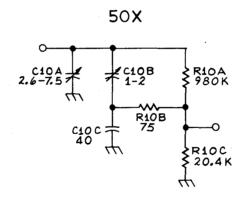
#### REFERENCE DIAGRAMS

- ATTENUATORS
- 3 OUTPUT AMPLIFIER
- SWITCHING & INTERCONNECTING PLUG

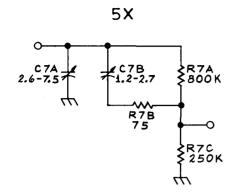


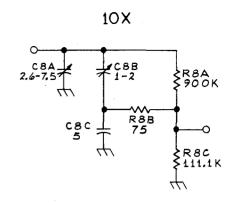


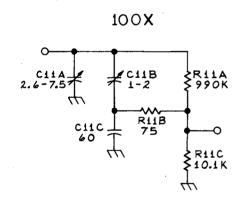


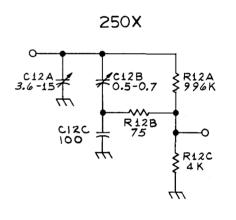


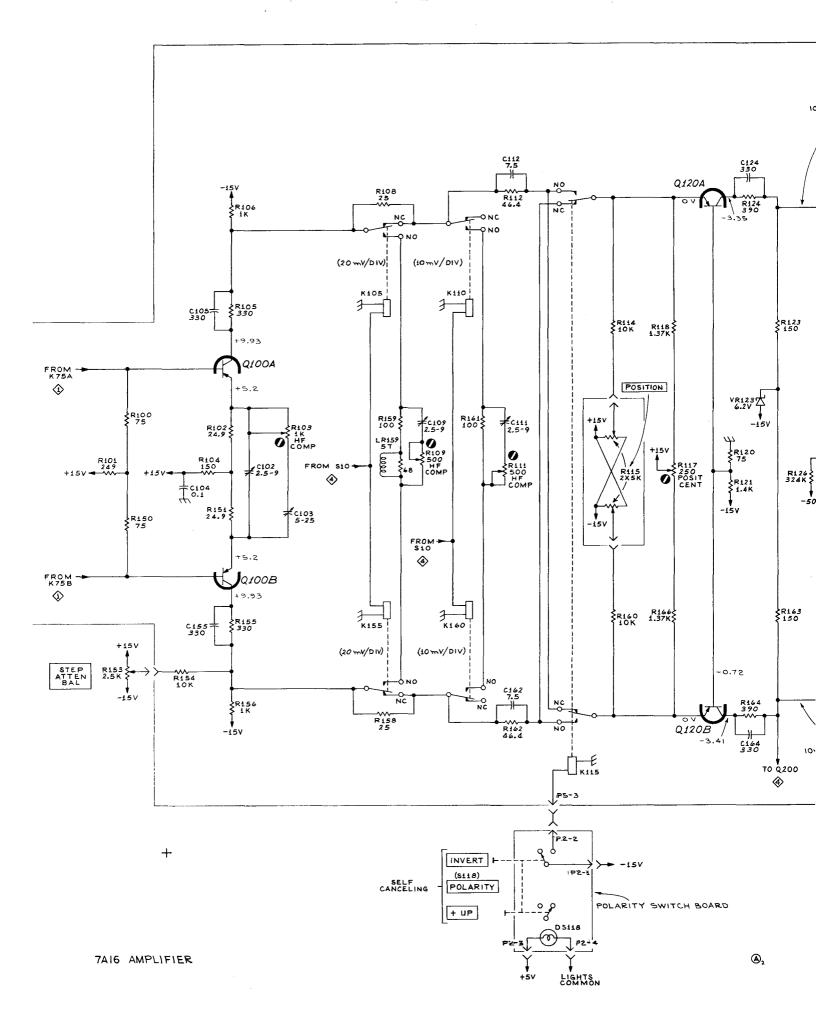
C11A 2.6-7.5

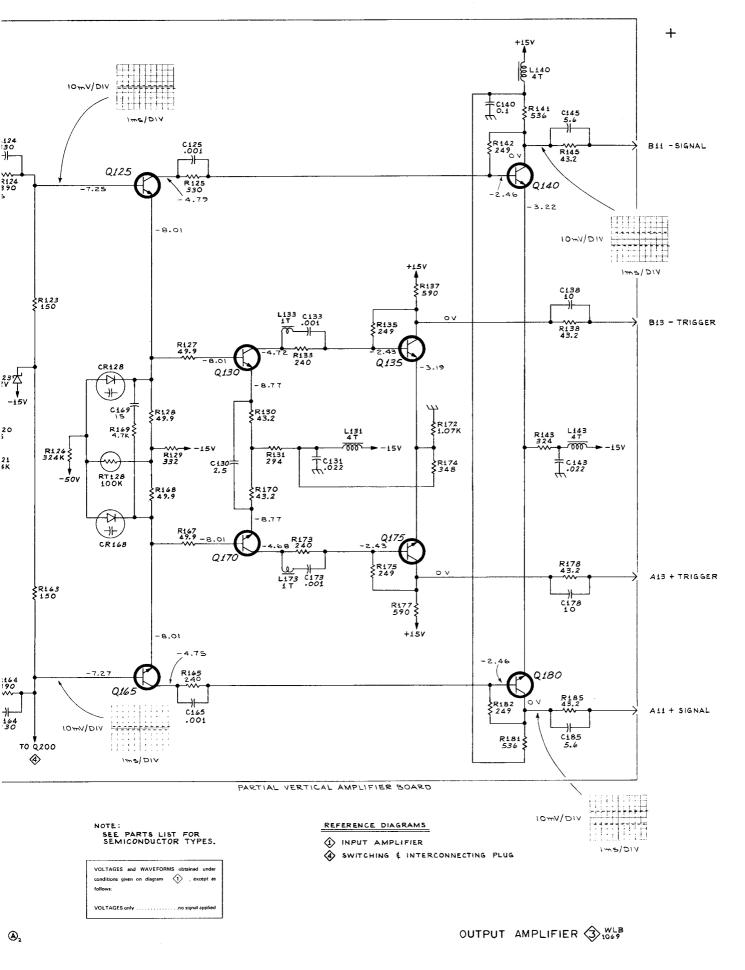




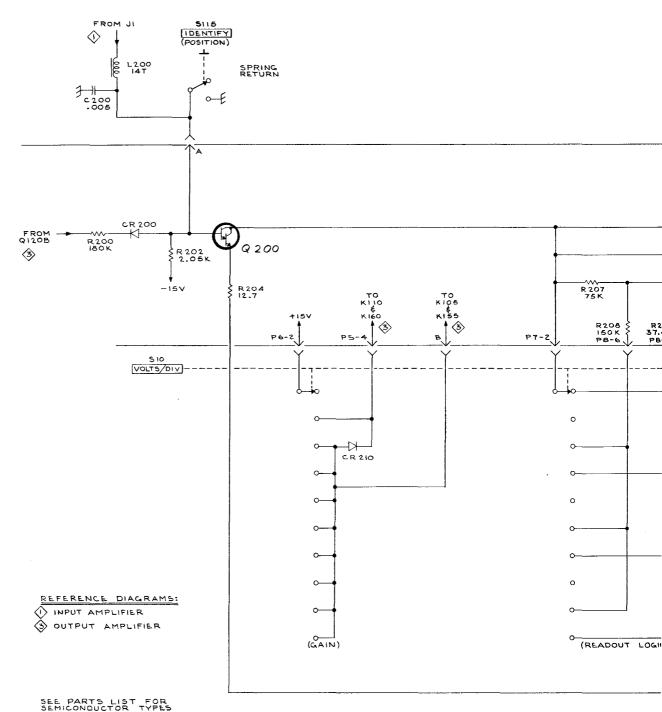






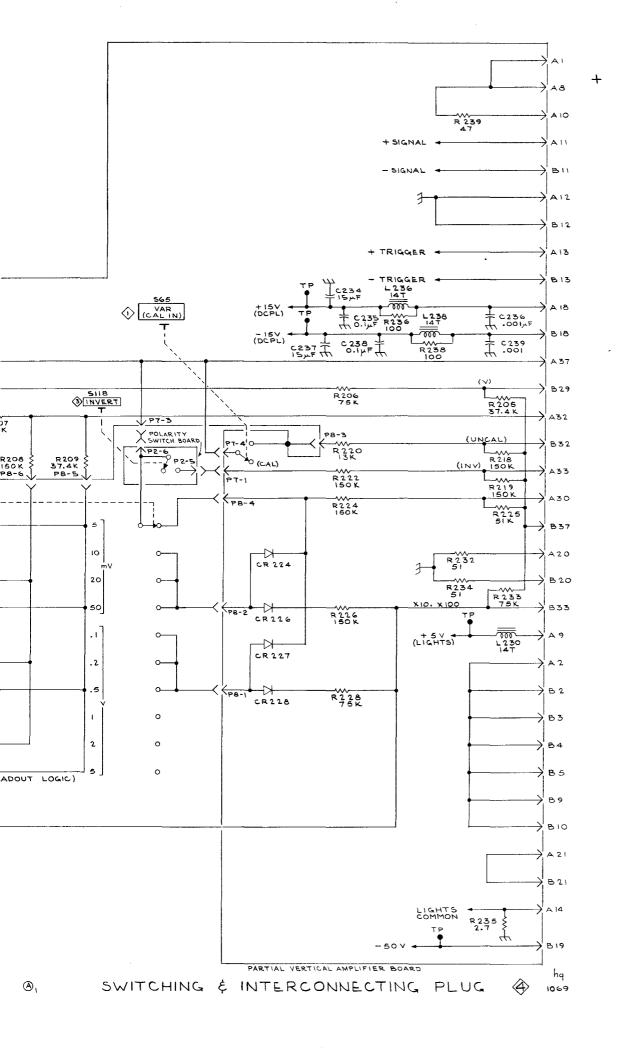






SELLICONSOCTOR TITLE

,



#### FIGURE AND INDEX NUMBERS

Items in this section are referenced by figure and index numbers to the illustrations which appear either on the back of the diagrams or on pullout pages immediately following the diagrams of the instruction manual.

#### INDENTATION SYSTEM

This mechanical parts list is indented to indicate item relationships. Following is an example of the indentation system used in the Description column.

Assembly and/or Component
Detail Part of Assembly and/or Component
mounting hardware for Detail Part
Parts of Detail Part
mounting hardware for Parts of Detail Part
mounting hardware for Assembly and/or Component

Mounting hardware always appears in the same indentation as the item it mounts, while the detail parts are indented to the right. Indented items are part of, and included with, the next higher indentation.

Mounting hardware must be purchased separately, unless otherwise specified.

#### PARTS ORDERING INFORMATION

Replacement parts are available from or through your local Tektronix, Inc. Field Office or representative.

Changes to Tektronix instruments are sometimes made to accommodate improved components as they become available, and to give you the benefit of the latest circuit improvements developed in our engineering department. It is therefore important, when ordering parts, to include the following information in your order: Part number, instrument type or number, serial or model number, and modification number if applicable.

If a part you have ordered has been replaced with a new or improved part, your local Tektronix, Inc. Field Office or representative will contact you concerning any change in part number.

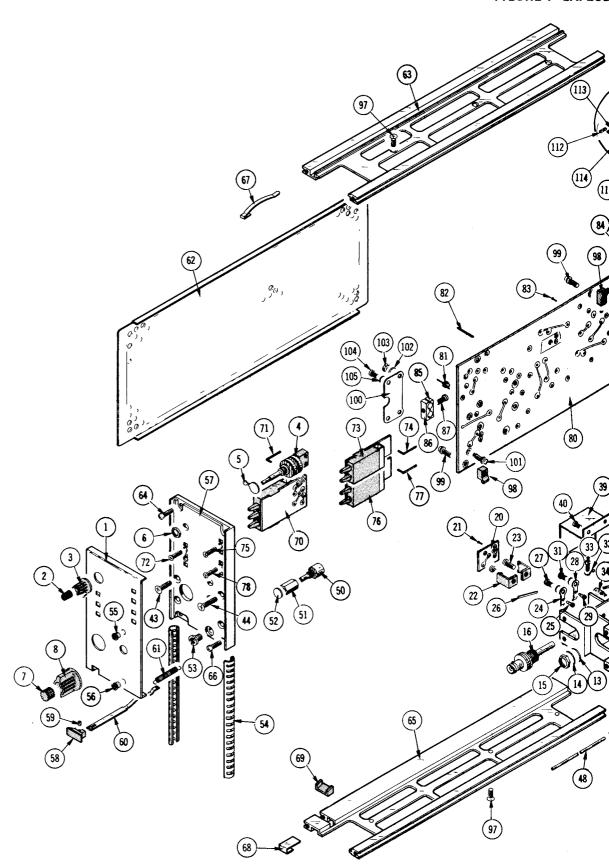
Change information, if any, is located at the rear of this manual.

#### ABBREVIATIONS AND SYMBOLS

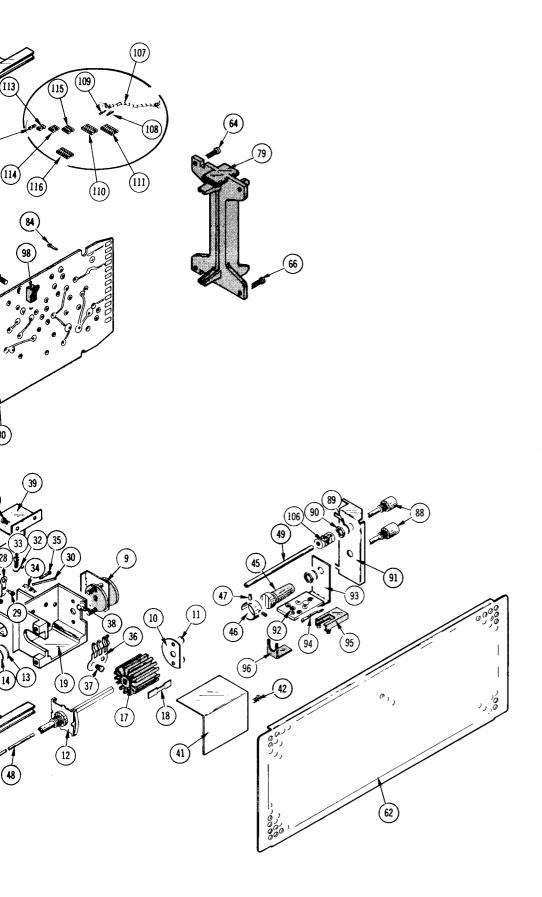
For an explanation of the abbreviations and symbols used in this section, please refer to the page immediately preceding the Electrical Parts List in this instruction manual.

#### INDEX OF MECHANICAL PARTS ILLUSTRATION

Title				Location (reverse side of)		
Figure	1	Exploded		Switching &	Interconnecting	Plug Diagram



#### XPLODED



## SECTION 8 MECHANICAL PARTS LIST

#### FIGURE 1 EXPLODED

Fig. & Index No.	Tektronix Part No.	Serial/Model Eff	No. Disc	Q t y	Description
1-1	333-1151-00			1	PANEL, front
	366-1059-00			i	KNOB, gray—IDENTIFY
-2 -3				;	
-3	366-1077-00			1	KNOB, gray—POSITION
	012 0152 00			-	knob includes:
	213-0153-00			1	SETSCREW, 5-40 x 1/8 inch, HSS
-4				1	RESISTOR, variable
_	010 0000 01			-	mounting hardware: (not included w/resistor)
-5	210-0223-01			1	TERMINAL, lug
-6	210-0583-00			1	NUT, hex., 1/4-32 x 5/16 inch
-7	366-1168-00			1	KNOB, red-black—VARIABLE (CAL IN)
-/					knob includes:
	213-0153-00			1	
0	366-1057-00			i	SETSCREW, 5-40 x 1/8 inch, HSS
-8					KNOB, gray—VOLTS/DIV
				-	knob includes:
	213-0153-00			2	SETSCREW, 5-40 x 1/8 inch, HSS
	263-0009-00			1	SWITCH, wired—VOLTS/DIV
-9				-	switch includes:
-7	263-0510-00			1	SWITCH, unwired
10	227 101 4 02			-	mounting hardware: (not included w/switch)
-10	337-1214-02			1	SHIELD
-11	210-0938-00			2	WASHER, flat, 0.109 ID x 0.250 inch OD
-12	384-0724-00			1	SHAFT-INDEX ASSEMBLY
				-	mounting hardware: (not included w/shaft-index assembly)
-13	210-0840-00			1	WASHER, flat, 0.390 ID x %16 inch OD
-14	210-0012-00			j	WASHER, lock, internal, $\frac{3}{8}$ ID x $\frac{1}{2}$ inch OD
-15	210-0413 00			7	NUT, hex., $\frac{3}{8}$ -32 x $\frac{1}{2}$ inch
					7, 10, 17, 10, 12 × 72 ms.
-16	131-0725-01	,		1	CONNECTOR, receptacle, w/capacitor
-1 <i>7</i>	105-0080-01			1	DRUM, attenuator, w/insert
	<b></b> -			-	drum includes:
	213-0022-00			1	SETSCREW, 4-40 x 0.188 inch, HSS
-18	124-0230-00			2	ATTENUATOR STRIP, dummy
-19	426-0480-01			1	FRAME, attenuator
	131-0927-00			1	CONTACT PLATE (not shown)
	<b></b>			-	mounting hardware: (not included w/contact plate)
	210-0938-00			7	WASHER, flat, #2
	211-0169-00			4	SCREW, $2-56 \times \frac{1}{8}$ inch, PHS
00	/70 1000 00			•	ACCEPTANCE OF THE PROPERTY OF
-20	670-1092-00			1	ASSEMBLY, circuit board-AC-DC-GND RELAY
	000 1000 00			-	assembly includes:
01	388-1309-00			1	BOARD, circuit
-21	136-0385-00			8	SOCKET, relay, 8 pin
00	244.01.42.00			-	mounting hardware: (not included w/assembly)
	344-0143-00			2	CLIP
	211-0179-00			2	SCREW, 4-40 x 1/8 inch, PHS
	210-1002-00			2	WASHER, flat, 0.125 1D x 0.250 inch OD
	131-0886-00	•	-	1	ASSEMBLY, contact spring, rear
	<b></b> -			-	assembly includes:
-24	214-1111-00			1	SPRING, flat
				-	,

Fig. & Index No.	Tektronix Part No.	Serial/M Eff	odel	No. Disc	Q t y	Description
1-25	131-0718-01				1	CONTACT, pin, electrical
1-23	358-0385-00				i	BUSHING, feedthru
-26	346-0061-00				1	STRAP, connector
					-	mounting hardware: (not included w/assembly)
	210-0938-00				1	WASHER, flat, 0.109 ID x 0.250 inch OD
-27	211-0069-00					SCREW, 2-56 x 1/8 inch, PHS
	131-0706-00				1	ASSEMBLY, contact spring, front assembly includes:
-28	214-1111-00				1	SPRING, flat
	131-0718-01				1	CONTACT, pin, electrical
-29	358-0385-00				1	BUSHING, feedthru
-30	346-0062-00				1	STRAP, connector
	010 0000 00				-	mounting hardware: (not included w/assembly)
-31	210-0938-00 211-0169-00				2 1	WASHER, flat, 0.109 ID x 0.250 inch OD SCREW, 2-56 x 1/8 inch, PHS
-31	211-0107-00				•	3CRE 44, 2-30 X /8 IIICII, 1113
-32	210-0259-00				1	LUG, solder, #2
					-	mounting hardware: (not included w/lug)
-33	211-0136-00				1	SCREW, 2-56 x 0.094 inch, PHS
	101 0001 00				,	ACCEMBLY star left at
	131-0901-00				1	ASSEMBLY, standoff, pin assembly included:
-34	342-0012-00				1	INSULATOR, standoff
-35	131-0885-00				i	TERMINAL, pin
-36	131-0675-00				1	CONTACT, electrical
					-	mounting hardware: (not included w/assembly)
-37	211-0179-00				2	SCREW, 4-40 x 0.125 inch, PHS
	210-1002-00				4	WASHER, flat, 0.125 ID x 0.250 inch OD
-38	401-0051-00				1	BEARING, sleeve
-39	337-1093-00				i	SHIELD, input
					-	mounting hardware: (not included w/shield)
-40	211-0136-00				4	SCREW, 2-56 x 0.094 inch, PHS
41	227 1004 00				1	CHIELD autout
-41	337-1094-00				1	SHIELD, output mounting hardware: (not included w/shield)
-42	211-0136-00				2	SCREW, 2-56 x 0.094 inch, PHS
-					-	mounting hardware: (not included w/switch)
-43	211-0541-00				2	SCREW, 6-32 x 1/4 inch, 100° csk, FHS
-44	211-0538-00				2	SCREW, 6-32 $\times$ $\frac{5}{16}$ inch, $100^{\circ}$ csk, FHS
-45	214-1190-01				1	EXTENDER—RETRACTOR, knob
					-	extender-retractor includes:
	213-0076-00				1	SETSCREW, 2-56 x 0.125 inch, HSS
	213-0239-00				1	SETSCREW, 3-48 x 0.062 inch, HSS
-46	376-0093-00				1	COUPLING, half
-47 49	214-0110-00				4 1	PIN, roll
-48 -49	384-0463-00 384-0459-00				1	EXTENSION SHAFT, 4.29 inches long EXTENSION SHAFT, 3.937 inches long
-50					i	RESISTOR, variable
					_	mounting hardware: (not included w/resistor)
	210-0471-00				1	NUT, hex., $\frac{1}{4}$ -32 x $\frac{19}{32}$ inch
	210-0046-00	D010100	D010	107	1	WASHER, lock, 0.261 ID x 0.400 inch OD
	358-0377-00	B010100	B0101	19/	1	BUSHING, 0.275 inch long
	358-0409-00	B010198			1	BUSHING

Fig. 8 Index No.	k Tektronix Part No.	Serial, Eff	/Model No. Disc	Q t	Description
140.	ruii 140.	LII	Disc	у	1 2 3 4 5
1-54 -55 -56 -57 -58	348-0157-00 348-0235-00 358-0378-00 358-0301-02 386-1447-09 366-1058-03	B010100 B010250	B010249	2 2 1 1 1	SHIELDING GASKET SHIELDING GASKET BUSHING, sleeve BUSHING, gray plastic, 0.188 inch ID SUBPANEL, front KNOB, latch mounting hardware: (not included w/knob)
-59	214-1095-00			1	PIN, spring
-60 -61 -62 -63	105-0076-00 214-1280-00 337-1054-00 426-0505-07			1 1 2 1	RELEASE BAR, latch SPRING, helical SHIELD, side FRAME SECTION, top mounting hardware: (not included w/frame)
-64	213-0192-00 361-0326-00			<b>4</b> 1	SCREW, thread forming, 6-32 x 0.625 inch Fil HS SPACER, sleeve
-65	426-0499-07			1	FRAME SECTION, bottom
-66	213-0192-00			4	mounting hardware: (not included w/frame) SCREW, thread forming, 6-32 x 0.625 inch Fil HS
-67 -68 -69 -70	214-1061-00 214-1054-00 105-0075-00 670-1124-00			1 1 1	SPRING, flat sliding ground SPRING, flat, latch detent BOLT, latch, plastic ASSEMBLY, circuit board—AC-DC-GND
<i>-7</i> 1	131-0589-00 380-0154-00 213-0181-00			- 7 1 - 1	assembly includes: TERMINAL, pin HOUSING mounting hardware: (not included w/housing) SCREW throad forming #2 v 0.275 inch BUS
-72	211-0156-00			2	SCREW, thread forming, $\#2 \times 0.375$ inch, PHS mounting hardware: (not included w/assembly) SCREW, 1-72 $\times$ $^{1}/_{4}$ inch, FHS
-73	670-1125-00			1	ASSEMBLY, circuit board—POLARITY assembly includes:
-74	131-0589-00 380-0153-00  213-0181-00			6 1 - 1	TERMINAL, pin HOUSING mounting hardware: (not included w/housing) SCREW, thread forming, #2 x 0.375 inch, PHS
-75	211-0156-00			1	mounting hardware: (not included w/assembly) SCREW, 1-72 $\times \frac{1}{4}$ inch, FHS
-76	670-1126-00			1	ASSEMBLY, circuit board—BANDWIDTH assembly includes:
-77	131-0589-00 380-0153-00			6 1 -	TERMINAL, pin HOUSING mounting hardware: (not included w/housing)
-78	213-0181-00  211-0156-00			1 - 1	SCREW, thread forming, #2 x 0.375 inch, PHS mounting hardware: (not included w/assembly) SCREW, 1-72 x 1/4 inch, FHS
-79	386-1402-00			1	PANEL, rear

B

1-80 670-1113-00 B010100 B019999 1 ASSEMBLY, circuit board—VERTICAL AMPLIFIER 670-1113-01 B020000 B029999 1 ASSEMBLY, circuit board—VERTICAL AMPLIFIER 670-1113-02 B030000 B039999 1 ASSEMBLY, circuit board—VERTICAL AMPLIFIER 670-1113-03 B040000 1 ASSEMBLY, circuit board—VERTICAL AMPLIFIER - assembly includes:	
388-1355-00	ed
-81 131-0157-00 1 CONNECTOR, terminal, standoff -82 131-0589-00 27 TERMINAL, pin -83 136-0252-01 106 SOCKET, pin connector -84 214-0579-00 5 PIN, test point	
-85 200-0945-03 1 COVER, half, transistor -86 200-0945-02 1 COVER, half, transistor, threaded -87 211-0001-00 1 SCREW, 2-56 x ½ inch, RHS -88 2 RESISTOR, variable	
mounting hardware for each: (not included w/re: -89 210-0046-00	
-91 407-0644-00 1 BRACKET, component mounting 670-1134-00 1 ASSEMBLY, circuit board-CAL-UNCAL	
-92 388-1391-00 1 BOARD, circuit -93 407-0663-00 1 BRACKET 210-0656-00 3 EYELET (not shown) -94 131-0604-00 2 CONTACT, spring	
-95 351-0236-00 1 GUIDE, actuator -96 214-1136-00 1 ACTUATOR mounting hardware: (not included w/assembly)	
-97 211-0105-00 6 SCREW, 4-40 x $^3$ / <sub>16</sub> inch, 100° csk, FHS -98 220-0547-01 6 NUT, $^5$ / <sub>16</sub> -32 x $^3$ / <sub>8</sub> x 0.130 inch long -99 211-0116-00 6 SCREW, sems, 4-40 x $^5$ / <sub>16</sub> inch, PHB	
-100 131-0825-00 1 LINK, terminal connector mounting hardware: (not included w/link)	
-101 211-0116-00 2 SCREW, sems, 4-40 x 5/16 inch, PHB -102 210-1002-00 2 WASHER, flat, 0.125 ID x 0.250 inch OD -103 210-0586-00 2 NUT, keps, 4-40 x 1/4 inch -104 211-0116-00 2 SCREW, sems, 4-40 x 5/16 inch, PHB -105 211-0116-00 2 SCREW, sems, 4-40 x 5/16 inch, PHB -106 211-0116-00 2 SCREW, sems, 4-40 x 5/16 inch, PHB -107 211-0116-00 2 SCREW, sems, 4-40 x 5/16 inch, PHB -108 210-1002-00 2 SCREW, sems, 4-40 x 5/16 inch, PHB -109 210-1002-00 2 SCREW, sems, 4-40 x 5/16 inch, PH	
-104 211-0169-00 2 SCREW, 2-56 x 0.125 inch, PHS -105 210-1008-00 2 WASHER, flat, 0.090 ID x 0.188 inch OD	
-106 376-0051-00	

Fig. & Index	Tektronix	Serial/Model	No.	Q t	Description
No.	Part No.	Eff	Disc	у	1 2 3 4 5
1-10 <i>7</i>	179-1427-00			1	WIRING HARNESS
				_	wiring harness includes:
-108	131-0621-00			1 <i>7</i>	CONNECTOR, terminal, straight
	131-0622-00			10	CONNECTOR, terminal, straight
-109	131-0707-00			1 <i>7</i>	CONNECTOR, terminal, straight
	131-0708-00			2	CONNECTOR, terminal, straight
-110	352-0164-00			2	HOLDER, terminal connector, straight, 6 wire
-111	352-0165-00			1	HOLDER, terminal connector, straight, 7 wire
-112	352-0197-00			4	HOLDER, terminal connector, straight, 1 wire
-113	352-0198 00			1	HOLDER, terminal connector, straight, 2 wire
-114	352-0199-00			1	HOLDER, terminal connector, straight, 3 wire
-115	352-0200-00			1	HOLDER, terminal connector, straight, 4 lire
-116	352-0203-00			2	HOLDER, terminal connector, straight, 7 wire

#### STANDARD ACCESSORIES

070-0980-00

2 INSTRUCTION, manual (not shown)

#### MANUAL CHANGE INFORMATION

At Teldronix, we continually strive to keep up with latest electronic developments by adding circuit and component improvements to our instruments as soon as they are developed and tested.

Sometimes, due to printing and shipping requirements, we can't get these changes immediately into printed manuals. Hence, your manual may contain new change information on following pages.

A single change may affect several sections. Sections of the manual are often printed at different times, so some of the information on the change pages may already be in your manual. Since the change information sheets are carried in the manual until ALL changes are permanently entered, some duplication may occur. If no such change pages appear in this section, your manual is correct as printed.

#### ELECTRICAL PARTS LIST AND SCHEMATIC CORRECTION

		VERTICAL AMPLIFIER	Circuit Board	d Assembly		
CHANGE	TO:					
	R64	321-0076-00	60.4 Ω	1/8 W	MF	1%
	R65	321-0024-00	17.4 Ω	1/8 W	MF	1%
	R84	321-0076-00	60.4 Ω	1/8 W	MF	1%
	R85	321-0024-00	17.4 Ω	1/8 W	MF	1%

#### ELECTRICAL PARTS LIST CONSECTION

CHANGE TO:

	AC-DC-GMD	Switch Circuit Board A	eparbly
	670-1124-01	Complete Board	
s3 <sup>14</sup> 670-	1124-01	Pushbutton	AC-GND-DC
	POLARITY '	Switch Circuit Board A	esembly
	670-1125-01	Complete Board	
S118 <sup>14</sup> 670-	1125-01	Pushbucton	INVERT
	BANDWIDTH	Switch Circuit Board A	s sembly
	670-1126-01	Complete Board	
675 14 670-	.1126_01	Pushbutton	BANDWIDTH

## Scans By Artek Media

Artek Media 1042 Plummer Cir. SW Rochester, MN 55902

Manuals@artekmedia.com

"High resolution scans of obsolete technical manuals"

If you purchased this manual from us (typically through our Ebay name of NR1DX) thank you very much. If you received this from a well-meaning "friend" for free we would appreciate your treating this much like you would "share ware". By that we mean a donation of at least \$5-10 per manual is appreciated in recognition of the time, energy and quality of effort that went into preserving this manual. Donations via PayPal go to: <a href="manuals@artekmedia.com">manuals@artekmedia.com</a> or can be mailed to us the address above. This is not a hobby for us but a semi-retirement business used to augment our diminished income in the face of the current degraded world economy.

Typically the scans in our manuals are done as follows;

- 1) Typed text pages are typically scanned in black and white at 300 dpi.
- 2) Photo pages are typically scanned in gray scale mode at 600 dpi
- Schematic diagram pages are typically scanned in black and white at 600 dpi unless the original manual had colored high lighting (as is the case for some 70's vintage Tektronix manuals).

Original pages, which exceed the 8.5 x 11 format, are scanned with enough overlap so that they can be printed and pieced. This is done for primarily for two reasons, the time involved in post processing these to their original size is not trivial and most people do not have the ability to print 11 X 17 pages anyway.

If your looking for a quality scanned technical manual in PDF format please drop us a line at <a href="manuals@artekmedia.com">manuals@artekmedia.com</a> and we will be happy to email you a current list of the manuals we have available. If you don't see the manual you need on the list drop us a line anyway we may still be able to point you to other sources. If you have an existing manual you would like scanned please write for details, This can often be done very reasonably in consideration for adding your manual to our library.

Thanks

Dave & Lynn Henderson Artek Media